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A collar lemma for partially hyperconvex surface group representations

This is the final peer-reviewed author's accepted manuscript (postprint) of the following publication:

Published Version:

BEYRER J., POZZETTI B. (2021). A collar lemma for partially hyperconvex surface group representations. TRANSACTIONS OF THE AMERICAN MATHEMATICAL SOCIETY, 374(10), 6927-6961 [10.1090/tran/8453].

Availability:

This version is available at: <https://hdl.handle.net/11585/984158> since: 2024-09-15

Published:

DOI: <http://doi.org/10.1090/tran/8453>

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A COLLAR LEMMA FOR PARTIALLY HYPERCONVEX SURFACE GROUP REPRESENTATIONS

JONAS BEYRER AND BEATRICE POZZETTI

ABSTRACT. We show that a collar lemma holds for Anosov representations of fundamental groups of surfaces into $SL(n, \mathbb{R})$ that satisfy partial hyperconvexity properties inspired from Labourie's work. This is the case for several open sets of Anosov representations not contained in higher rank Teichmüller spaces, as well as for Θ -positive representations into $SO(p, q)$ if $p \geq 4$. We moreover show that 'positivity properties' known for Hitchin representations, such as being positively ratioed and having positive eigenvalue ratios, also hold for partially hyperconvex representations.

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Date: April 13, 2021.

J.B. acknowledges funding by the Deutsche Forschungsgemeinschaft (DFG, German Research Foundation), 338644254 (SPP2026), and the Schweizerischer Nationalfonds (SNF, Swiss Research Foundation), P2ZHP2 184022 (Early Postdoc.Mobility). B.P acknowledges funding by the DFG, 427903332 (Emmy Noether). Both authors acknowledge funding by the DFG, 281869850 (RTG 2229). BP thanks Tengren Zhang and Andres Sambarino for inspiring discussions on the topic of this article, we thank Nicolas Tholozan for an interesting discussion and for sharing his preprint [Tho] with us. We thank the anonymous referee for carefully reading the paper and the valuable remarks that helped improving its exposition.

1. INTRODUCTION

A fundamental result on the geometry of hyperbolic surfaces is the collar lemma which states that, in a hyperbolic surface S_g , every simple closed geodesic c admits an embedded collar neighbourhood whose length diverges logarithmically as the length of c shrinks to zero [Kee74]. This phenomenon is at the basis of various compactness results for moduli spaces, and admits algebraic reformulations useful to study the length spectrum of a hyperbolization: if two elements γ and δ in the fundamental group $\pi_1(S_g)$ intersect geometrically, then there is an explicit lower bound on the length of γ which is a function only dependent of the length of δ .

Higher rank Teichmüller theories, which include Hitchin representations and maximal representations, form connected components of the character variety $\text{Hom}(\pi_1(S_g), \mathbf{G})//\mathbf{G}$ that consist only of discrete and faithful representations. These components form a robust generalization of the Teichmüller component, which is the only component with such property for the group $\mathbf{G} = \text{SL}(2, \mathbb{R})$. A number of geometric features of holonomies of hyperbolizations have been generalized for such higher rank Teichmüller theories (after minor algebraic reformulations): this is the case for Basmajian and McShane identities [LM09, VY17, FP20] and for the collar lemma, which was proven for Hitchin representations by Lee-Zhang [LZ17] and for maximal representations by Burger-P. [BP17]. It was conjectured that the validity of the collar lemma distinguishes higher rank Teichmüller theories within the larger class of Anosov representations, the by now acclaimed generalization of convex cocompactness to higher rank.

In this paper we show that, instead, a collar lemma holds also beyond higher rank Teichmüller theories, and we generalize it to other (conjectural) classes of higher rank Teichmüller theories. To be more precise we study Anosov representations $\rho : \Gamma \rightarrow \text{SL}(E)$ of fundamental groups of surfaces $\Gamma = \pi_1(S)$ on a real vector space E of dimension d . Given such a representation, and for every element $g \in \Gamma$, we denote by $\lambda_1(\rho(g)), \dots, \lambda_d(\rho(g))$ the (generalized) eigenvalues of the matrix $\rho(g)$ ordered so that their absolute values are non-increasing. Moreover we call two elements $g, h \in \Gamma = \pi_1(S_g)$ *linked*, if the corresponding closed geodesics with respect to some (and thus any) hyperbolic metric intersect in S_g .

Under specific hyperconvexity assumptions inspired from Labourie's work, called property H_k and property C_k , we show

Theorem 1.1. *Let $\rho : \Gamma \rightarrow \text{SL}(E)$ be an Anosov representation satisfying properties $H_{k-1}, H_k, H_{k+1}, H_{d-k-1}, H_{d-k}, H_{d-k+1}$ and C_{k-1}, C_k . Then for*

any linked pair $g, h \in \Gamma$ it holds

$$\frac{\lambda_1 \dots \lambda_k}{\lambda_d \dots \lambda_{d-k+1}}(\rho(g)) > \left(1 - \frac{\lambda_{k+1}}{\lambda_k}(\rho(h))\right)^{-1}.$$

Here H_0, C_0 and H_d are empty conditions. We now introduce the hyperconvexity properties needed as assumptions in Theorem 1.1, and some other consequences of these properties that we establish in the paper.

Property H_k and positively ratioed representations. Recall that, for every $l \in \{1, \dots, d-1\}$, a l -Anosov representation admits a continuous equivariant boundary map $\xi_l : \partial\Gamma \rightarrow \text{Gr}_l(E)$.

Following Labourie [Lab06, Section 7.1.4] we say

Definition 1.2. A representation $\rho : \Gamma \rightarrow \text{SL}(E)$ satisfies *property H_k* if it is $\{k, d-k-1, d-k+1\}$ -Anosov, and for every pairwise distinct triple $x, y, z \in \partial\Gamma$ the sum

$$(\xi_k(x) \cap \xi_{d-k+1}(z)) + (\xi_k(y) \cap \xi_{d-k+1}(z)) + \xi_{d-k-1}(z)$$

is direct.

In [MZ19] Martone and Zhang introduced the notion of positively ratioed representations: those are Anosov representations that satisfy some additional 'positivity' property ensuring that suitable associated length functions can be computed as intersection with a geodesic current. In the same paper they have shown that the most studied examples of representations in higher rank Teichmüller theories, i.e. Hitchin and maximal representations, satisfy this positivity.

We add to this by showing that representations satisfying properties H_k, H_{d-k} are also positively ratioed. This provides new examples of this notion and in particular the first open sets in $\text{Hom}(\Gamma, \text{SL}(E))$ of positively ratioed representations that are not in higher Teichmüller spaces:

Theorem 1.3. *Let $\rho : \Gamma \rightarrow \text{SL}(E)$ be a $\{k-1, k, k+1\}$ -Anosov representation satisfying property H_k and H_{d-k} . Then ρ is k -positively ratioed.*

It is also possible to deduce Theorem 1.3 following the lines of Labourie's proof for Hitchin representations [Lab07, Section 4.4] using that, whenever a representation ρ has property H_k , the image of its associated boundary map is a C^1 -circle in $\text{Gr}_k(E)$ [PSW19b, Proposition 8.11]. The argument we provide here is, however, more direct and closer to the circle of ideas important in the rest of the paper.

Theorem 1.3 lets us add to Martone-Zhang's list of positively ratioed representations a few more representations in (conjectural) higher Teichmüller theories: Hitchin representations into $\text{SO}(p, p)$ and Θ -positive representations into $\rho : \Gamma \rightarrow \text{SO}(p, q)$ as introduced by Guichard-Wienhard [GW16]. A straightforward computation shows that ρ satisfies property H_k if and only if the dual ρ^\flat satisfies property H_{d-k} . Moreover representations into $\text{SO}(p, q)$

are self dual. It was proven in [PSW19b, Theorem 9.9] and [PSW19a, Theorem 10.1] that representations in the Hitchin component in $\mathrm{SO}(p, p)$ and Θ -positive representations in $\mathrm{SO}(p, q)$ satisfy property H_k . As a result we obtain:

Corollary 1.4. *The following are examples of positively ratioed representations:*

- (1) *If $\rho : \Gamma \rightarrow \mathrm{SO}(p, p)$ belongs to the Hitchin component, then it is k -positively ratioed for $1 \leq k \leq p - 2$, and both irreducible factors of $\wedge^p \rho$ are 1-positively ratioed.*
- (2) *If $\rho : \Gamma \rightarrow \mathrm{SO}(p, q)$ is Θ -positive in the sense of Guichard-Wienhard, then it is k -positively ratioed for $1 \leq k \leq p - 2$.*

We now turn to the second feature of representations satisfying property H_k , which could be of independent interest. This justifies why in Theorem 1.1 we do not need to take the absolute value:

Proposition 1.5. *If ρ satisfies property H_k , then for every $h \in \Gamma \setminus \{e\}$ we have*

$$\frac{\lambda_k}{\lambda_{k+1}}(\rho(h)) > 1;$$

equivalently the k -th and $(k + 1)$ -th eigenvalue of $\rho(h)$ have the same sign.

One can show that for a k -Anosov representation $\rho : \Gamma \rightarrow \mathrm{SL}(E)$ and every non-trivial $g \in \Gamma$

$$\frac{\lambda_1 \dots \lambda_k}{\lambda_d \dots \lambda_{d-k+1}}(\rho(g)) > 1.$$

In particular, if $\rho : \Gamma \rightarrow \mathrm{SL}(E)$ is a representation satisfying properties H_1, \dots, H_k and H_{d-k+1}, \dots, H_d . Then the signs of all $\lambda_j(\rho(g))$ for $g \in \Gamma \setminus \{e\}$ and $j \in \{1, \dots, k + 1\} \cup \{d - k, \dots, d\}$ are equal.

Property C_k and convexity of projections. In the paper we introduce and study a second hyperconvexity property of representations, property C_k :

Definition 1.6. A representation $\rho : \Gamma \rightarrow \mathrm{SL}(E)$ satisfies *property C_k* if it is $\{k, k + 1, d - k - 2, d - k + 1\}$ -Anosov, and for every pairwise distinct triple $x, y, z \in \partial\Gamma$ the sum

$$\xi_{d-k-2}(x) + (\xi_k(y) \cap \xi_{d-k+1}(x)) + \xi_{k+1}(z)$$

is direct.

We prove that property C_k together with property H_k implies that the shadow ξ_x of the k -curve $\xi_k : \partial\Gamma \rightarrow \mathrm{Gr}_k(E)$ in the projective plane associated to the quotient $\mathbb{P}(\xi_{d-k+1}(x)/\xi_{d-k-2}(x))$ is itself hyperconvex; this means that the sum $\xi_x(y) \oplus \xi_x(z) \oplus \xi_x(w) = \mathbb{R}^3$ for all pairwise distinct $y, z, w \in \partial\Gamma$.

Proposition 1.7. *If $\rho : \Gamma \rightarrow \mathrm{SL}(E)$ satisfies property H_k and C_k , then for every $x \in \partial\Gamma$ the curve*

$$\begin{cases} y & \mapsto [\xi^k(y) \cap \xi^{d-k+1}(x)] \\ x & \mapsto [\xi^{d-k-1}(x)] \end{cases}$$

is a continuous hyperconvex curve in the plane $\mathbb{P}(\xi^{d-k+1}(x)/\xi^{d-k-2}(x))$.

We say that a representation $\rho : \Gamma \rightarrow \mathrm{SL}(E)$ is *Fuchsian* if it is obtained composing a representation of $\mathrm{SL}(2, \mathbb{R})$ with the holonomy of a hyperbolization. It is easy to check which Fuchsian representations satisfy property C_k : if we split $E = E_1 \oplus \dots \oplus E_l$ as a direct sum of irreducible $\mathrm{SL}(2, \mathbb{R})$ -modules of non-increasing dimensions, the induced representation has property C_k if and only if $\dim E_1 - \dim E_2 \geq 2k + 3$. Furthermore, we show that representations satisfying property C_k form a union of connected components of strongly irreducible representations that are Anosov in the right degrees:

Proposition 1.8. *Property C_k is open and closed among strongly irreducible $\{k, k+1, d-k-2, d-k+1\}$ -Anosov representations satisfying property H_k .*

Comparison to Lee-Zhang and higher rank Teichmüller theories. In the case of Hitchin representations into $\mathrm{SL}_d(\mathbb{R})$ Lee-Zhang [LZ17] proved a collar Lemma comparing $\frac{\lambda_k}{\lambda_{k+1}}(\rho(g))$ to $\frac{\lambda_1}{\lambda_d}(\rho(h))$. For $k \neq 1$ this is a stronger result than ours.¹ However in our generality, it is not to expect that $\frac{\lambda_1}{\lambda_d}(\rho(h))$ is well behaved (we do not assume that the representations are 1-Anosov). In particular under our assumptions comparing k -th root and k -th weight seems to be the natural choice.

Theorem 1.1 yields also new results for higher rank Teichmüller theories. Indeed we prove that Guichard-Wienhard's Θ -positive representations into $\mathrm{SO}(p, q)$ satisfy property C_k :

Proposition 1.9. *Let $\rho : \Gamma \rightarrow \mathrm{SO}(p, q)$, $p < q$ be Θ -positive Anosov. For every $1 \leq k \leq p-3$ the representation ρ has property C_k .*

Thus Theorem 1.1 yields:

Corollary 1.10. *Let $\rho : \Gamma \rightarrow \mathrm{SO}(p, q)$ be Θ -positive Anosov. Then for any linked pair $g, h \in \Gamma \setminus \{e\}$ and all $1 \leq k \leq p-3$*

$$\frac{\lambda_1 \dots \lambda_k}{\lambda_d \dots \lambda_{d-k+1}}(\rho(g)) > \left(1 - \frac{\lambda_{k+1}}{\lambda_k}(\rho(h))\right)^{-1}.$$

Geometric reformulations and counterexamples. It is possible to give a more geometric reformulation of the collar lemma in terms of the naturally defined (pseudo) length functions

$$\ell_{\omega_k + \omega_{d-k}}(\rho(g)) = \log \left| \frac{\lambda_1 \dots \lambda_k}{\lambda_d \dots \lambda_{d-k+1}}(\rho(g)) \right|, \quad \ell_{\alpha_k}(\rho(h)) = \left| \frac{\lambda_k}{\lambda_{k+1}}(\rho(h)) \right|.$$

¹Lee-Zhang use in their proof strong properties of the Frenet curve associated to the Hitchin representations; a tool that we cannot use with our assumptions.

Here the first quantity corresponds to the translation length of $\rho(g)$ on the symmetric space endowed to the Finsler distance associated to the symmetrized k -weight. Instead the second quantity doesn't, in general, come from a metric on the symmetric space: for example, it doesn't satisfy the triangle inequality. On the other hand, ℓ_{α_k} is, in many ways, a better generalization of the hyperbolic length function, at least for representation $\rho : \Gamma \rightarrow \mathrm{SL}(E)$ satisfying property H_k : for example it is proven in [PSW19b] that the associated entropy is constant and equal to one, and in [PSW19b, Appendix A] that the pressure metric associated to the first root has, on the Hitchin component, more similarities to the Weyl-Petersson metric than the usual pressure metric.

Theorem 1.1 can be reformulated in terms of these geometric quantities:

$$e^{\ell_{\omega_k + \omega_{d-k}}(\rho(g))} > \left(1 - e^{-\ell_{\alpha_k}(\rho(h))}\right)^{-1}.$$

Note that, since the eigenvalues λ_i are ordered so that their modulus does not increase, we have that $\ell_{\omega_k + \omega_{d-k}}(\rho(h)) > \ell_{\alpha_k}(\rho(h))$ and thus

$$\left(1 - e^{-\ell_{\alpha_k}(\rho(h))}\right)^{-1} > \left(1 - e^{-\ell_{\omega_k + \omega_{d-k}}(\rho(h))}\right)^{-1}.$$

If one is only interested in the length function $\ell_{\omega_k + \omega_{d-k}}$, this yields the following version of the collar lemma.

Corollary 1.11. *If $\rho : \Gamma \rightarrow \mathrm{SL}(E)$ satisfies the assumptions of Theorem 1.1, then*

$$e^{\ell_{\omega_k + \omega_{d-k}}(\rho(g))} > \left(1 - e^{-\ell_{\omega_k + \omega_{d-k}}(\rho(h))}\right)^{-1}.$$

After this work was completed we got to know that Nicolas Tholoan independently obtained Corollary 1.11 with different techniques [Tho].

While it might not seem very natural at first sight to compare two different length functions for the collar lemma, we have good reasons to do so: on the one hand the collar lemma in Theorem 1.1 is stronger than the one in Corollary 1.11. On the other hand we prove that a 'strong' collar lemma, relating $\ell_{\alpha_k}(\rho(h))$ to $\ell_{\alpha_k}(\rho(g))$ for a linked pair $g, h \in \Gamma$ cannot, in general, hold. We construct sequences of positive representations $\rho_n : \Gamma_{1,1} \rightarrow \mathrm{PSL}(3, \mathbb{R})$ from the fundamental group of the once punctured torus for which the stronger statement fails:

Theorem 1.12. *There is a one parameter family of positive representations $\rho_x : \Gamma_{1,1} \rightarrow \mathrm{PSL}(3, \mathbb{R})$, for $x \in (0, \infty)$, and $\gamma, \delta \in \Gamma_{1,1}$ such that*

$$\ell_{\alpha_1}(\rho_x(\gamma)) = \ell_{\alpha_1}(\rho_x(\delta)) \rightarrow 0$$

as x goes to zero.

This ensures the existence of a sequence of Hitchin representations from $\pi_1(S_2)$ with the same properties.

Sketch of the proof. The proof of the collar lemma is based on the comparison between two cross ratios which can be associated to the boundary map, a projective cross ratio that computes the eigenvalue gap $\lambda_k/\lambda_{k+1}(\rho(h))$, and a Grassmannian cross ratio which computes the left hand side in the expression of Theorem 1.1. Using property H_k , the standard transformation laws of the projective cross ratio lets us obtain an upper bound on the right hand side (this step follows the same lines as [LZ17]). Then the connection between the two cross ratios yields an upper bound in terms of a Grassmannian cross ratio, involving, as one of its four entries, the space $(\xi_{d-k+1}(h_-) \cap \xi_k(g_+)) \oplus \xi_{d-k-1}(h_-)$. The bulk of the proof consists in showing that replacing this last subspace with $\xi_{d-k}(g_+)$ only increases the cross ratio. This latter step is obtained by considering a natural Lipschitz path interpolating between the two k -dimensional subspaces. Since the representation has properties H_{d-k+1} and H_{d-k-1} such path is a monotone curve in a C^1 -surface inside the $(d-k)$ -Grassmannian, and the proof reduces to studying the horizontal and vertical derivatives. That's where the properties C_k and C_{k-1} , as well as the additional H_j properties come into play.

Outline of the paper. In Section 2 we set few standing assumptions and recall basic facts about Anosov representations that will be needed in the paper. In Section 3 we introduce the two cross ratios that will play an important role in the paper, and find useful ways to relate them. Section 4 is devoted to the study of the partial hyperconvexity properties, property H_k and C_k . Here is where their basic properties are proven: the conditions are open and closed among irreducible, have important implications on projections. We also discuss validity of these properties for Θ -positive representations and Fuchsian loci. In Section 5 we discuss positively ratioed representations, and prove Theorem 1.3. In Section 6 we prove the collar lemma, Theorem 1.1, and in Section 7 we construct the counterexample of Theorem 1.12.

2. PRELIMINARIES

We begin with some conventions and notations that we keep for the rest of this paper.

Notation 2.1. *In the ongoing we have*

- E will always be a real vector space of dimension d
- Γ always a surface group, i.e. $\Gamma = \pi_1(S_g)$ for S_g a closed surface of genus at least $g \geq 2$.

Since Γ is a surface group, the Gromov boundary $\partial_\infty \Gamma$ is homeomorphic to a circle.² This induces an order on the boundary:

²Actually all our results equally well work for hyperbolic groups with circle boundary, i.e. virtual surface groups by [Gab92]; one would only need to replace 'non-trivial element of Γ ' with 'infinite order element of Γ '.

Definition 2.2. We call a tuple $(x_1, \dots, x_n) \in \partial_\infty \Gamma^n$ of distinct points with $n \geq 4$ *cyclically ordered* or *in that cyclic order* if the points are in positive order on $\partial_\infty \Gamma \simeq S^1$ for one of the two orientations.

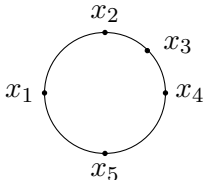


FIGURE 1. Cyclically ordered 5-tuples $(x_1, \dots, x_5), (x_5, \dots, x_1)$

Note that such a tuple will never be in positive order for both orientations. Moreover with our convention every cyclic shift of a cyclically ordered tuple is still cyclically ordered, and the same holds if the order of the tuple is reversed. As in [MZ19] we use the following notation for intervals:

Notation 2.3. Given pairwise distinct points $x, y, z \in \partial_\infty \Gamma$ we denote by $(x, y)_z$ the connected component of $\partial_\infty \Gamma \setminus \{x, y\}$ that does not contain z .

Throughout the paper we will be concerned with various subspaces $V < E$; it will often be convenient to record the dimension of such subspaces with an exponent, so that the notation V^v will imply that $\dim(V) = v$. If V^v, W^w, U^u are subspaces of E we will write $V^v \oplus W^w = U^u$ to mean that the sum of V^v and W^w as subspaces of U^u is direct and spans the subspace U^u , thus in particular $u = v + w$.

We denote by $\text{Gr}_k(E)$ the Grassmannian of k -planes in E . Given $V \in \text{Gr}_k(E)$ and $W \in \text{Gr}_{d-k}(E)$, we write $V \pitchfork W$ if V and W are *transverse*, i.e. $V \oplus W = E$, and $V \not\pitchfork W$ if they are not transverse.

Notation 2.4. When two nested subspaces $X^i < X^j$ are fixed, with quotient $X := X^j / X^i$, we will denote by $[\cdot]_X$ the projection that associates to a subspace $V^l \in \text{Gr}_l(X^j) \setminus \text{Gr}_l(X^i)$ the subspace of X of dimension $l' := l - \dim(V^l \cap X^i)$ given by

$$[V^l]_X := (V^l + X^i) / X^i \in \text{Gr}_{l'}(X).$$

Given any representation $\rho : \Gamma \rightarrow \text{SL}(E)$, we denote by $\rho^\flat : \Gamma \rightarrow \text{SL}(E^*)$ the *dual (or contragredient) representation*; this is defined by the relation

$$(\rho^\flat(g)(w^*))(v) = w^*(\rho(g^{-1})v)$$

for all $g \in \Gamma, w^* \in E^*$ and $v \in E$.

2.1. Anosov representations. Anosov representations were introduced by Labourie for fundamental groups of negatively curved manifolds [Lab06] and generalized by Guichard-Wienhard to hyperbolic groups [GW12]. Those

representations yield generalizations of Teichmüller theory and convex co-compactness from rank one to higher rank. We will now recall the basic definitions recast in the framework of [BPS19], which will be useful in the proof of Proposition 1.7

Given $A \in \mathrm{SL}(E)$ we denote by $|\lambda_1(A)| \geq \dots \geq |\lambda_d(A)|$ the (*generalized*) *eigenvalues* of A counted with multiplicity and ordered non-increasingly in modulus. We will furthermore fix once and for all a scalar product on E and denote by $\sigma_1(A) \geq \dots \geq \sigma_d(A)$ the *singular values* of the matrix A . That means that $\sigma_i(A)^2$ are the eigenvalues of the symmetric matrix $A^t A$.

We fix a word metric on the Cayley graph of Γ for a fixed finite generating set of Γ and denote this by $|\cdot|_\Gamma$.

We will use the definition of Anosov representations from [BPS19], which was shown to be equivalent to Labourie's and Guichard-Wienhard's original definition with different methods in [KLP17, BPS19]:

Definition 2.5. An homomorphism $\rho : \Gamma \rightarrow \mathrm{SL}(E)$ is k -Anosov if there exist positive constants c, μ such that, for all $\gamma \in \Gamma$

$$\frac{\sigma_k}{\sigma_{k+1}}(\rho(\gamma)) \geq ce^{\mu|\gamma|_\Gamma}.$$

The following properties follow easily from the definition:

Remark 2.6. Let $\rho : \Gamma \rightarrow \mathrm{SL}(E)$ be k -Anosov

- (1) The representation ρ is faithful and has discrete image. Its orbit map is a quasi isometric embedding.
- (2) The representation ρ is also $(d-k)$ -Anosov: indeed $\sigma_{d-p}(\rho(\gamma^{-1})) = \sigma_p(\rho(\gamma))^{-1}$.

Furthermore it holds

Proposition 2.7 ([BPS19, KLP17, GW12]). *The set of k -Anosov representation is open in $\mathrm{Hom}(\Gamma, \mathrm{SL}(E))$.*

As already mentioned in the introduction, an important property of Anosov representations is that they admit continuous, transverse, dynamics preserving, equivariant boundary maps. This can be obtained as uniform limits of *Cartan attractors*, as we now recall.

Every element $g \in \mathrm{SL}(E)$ admits a *Cartan decomposition*, namely can be written uniquely as $g = k_g a_g l_g$ where $l_g, k_g \in \mathrm{SO}(E)$ and a_g is diagonal with entries $\sigma_1(g), \dots, \sigma_d(g)$. The k -th Cartan attractor is the subspace

$$U_k(g) = k_g \langle e_1, \dots, e_k \rangle.$$

In other words $U_k(g)$ is a choice of the p longest axes of the ellipsoid $g \cdot B_1(0) \subset E$. Here $B_1(0)$ is the unit ball around the origin in E . Observe that if g has a gap of index k , i.e. $\sigma_k(g) > \sigma_{k+1}(g)$, then the k -th Cartan attractor doesn't depend on the choice of a Cartan decomposition.

Then the following holds:

Proposition 2.8 ([BPS19, Proposition 4.9]). *Let $\rho : \Gamma \rightarrow \mathrm{SL}(E)$ be k -Anosov. Then for every geodesic ray $(\gamma_n)_{n \in \mathbb{N}}$ in Γ with endpoint $x \in \partial\Gamma$ the limits*

$$\xi^k(x) := \lim_{n \rightarrow \infty} U_k(\rho(\gamma_n)) \quad \xi^{d-k}(x) := \lim_{n \rightarrow \infty} U_{d-k}(\rho(\gamma_n))$$

exist, do not depend on the ray and define continuous, ρ -equivariant, transverse maps $\xi^k : \partial\Gamma \rightarrow \mathrm{Gr}_k(E)$, $\xi^{d-k} : \partial\Gamma \rightarrow \mathrm{Gr}_{d-k}(E)$.

The uniformity of the limits in Proposition 2.8 can be estimated explicitly with respect to the distance on the Grassmannians induced by the fixed scalar product. To be more precise, for $v, w \in E$ we let $\angle(v, w)$ be the angle between the two vectors with respect to the chosen scalar product.

The sine of the angle gives a distance, that we will denote by d , on the projective space $\mathbb{P}(E)$. More generally on every Grassmannian $\mathrm{Gr}_k(E)$ we set for $X, Y \in \mathrm{Gr}_k(E)$

$$d(X, Y) := \max_{v \in X^\times} \min_{w \in Y^\times} \sin \angle(v, w) = \min_{v \in X^\times} \max_{w \in Y^\times} \sin \angle(v, w),$$

where $X^\times = X \setminus \{0\}$, $Y^\times = Y \setminus \{0\}$. This corresponds to the Hausdorff distance of $\mathbb{P}(X)$ and $\mathbb{P}(Y)$ regarded as subsets of $\mathbb{P}(E)$ with the aforementioned distance.

Following Bochi-Potrie-Sambarino [BPS19] we further define the angle of two subspaces $X, Y < E$ as

$$\angle(X, Y) = \min_{v \in X^\times} \min_{w \in Y^\times} \angle(v, w)$$

Observe that in projective space $\sin \angle(X, Y) = d(X, Y)$ while for general Grassmannians the inequality $\sin \angle(X, Y) \leq d(X, Y)$ is, apart from very special cases, strict.

It then holds

Proposition 2.9 (cfr. [BPS19, Lemma 4.7]). *Let $\rho : \Gamma \rightarrow \mathrm{SL}(E)$ be k -Anosov. Then there exist positive constants C, μ such that, for every geodesic ray $(\gamma_n)_{n \in \mathbb{N}}$ starting at the identity with endpoint x it holds*

$$d(\xi^k(x), U_k(\rho(\gamma_n))) \leq C e^{-\mu n}.$$

Observe that, if $|\lambda_p(\gamma)| > |\lambda_{p+1}(\gamma)|$, then $U_p(\gamma^n)$ converges to the span of the first p generalized eigenvalues, as a result one gets

Proposition 2.10 ([BPS19]). *Let $\rho : \Gamma \rightarrow \mathrm{SL}(E)$ be k -Anosov. Then ξ^k and ξ^{d-k} are dynamics preserving, i.e. for every infinite order element $\gamma \in \Gamma$ with attracting fixed point $\gamma^+ \in \partial_\infty \Gamma$ we have that $\xi^k(\gamma^+)$ and $\xi^{d-k}(\gamma^+)$ are attractive fixed points for the actions of $\rho(\gamma^+)$ on $\mathrm{Gr}_k(E)$ and $\mathrm{Gr}_{d-k}(E)$, respectively.*

Notation 2.11. *Following the notation introduced in [PSW19b], we will often write x_ρ^k instead of $\xi^k(x)$ for the boundary map ξ^k associated to a k -Anosov representation ρ . If the representation is clear out of context, we will sometimes just write x^k .*

Similarly we will write g_ρ instead of $\rho(g)$ for any $g \in \Gamma$.

We conclude the section by proving Proposition 2.13, that provides the general setup useful to prove Proposition 1.7. For this we need another Lemma from [BPS19]:

Lemma 2.12 ([BPS19, Lemma A.6]). *Assume that $g \in \mathrm{SL}(E)$ has a gap of index k . Then for every $P \in \mathrm{Gr}_k(E)$ transverse to $U_{d-k}(g^{-1})$ it holds*

$$d(gP, U_k(g)) \leq \frac{\sigma_{k+1}}{\sigma_k}(g) \frac{1}{\sin \angle(P, U_{d-k}(g^{-1}))}.$$

The last ingredient we will need in the proof of Proposition 2.13 is the concept of ν -separated triples: we fix a distance d on $\partial\Gamma$ inducing the topology and say that an n -tuple $(x_1, \dots, x_n) \in \partial\Gamma$ is ν -separated if $d(x_i, x_k) > \nu$ for all $i \neq k$. It follows from the properties of the convergence action of Γ on $\partial\Gamma$ that there exists ν_0 such that for every pairwise distinct triple $(a, b, c) \in \Gamma$ there exists $g \in \Gamma$ such that (ga, gb, gc) is ν_0 -separated. We will further assume, up to possibly shrinking ν_0 , that the endpoints of every biinfinite geodesic in Γ through the origin are ν_0 -separated.

We now have all the tools we need to prove the only original result in the section. This is a generalization of the main argument in [PSW19b, Proposition 6.7]. We denote by $\partial_\infty\Gamma^{(2)}$ the set of distinct pairs in the boundary of Γ :

Proposition 2.13. *Let $\rho : \Gamma \rightarrow \mathrm{SL}(E)$ be k -Anosov and $F : \partial_\infty\Gamma^{(2)} \rightarrow \mathrm{Gr}_k(E)$ be continuous, ρ -equivariant. Assume that, for every pairwise distinct triple $x, y, z \in \partial\Gamma$,*

$$F(x, y) \pitchfork z^{d-k}.$$

Then

$$\lim_{y \rightarrow x} F(x, y) = x^k$$

Proof. Observe that, as the set of ν_0 -separated triples is precompact, the assumption guarantees that there is ϵ such that, whenever (x, y, z) is ν_0 separated, it holds

$$\sin \angle(F(x, y), z^{d-k}) > \epsilon.$$

We choose a biinfinite geodesic $(\gamma_i)_{i \in \mathbb{Z}}$ through the origin with positive endpoint x , and denote by z the negative endpoint of $(\gamma_i)_{i \in \mathbb{Z}}$. Observe that for every y there is $n = n_y$ such that $(\gamma_n^{-1}x, \gamma_n^{-1}y, \gamma_n^{-1}z)$ is ν_0 -separated (see [PSW19b, Lemma 6.8]). Furthermore n_y goes to infinity as y converges to x .

It follows from Proposition 2.9 that, since ρ is $(d-k)$ -Anosov, and the ray $(\gamma_n^{-1}\gamma_{n-i})_{i \in \mathbb{N}}$ is a geodesic ray from the origin with endpoint $\gamma_n^{-1}z$, it holds

$$d(U_{d-k}(\rho(\gamma_n^{-1})), \rho(\gamma_n^{-1})z^{d-k}) \leq Ce^{-\mu n}.$$

Thus in particular, we can find N such that, for every y such that $n_y > N$, we have

$$\begin{aligned} \sin \angle(F(\gamma_n^{-1}x, \gamma_n^{-1}y), U_{d-k}(\rho(\gamma_n^{-1}))) &\geq \\ \sin \angle(F(\gamma_n^{-1}x, \gamma_n^{-1}y), \rho(\gamma_n^{-1})z^{d-k}) - d(U_{d-k}(\rho(\gamma_n^{-1})), \rho(\gamma_n^{-1})z^{d-k}) &\geq \frac{\epsilon}{2}. \end{aligned}$$

Lemma 2.12 ensures

$$d(F(x, y), U_k(\rho(\gamma_n))) \leq \frac{\sigma_{k+1}}{\sigma_k}(\rho(\gamma_n)) \frac{2}{\epsilon} \leq \frac{2e^{-\mu n}}{\epsilon c}.$$

The result then follows from Proposition 2.9 using the triangle inequality. \square

3. CROSS RATIOS

An important tool will be cross ratios, which we introduce here. We will need two different notions of cross ratio and their relation.

3.1. Projective cross ratios. Probably the most classical notion of cross ratio is the *projective cross ratio* pcr on \mathbb{RP}^1 . This cross ratio can be defined by

$$\text{pcr}(x_1, x_2, x_3, x_4) := \frac{\tilde{x}_1 \wedge \tilde{x}_3 \tilde{x}_4 \wedge \tilde{x}_2}{\tilde{x}_1 \wedge \tilde{x}_2 \tilde{x}_4 \wedge \tilde{x}_3}$$

if no three of the four $x_i \in \mathbb{RP}^1$ are equal and $\tilde{x}_i \in \mathbb{R}^2 \setminus \{0\}$ are non-trivial lifts. We also need to choose an identification $\wedge^2 \mathbb{R}^2 \simeq \mathbb{R}$, but the definition is independent of all choices made.

Lemma 3.1. *Let $x_1, \dots, x_5 \in \mathbb{RP}^1$. Then whenever all quantities are defined we have*

- (1) $\text{pcr}(x_1, x_2, x_3, x_4)^{-1} = \text{pcr}(x_4, x_2, x_3, x_1) = \text{pcr}(x_1, x_3, x_2, x_4)$
- (2) $\text{pcr}(x_1, x_2, x_3, x_4) \cdot \text{pcr}(x_4, x_2, x_3, x_5) = \text{pcr}(x_1, x_2, x_3, x_5)$
- (3) $\text{pcr}(x_1, x_2, x_3, x_4) \cdot \text{pcr}(x_1, x_3, x_5, x_4) = \text{pcr}(x_1, x_2, x_5, x_4)$
- (4) $\text{pcr}(x_1, x_2, x_3, x_4) = 0 \iff x_1 = x_3 \text{ or } x_4 = x_2$
- (5) $\text{pcr}(x_1, x_2, x_3, x_4) = 1 \iff x_1 = x_4 \text{ or } x_2 = x_3$
- (6) $\text{pcr}(x_1, x_2, x_3, x_4) = \infty \iff x_1 = x_2 \text{ or } x_4 = x_3$
- (7) $\text{pcr}(x_1, x_2, x_3, x_4) = \text{pcr}(gx_1, gx_2, gx_3, gx_4) \quad \forall g \in \text{SL}(\mathbb{R}^2)$
- (8) $\text{pcr}(x_1, x_2, x_3, x_4) = 1 - \text{pcr}(x_1, x_2, x_4, x_3)$.
- (9) *If x_1, \dots, x_5 are cyclically ordered, then*

$$\begin{aligned} \text{pcr}(x_1, x_2, x_3, x_5) &< \text{pcr}(x_1, x_2, x_4, x_5) \\ \text{pcr}(x_1, x_3, x_4, x_5) &< \text{pcr}(x_2, x_3, x_4, x_5). \end{aligned}$$

- (10) $\text{pcr}(x_1, x_2, x_3, x_4) > 1$ if and only if (x_1, x_2, x_3, x_4) is cyclically ordered.

All properties are straight forward to check (and well known).

We will later use the following consequence of Lemma 3.1 (9):

Lemma 3.2. *Let $c : I \subset \mathbb{R} \rightarrow \mathbb{RP}^1$ be C^1 at $i_0 \in I$. If $c(i_0), x_1, x_2 \in \mathbb{RP}^1$ are pairwise distinct and $dc|_{i_0} \neq 0$, then*

$$\left. \frac{d}{dt} \right|_{t=i_0} \text{pcr}(c(i_0), x_1, x_2, c(t)) \neq 0.$$

The projective cross ratio can be used to define a cross ratio on pencils of vector subspaces:

Definition 3.3. Let $V^{k-1} \in \text{Gr}_{k-1}(E)$, $V^{k+1} \in \text{Gr}_{k+1}(E)$ and $W_i^k \in \text{Gr}_k(E)$ for $i = 1, \dots, 4$ such that $V^{k-1} < W_i^k < V^{k+1}$. We set

$$\text{pcr}_{V^{k-1}}(W_1^k, W_2^k, W_3^k, W_4^k) := \text{pcr}([W_1^k], [W_2^k], [W_3^k], [W_4^k]),$$

where $[W_i^k] \in \mathbb{P}(V^{k+1}/V^{k-1}) \simeq \mathbb{R}\mathbb{P}^1$ is the projection.

We will also allow entries of the form $w \in \mathbb{P}(V^{k+1} \setminus V^{k-1})$ in the left hand side, as this defines via $w \oplus V^{k-1}$ a k -vector space satisfying the assumption of Definition 3.3.

This cross ratio is useful to determine the root gap:

Proposition 3.4 (cfr. [LZ17, Lem. 2.9]). *Let ρ be $\{k-1, k, k+1\}$ -Anosov. Then for every non-trivial $h \in \Gamma$*

$$\frac{\lambda_k(h_\rho)}{\lambda_{k+1}(h_\rho)} = \text{pcr}_{h_-^{d-k-1}}(h_-^{d-k}, x^k \cap h_-^{d-k+1}, hx^k \cap h_-^{d-k+1}, h_+^k \cap h_-^{d-k+1})$$

for any $x \in \partial_\infty \Gamma \setminus \{h_\pm\}$.

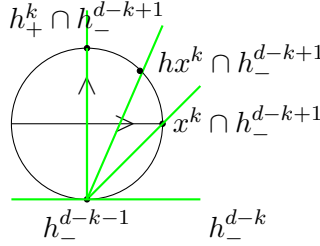


FIGURE 2. Schematic picture of the statement of Proposition 3.4, all thick green lines are to be understood as subspaces of h_-^{d-k+1} ; their cross ratio is the k -th eigenvalue gap

Proof. Pick a generalized eigenbasis (e_1, \dots, e_d) of h_ρ such that e_i corresponds to $\lambda_i(h_\rho)$ with the λ_i ordered decreasingly in modulus as usual. Then $h_-^{d-k+1}/h_-^{d-k-1} \simeq \langle e_k, e_{k+1} \rangle$. Moreover by the Anosov condition e_k, e_{k+1} are eigenvectors (and not only generalized eigenvectors). Thus if $[\cdot]$ denotes the projection to $\mathbb{P}(h_-^{d-k+1}/h_-^{d-k-1})$, we get in the basis $[e_k], [e_{k+1}]$ that

$$\begin{aligned} [h_+^k \cap h_-^{d-k+1}] &= [e_k], & [h_-^{d-k}] &= [e_{k+1}], \\ [x^k \cap h_-^{d-k+1}] &= \left[\begin{pmatrix} a \\ b \end{pmatrix} \right], & [hx^k \cap h_-^{d-k+1}] &= \left[\begin{pmatrix} \lambda_k(h_\rho)a \\ \lambda_{k+1}(h_\rho)b \end{pmatrix} \right] \end{aligned}$$

for some $a, b \in \mathbb{R} \setminus \{0\}$. The claim follows through a short calculation. \square

3.2. Grassmannian cross ratio. The projective cross ratio has a generalization to Grassmannians, which we now describe. Set

$$\mathcal{A}_k := \{(V_1, W_2, W_3, V_4) \mid V_1, V_4 \in \text{Gr}_k(E), W_2, W_3 \in \text{Gr}_{d-k}(E) \text{ and } V_j \pitchfork W_i \\ \text{for } (j, i) = (1, 2), (4, 3) \text{ or } (j, i) = (1, 3), (4, 2)\}$$

Definition 3.5. Let $(V_1, W_2, W_3, V_4) \in \mathcal{A}_k$. Then the (generalized) cross ratio $\text{gcr}_k : \mathcal{A}_k \rightarrow \mathbb{R} \cup \{\infty\}$ is defined by

$$\text{gcr}_k(V_1, W_2, W_3, V_4) := \frac{V_1 \wedge W_3 \ V_4 \wedge W_2}{V_1 \wedge W_2 \ V_4 \wedge W_3},$$

where $V_i \wedge W_j$ denotes the element $v_1 \wedge \dots \wedge v_k \wedge w_1 \wedge \dots \wedge w_{d-k} \in \wedge^d E \simeq \mathbb{R}$ for fixed bases $(v_1, \dots, v_k), (w_1, \dots, w_{d-k})$ of V_i and W_j , respectively, and a fixed identification $\wedge^d E \simeq \mathbb{R}$. Note that the value of gcr_k is independent of all choices made. Here we use the convention $\frac{a}{0} := \infty$ for any non-zero $a \in \mathbb{R}$.

Remark 3.6. The modulus of this (generalized) cross ratio is a special case of the, in general vector valued, cross ratios on flag manifolds G/P constructed in [BEY21] - see Example 2.11 therein.

Lemma 3.7. *Let $V_1, V_4, V_5 \in \text{Gr}_k(E)$ and $W_2, W_3, W_5 \in \text{Gr}_{d-k}(E)$. Then whenever all quantities are defined we have*

- (1) $\text{gcr}_k(V_1, W_2, W_3, V_4)^{-1} = \text{gcr}_k(V_4, W_2, W_3, V_1) = \text{gcr}_k(V_1, W_3, W_2, V_4)$
- (2) $\text{gcr}_k(V_1, W_2, W_3, V_4) \cdot \text{gcr}_k(V_4, W_2, W_3, V_5) = \text{gcr}_k(V_1, W_2, W_3, V_5)$
- (3) $\text{gcr}_k(V_1, W_2, W_3, V_4) \cdot \text{gcr}_k(V_1, W_3, W_5, V_4) = \text{gcr}_k(V_1, W_2, W_5, V_4)$
- (4) $\text{gcr}_k(V_1, W_2, W_3, V_4) = 0 \iff V_1 \not\pitchfork W_3 \text{ or } V_4 \not\pitchfork W_2$
- (5) $\text{gcr}_k(V_1, W_2, W_3, V_4) = \infty \iff V_1 \not\pitchfork W_2 \text{ or } V_4 \not\pitchfork W_3$
- (6) $\text{gcr}_k(V_1, W_2, W_3, V_4) = \text{gcr}_k(gV_1, gW_2, gW_3, gV_4) \quad \forall g \in \text{SL}(E)$

Notation 3.8. *Given a k -Anosov representation ρ and pairwise distinct $x, y, z, w \in \partial_\infty \Gamma$. Then $(x^k, y^{d-k}, z^{d-k}, w^k) \in \mathcal{A}_k$. In this case we write*

$$\text{gcr}_k(x, y, z, w) := \text{gcr}_k(x^k, y^{d-k}, z^{d-k}, w^k).$$

The k -cross ratio can give information on the eigenvalues of specific elements: We say that an element $A \in \text{SL}(E)$ has an eigenvalue gap of index k if $|\lambda_k(A)| > |\lambda_{k+1}(A)|$. In this case, we denote by $A_k^+ \in \text{Gr}_k(E)$ the span of the first k generalized eigenspaces. Furthermore if A also has an eigenvalue gap of index $d - k$ we denote by $A_k^- := (A^{-1})_k^+ \in \text{Gr}_k(E)$.

Then following is easy to check:

Lemma 3.9. *If A has eigenvalue gaps of indices $k, d - k$ then for every $V \in \text{Gr}_k(E)$ transverse to A_{d-k}^\pm , and $W \in \text{Gr}_{d-k}(E)$ transverse to A_k^\pm it holds*

$$\text{gcr}_k(A_k^-, W, AW, A_k^+) = \text{gcr}_k(V, A_{d-k}^-, A_{d-k}^+, AV) = \frac{\lambda_1(A) \dots \lambda_k(A)}{\lambda_d(A) \dots \lambda_{d-k+1}(A)}$$

Note that, since the boundary map of a k -Anosov representation is dynamics preserving, we have that g_ρ has eigenvalue gaps of indices $k, d-k$ for every non-trivial $g \in \Gamma$. Furthermore $\xi^k(g_+) = (g_\rho)_k^+$, $\xi^k(g_-) = (g_\rho)_k^-$ for g_\pm attractive and repulsive fixed points of g respectively. This yields:

Corollary 3.10. *Let ρ be k -Anosov. Then for every non-trivial $g \in \Gamma$ and every $x \in \partial_\infty \Gamma \setminus \{g_\pm\}$ we have*

$$\text{gcr}_k(g_-, x, gx, g_+) = \text{gcr}_k(x, g_-, g_+, gx) = \frac{\lambda_1(g_\rho) \cdots \lambda_k(g_\rho)}{\lambda_d(g_\rho) \cdots \lambda_{d-k+1}(g_\rho)} > 1.$$

Proof. It remains to show that $\text{gcr}_k(g_-, x, gx, g_+) > 1$. Observe that k -Anosov yields that

$$\left| \frac{\lambda_1(g_\rho) \cdots \lambda_k(g_\rho)}{\lambda_d(g_\rho) \cdots \lambda_{d-k+1}(g_\rho)} \right| > 1.$$

For y in the same connected component of $\partial_\infty \Gamma \setminus \{g_\pm\}$ as x we define the map $y \mapsto \text{gcr}_k(g_-, x, y, g_+)$, which is continuous and never zero. As $\text{gcr}_k(g_-, x, x, g_+) = 1$, the image of this map is in $\mathbb{R}_{>0}$. In particular

$$\text{gcr}_k(g_-, x, gx, g_+) > 0,$$

which yields the claim. \square

3.3. Relations of the cross ratios. We now investigate relations between the various cross ratios introduced so far. For this it will be useful to remember the projection $[\cdot]_X$ introduced in Notation 2.4.

Proposition 3.11. *Let $P^k \neq Q^k \in \text{Gr}_k(E)$. Denote by $X^{k+l} := \langle P^k, Q^k \rangle$ their span, by $X^{k-l} := P^k \cap Q^k$ their intersection and by $X := X^{k+l}/X^{k-l}$ the quotient. For each $(d-k)$ -dimensional subspaces S^{d-k}, T^{d-k} transverse to X^{k-l} it holds*

$$\text{gcr}_k(P^k, S^{d-k}, T^{d-k}, Q^k) = \text{gcr}_l([P^k]_X, [S^{d-k} \cap X^{k+l}]_X, [T^{d-k} \cap X^{k+l}]_X, [Q^k]_X),$$

whenever one of the sides is defined.

Proof. This is a direct computation: if we pick a basis (e_1, \dots, e_d) such that

$$X^j = \langle e_1, \dots, e_j \rangle, \quad j = k-l, k+l$$

and choose a basis of S^{d-k} (resp. T^{d-k}) whose first l vectors belong to X^{k+l} , in order to compute the cross ratio on the left hand side we have to compute the determinant of four block upper triangular matrices, whose first blocks are always the identity, the third blocks cancel between the numerator and denominator, and the remaining blocks (of size $2l \times 2l$) gives the desired cross ratio on the right. \square

Since by definition $\text{gcr}_1 = \text{pcr}$ on $\mathbb{P}(\mathbb{R}^2)$, we immediately get

Corollary 3.12. *Let $P^k, Q^k \in \text{Gr}_k(E)$ be such that $\dim P^k \cap Q^k = k - 1$. Then, using the notation of the Proposition 3.11, it holds*

$$\text{gcr}_k(P^k, S^{d-k}, T^{d-k}, Q^k) = \text{pcr}([P^k]_X, [S^{d-k} \cap X^{k+1}]_X, [T^{d-k} \cap X^{k+1}]_X, [Q^k]_X),$$

whenever one of the sides is defined.

In the special case of points and hyperplanes in $\mathbb{P}(E)$ the above connection works for all transverse points

Corollary 3.13. *Let $p^1, q^1 \in \mathbb{P}(E)$ be transverse to $V^{d-1}, W^{d-1} \in \text{Gr}_{d-1}(E)$. Then*

$$\text{gcr}_1(p^1, V^{d-1}, W^{d-1}, q^1) = \text{pcr}_{V^{d-1} \cap W^{d-1}}(p^1, V^{d-1}, W^{d-1}, q^1).$$

4. PARTIAL HYPERCONVEXITY

4.1. Property H_k . The following transversality property was introduced by Labourie [Lab06, Section 7.1.4] in the context of Hitchin representations, and generalized to other groups in [PSW19b, Section 8.2].

Definition 4.1 ([Lab06, Section 7.1.4]). A representation $\rho : \Gamma \rightarrow \text{SL}(E)$ satisfies *property H_k* if it is $\{k - 1, k, k + 1\}$ -Anosov and the following sum is direct

$$(1) \quad x^k + \left(y^k \cap z^{d-k+1} \right) + z^{d-k-1}.$$

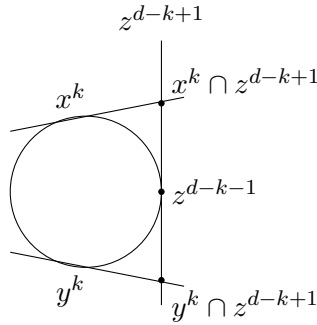


FIGURE 3. Property H_k

Property H_k has the following equivalent characterization, which follows from the transversality properties guaranteed by $(k - 1)$ -Anosov:

$$(2) \quad \left(x^k \cap z^{d-k+1} \right) \oplus \left(y^k \cap z^{d-k+1} \right) \oplus z^{d-k-1} = z^{d-k+1}.$$

The following result from [PSW19b] will be important for us (see also [ZZ19]):

Proposition 4.2 ([PSW19b, Proposition 8.11]). *Let $\rho : \Gamma \rightarrow \mathrm{SL}(E)$ satisfy property H_k . Then the boundary curve ξ^k has C^1 -image and the tangent space is given by*

$$T_{x^k} \xi^k(\partial_\infty \Gamma) = \{\phi \in \mathrm{Hom}(x^k, y^{d-k}) \mid x^{k-1} \subseteq \ker \phi, \mathrm{Im} \phi \subseteq x^{k+1} \cap y^{d-k}\}$$

for any $y \neq x \in \partial_\infty \Gamma$.

The tangent space $T_{x^k} \mathrm{Gr}_k(E)$ has a natural identification with $\mathrm{Hom}(x^k, y^{d-k})$ for every $y^{d-k} \in \mathrm{Gr}_{d-k}(E)$ transverse to x^k , and the above proposition is independent on the choice of $y \neq x \in \partial_\infty \Gamma$. With a slight abuse of notation we will not distinguish between $T_{x^k} \mathrm{Gr}_k(E)$ and $\mathrm{Hom}(x^k, y^{d-k})$.

Proposition 4.2 can be rephrased as saying that, whenever ρ satisfies property H_k , at the point x^k , the differentiable curve ξ^k is tangent to the pencil

$$\mathbb{R}\mathbb{P}^1 = \mathbb{P}\left(x^{k+1}/x^{k-1}\right) := \left\{Z \in \mathrm{Gr}_k(E) \mid x^{k-1} \subset Z \subset x^{k+1}\right\}.$$

Definition 4.3. A *linear approximation* of ξ^k at x is a smooth monotone map $x_t : (-\epsilon, \epsilon) \rightarrow \mathbb{P}(x^{k+1}/x^{k-1})$ with $x_0 = x^k$ and non vanishing derivative at 0.

As the Anosov property is open in $\mathrm{Hom}(\Gamma, \mathrm{SL}(E))$ and property H_k is a transversality condition on the set of triples of points in the boundary, one immediately gets (cfr. [Lab06, Proposition 8.2]):

Proposition 4.4. *The set of representations satisfying property H_k is open in $\mathrm{Hom}(\Gamma, \mathrm{SL}(E))$.*

Recall that we denote by ρ^\flat the contragradient representation. The following proposition follows from a straight forward computation:

Proposition 4.5. *A representation $\rho : \Gamma \rightarrow \mathrm{SL}(E)$ satisfies properties H_k if and only if ρ^\flat satisfies property H_{d-k} .*

Thus if the Zariski closure of $\rho(\Gamma)$ is contained in $\mathrm{Sp}(2n, \mathbb{R})$ or $\mathrm{SO}(p, q)$, then ρ satisfies property H_k if and only if it satisfies property H_{d-k} .

Property H_k can be restated as an injectivity property of the natural projections of the boundary on the projective lines $\mathbb{P}(x^{d-k+1}/x^{d-k-1})$:

Definition 4.6. Let ρ be a $\{k-1, k, k+1\}$ -Anosov representation, fix a point $x \in \partial_\infty \Gamma$ and set $X := x^{d-k+1}/x^{d-k-1}$.

The k -th $\mathbb{R}\mathbb{P}^1$ -projection based at x is the map

$$P_x : \partial_\infty \Gamma \rightarrow \mathbb{P}(x^{d-k+1}/x^{d-k-1})$$

given by

$$P_x(y) = \begin{cases} [y^k \cap x^{d-k+1}]_X & y \neq x, \\ [x^{d-k}]_X & y = x \end{cases}$$

Proposition 4.7. *A $\{k-1, k, k+1\}$ -Anosov representation satisfies property H_k if and only if P_x is injective for all $x \in \partial_\infty \Gamma$.*

Proof. This is essentially by definition. One only has to note that k -Anosov guarantees already that $P_x(y) \neq P_x(x)$ for $y \neq x$. \square

A representation $\rho : \Gamma \rightarrow \mathrm{SL}(E)$ is called *strongly irreducible* if the restriction of ρ to any finite index subgroup $\Gamma' < \Gamma$ is an irreducible representation.

Proposition 4.8. *The subset of representations satisfying property H_k is a union of connected components of strongly irreducible $\{k-1, k, k+1\}$ -Anosov representations.*

Proof. Since $P_x : \partial_\infty \Gamma \rightarrow \mathbb{P}(x^{d-k+1}/x^{d-k-1})$ is injective, the same argument as in [PSW19b, Proposition 9.3] implies that this is a closed condition within the set of representations for which P_x is not locally constant. The fact that ρ is strongly irreducible guarantees that P_x is not locally constant [Lab06, Lem 10.2]. The claim follows. \square

For property H_k we get additionally the following properties for P_x .

Proposition 4.9. *Let ρ satisfy property H_k . Then*

- (1) P_x is continuous;
- (2) For every cyclically ordered n -tuple $(y_1, \dots, y_n) \in \partial_\infty \Gamma^n$ the n -tuple $(P_x(y_1), \dots, P_x(y_n))$ is cyclically ordered in $\mathbb{P}(x^{d-k+1}/x^{d-k-1})$.

Proof. (1) The continuity at $\partial_\infty \Gamma \setminus \{x\}$ follows directly from the continuity of $y \mapsto y^k$. Property H_k guarantees that

$$F(x, y) := \left((y^k \cap x^{d-k+1}) \oplus x^{d-k-1} \right) \pitchfork z^k$$

for every pairwise distinct triple x, y, z . Since F is ρ -equivariant, Proposition 2.13 implies that

$$F(x, y) = \left((y^k \cap x^{d-k+1}) \oplus x^{d-k-1} \right) \rightarrow x^{d-k}$$

for $y \rightarrow x$. If we project this to $\mathbb{P}(x^{d-k+1}/x^{d-k-1})$ we get $P_x(y) \rightarrow P_x(x)$ for $y \rightarrow x$ as desired.

(2) Since P_x is an injective continuous map between topological circles, it is a homeomorphism. Therefore it preserves the cyclic order on all of $\partial_\infty \Gamma$. \square

Remark 4.10. Note that the function on 4-tuples of points in $\partial_\infty \Gamma$ given by $(x, y, z, t) \mapsto \mathrm{pcr}(P_x(u), P_x(y), P_x(z), P_x(w))$ has the symmetries of the projective cross ratio as in Lemma 3.1 ((1) – (3), (8)). By Proposition 4.9 it also inherits (4) – (6), (9), (10) of that Lemma.

Corollary 4.11. *If ρ satisfies property H_k , then for every $h \in \Gamma \setminus \{e\}$ we have $\lambda_k(h_\rho)/\lambda_{k+1}(h_\rho) > 0$.*

Proof. For any $y \in \partial_\infty \Gamma \setminus \{h_\pm\}$, we have that h_+, hy, y, h_- are in that cyclic order on $\partial_\infty \Gamma$. Thus Proposition 4.9 implies that

$$P_{h_-}(h_+), P_{h_-}(hy), P_{h_-}(y), P_{h_-}(h_-)$$

are in that cyclic order on $\mathbb{P}(h_-^{d-k+1}/h_-^{d-k-1}) \simeq \mathbb{R}\mathbb{P}^1$. Thus by Proposition 3.4 together with Lemma 3.1 (10) it follows that

$$\frac{\lambda_k(h_\rho)}{\lambda_{k+1}(h_\rho)} = \text{pcr}(P_{h_-}(h_+), P_{h_-}(hy), P_{h_-}(y), P_{h_-}(h_-)) > 0. \quad \square$$

4.2. Property C_k . We will need also to consider representations that satisfy a bit more transversality of the boundary maps than property H_k . We introduce here this new notion.

Definition 4.12. A representation $\rho : \Gamma \rightarrow \text{SL}(E)$ satisfies *property C_k* if it is $\{k-1, k, k+1, k+2\}$ -Anosov and for pairwise distinct $x, y, z \in \partial_\infty \Gamma$ the sum

$$x^{d-k-2} + (x^{d-k+1} \cap y^k) + z^{k+1}$$

is direct.

Note that by transversality of the boundary maps property C_k is equivalent to

$$(y^k \cap x^{d-k+1}) \oplus (z^{k+1} \cap x^{d-k+1}) \oplus x^{d-k-2} = x^{d-k+1}$$

for all pairwise distinct $x, y, z \in \partial_\infty \Gamma$. The special case of $k=1$, i.e. $x^{d-3} \oplus y^1 \oplus z^2 = E$, is referred to as $(1, 2, 3)$ -hyperconvex in [PSW19b].

Since property C_k is a transversality property on triples of points, the following is proved in the same way as Proposition 4.4.

Proposition 4.13. *Property C_k is an open condition in $\text{Hom}(\Gamma, \text{SL}(E))$.*

Again a straight forward computation yields:

Proposition 4.14. *A representation ρ satisfies property C_k if and only if ρ^\flat satisfies C_{d-k} .*

Property C_k has consequences on the following naturally defined projections on the projective planes $\mathbb{P}(x^{d-k+1}/x^{d-k-2})$:

Definition 4.15. Let $\rho : \Gamma \rightarrow \text{SL}(E)$ be $\{k-1, k, k+1, k+2\}$ -Anosov and fix a point $x \in \partial_\infty \Gamma$. We denote by $X = X_\rho$ the three dimensional vector space x^{d-k+1}/x^{d-k-2} , and denote by $\mathcal{F}(X)$ the space of complete flags of X .

The k -th $\mathbb{R}\mathbb{P}^2$ projection associated to x is the flag map $\pi_x : \partial_\infty \Gamma \rightarrow \mathcal{F}(X)$ given by

$$\pi_x^{(1)}(y) = \begin{cases} [y^k \cap x^{d-k+1}]_X & y \neq x \\ [x^{d-k-1}]_X & y = x \end{cases}$$

$$\pi_x^{(2)}(y) = \begin{cases} [y^{k+1} \cap x^{d-k+1}]_X & y \neq x \\ [x^{d-k}]_X & y = x. \end{cases}$$

Recall from Labourie [Lab06] the following

Definition 4.16. A continuous curve $\xi : \partial_\infty \Gamma \rightarrow \mathbb{R}\mathbb{P}^2$ is *hyperconvex* if $\xi(x) \oplus \xi(y) \oplus \xi(z) = \mathbb{R}^3$ for all pairwise distinct $x, y, z \in \partial_\infty \Gamma$.

The combination of H_k and C_k ensures that all k -th $\mathbb{R}\mathbb{P}^2$ -projections are hyperconvex :

Proposition 4.17. *If $\rho : \Gamma \rightarrow \mathrm{SL}(E)$ satisfies properties H_k and C_k , then for each $x \in \partial_\infty \Gamma$, $\pi_x^{(1)} : \partial_\infty \Gamma \rightarrow \mathbb{P}(X)$ defines a continuous hyperconvex curve that admits a C^1 parametrization with tangents $\pi_x^{(2)}$.*

Proof. We first show the transversality: If the triple is of the form x, y, z , the sum $\pi_x^{(1)}(x) + \pi_x^{(1)}(y) + \pi_x^{(1)}(z)$ is direct if and only if the sum

$$(y^k \cap x^{d-k+1}) + (z^k \cap x^{d-k+1}) + x^{d-k-1}$$

is direct, which holds as ρ satisfies property H_k .

Let now $x, y, z, w \in \partial_\infty \Gamma$ be pairwise distinct. We can assume without loss of generality that the points are in that cyclic order. We set $X' := X/\pi_x^{(1)}(w)$. The claim follows if we show that the projection

$$\begin{aligned} \pi_{x,w} : \partial_\infty \Gamma \setminus \{x, w\} &\rightarrow \mathbb{P}(X') \simeq \mathbb{R}\mathbb{P}^1 \\ u &\mapsto [\pi_x^{(1)}(u)]_{X'} \end{aligned}$$

restricted to any connected component of $\partial_\infty \Gamma \setminus \{x, w\}$ is injective. Note that property H_k guarantees that the projection is well defined. Since property C_k implies that $\pi_x^{(2)}(w)/\pi_x^{(1)}(w)$ is not in the image, the map $\pi_{x,w}$ is a continuous map from a topological interval to a topological interval. Hence it is enough to check local injectivity.

By property H_k it follows that $u \mapsto (u^k \cap x^{d-k+1})$ has C^1 -image with tangent given by $u^{k+1} \cap x^{d-k+1}$ (Proposition 4.2). Thus, by construction, outside x , the map $\pi_x^{(1)}$ has C^1 image with derivative $\pi_x^{(2)}$. Since, by property C_k , we have

$$[\pi_x^{(2)}(u)]_{X'} = \mathbb{P}(X'),$$

or equivalently $\pi_x^{(2)}(u)$ never belongs to the kernel of the projection to X' , it follows that the tangent space of the image of $\pi_{x,w}$ is nowhere degenerate. This implies local injectivity and thus yields transversality.

The continuity of π_x at a point $y \in \partial_\infty \Gamma \setminus \{x\}$ is clear. We are left to show that those maps extend continuously at x . This will be guaranteed by Proposition 2.13: we define the maps

$$\begin{aligned} F^{d-k+1}(x, y) &:= \left(y^k \cap x^{d-k+1} \right) \oplus x^{d-k-2} \in \mathrm{Gr}_{d-k-1}(V) \\ F^{d-k}(x, y) &:= \left(y^{k+1} \cap x^{d-k+1} \right) \oplus x^{d-k-2} \in \mathrm{Gr}_{d-k}(V). \end{aligned}$$

Property C_k guarantees that for every pairwise distinct triple (x, y, z) it holds

$$\begin{aligned} z^{k+1} &\pitchfork \left(y^k \cap x^{d-k+1} \right) \oplus x^{d-k-2} \\ z^k &\pitchfork \left(y^{k+1} \cap x^{d-k+1} \right) \oplus x^{d-k-2}. \end{aligned}$$

Thus Proposition 2.13 applies to F^{d-k+1}, F^{d-k} and this yields the continuity of π_x at x .

Since the map $\pi_x^{(1)}$ is the composition of the boundary map ξ^k , which has C^1 image, with a smooth projection, and we verified that the derivative of a C^1 parametrization of ξ^k never belongs to the kernel of the projection, and has image $\pi_x^{(2)}$, it follows that $\pi_x^{(1)}$ admits a C^1 parametrization with tangents $\pi_x^{(2)}$ outside x . The analogous statement at x follows by continuity. \square

The projections π_x are also useful to show that property C_k is closed within the space of Anosov representations:

Proposition 4.18. *Property C_k is closed among strongly irreducible $\{k-1, k, k+1, k+2\}$ -Anosov representations satisfying property H_k .*

Proof. Let $\{\rho_n\}$ be a sequence of $\{k-1, k, k+1, k+2\}$ -Anosov representations satisfying property H_k and C_k converging to ρ_0 , a strongly irreducible $\{k-1, k, k+1, k+2\}$ -Anosov representation satisfying property H_k . Denote, as above, $X_{\rho_0} := x_{\rho_0}^{d-k+1}/x_{\rho_0}^{d-k-2}$.

Since ρ_0 is strongly irreducible, it follows by [Lab06, Lem 10.2] that, for fixed $z \neq x$, the set of $u \in \partial_\infty \Gamma$ for which

$$(3) \quad \pi_{x_{\rho_0}}^{(1)}(u) \not\pitchfork \pi_{x_{\rho_0}}^{(2)}(z) \quad \text{or} \quad \pi_{x_{\rho_0}}^{(2)}(u) \not\pitchfork \pi_{x_{\rho_0}}^{(1)}(z)$$

doesn't contain open intervals: indeed the two conditions are equivalent respectively to

$$u_{\rho_0}^k \not\pitchfork \left(x_{\rho_0}^{d-k-2} \oplus (z_{\rho_0}^{k+1} \cap x_{\rho_0}^{d-k+1}) \right), \quad u_{\rho_0}^{k+1} \not\pitchfork \left(x_{\rho_0}^{d-k-2} \oplus (z_{\rho_0}^k \cap x_{\rho_0}^{d-k+1}) \right),$$

conditions that, by [Lab06, Lem 10.2] violate strong irreducibility if happening on an open intervals.

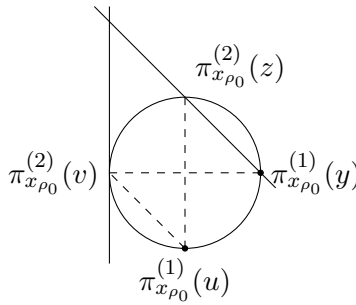


FIGURE 4. Sample situation of Equation (4). The dashed lines encode transversality

As a result, for any distinct triple $x, y, z \in \partial_\infty \Gamma$ we can find $u, v \in \partial_\infty \Gamma \setminus \{x\}$ such that y, z, v, u are cyclically ordered and

$$(4) \quad \pi_{x_{\rho_0}}^{(1)}(y) \pitchfork \pi_{x_{\rho_0}}^{(2)}(v), \quad \pi_{x_{\rho_0}}^{(1)}(u) \pitchfork \pi_{x_{\rho_0}}^{(2)}(z), \quad \pi_{x_{\rho_0}}^{(1)}(u) \pitchfork \pi_{x_{\rho_0}}^{(2)}(v).$$

Indeed we find u in the interval³ $(y, x)_z$ such that $\pi_{x_{\rho_0}}^{(1)}(u) \pitchfork \pi_{x_{\rho_0}}^{(2)}(z)$ as otherwise this would contradict Equation (3). Since transversality is an open condition, Equation (3) implies that we find an open set $\hat{U} \subset (u, x)_y$ such that for all $w \in \hat{U}$ we have $\pi_{x_{\rho_0}}^{(1)}(y) \pitchfork \pi_{x_{\rho_0}}^{(2)}(w)$. Moreover Equation (3) implies also that the set of points in the interval $w \in (u, x)_y$ such that $\pi_{x_{\rho_0}}^{(1)}(u) \pitchfork \pi_{x_{\rho_0}}^{(2)}(w)$ is dense in \hat{U} . Therefore we find the $v \in \hat{U}$ as desired.

Set $X_{\rho_n} := x_{\rho_n}^{d-k+1}/x_{\rho_n}^{d-k-2}$. Proposition 4.17 gives that, for fixed n , the curve $\pi_{x_{\rho_n}}^{(1)} : \partial_\infty \Gamma \rightarrow \mathbb{P}(X_{\rho_n})$ is hyperconvex; as a result, for all cyclically ordered quadruples $a, b, c, d \in \partial_\infty \Gamma \setminus \{x\}$,

$$\text{gcr}_1^{X_{\rho_n}}(\pi_{x_{\rho_n}}^{(1)}(a), \pi_{x_{\rho_n}}^{(2)}(b), \pi_{x_{\rho_n}}^{(2)}(c), \pi_{x_{\rho_n}}^{(1)}(d)) > 1.$$

Here $\text{gcr}_1^{X_{\rho_n}}$ is the cross ratio of points and hyperplanes of X_{ρ_n} as in Definition 3.5.

Furthermore, it follows from the continuity of gcr_{d-k-1} that if y, z, v, u satisfy Equation (4), we have

$$(5) \quad \begin{aligned} & \text{gcr}_1^{X_{\rho_n}}(\pi_{x_{\rho_n}}^{(1)}(y), \pi_{x_{\rho_n}}^{(2)}(z), \pi_{x_{\rho_n}}^{(2)}(v), \pi_{x_{\rho_n}}^{(1)}(u)) \\ & \rightarrow \text{gcr}_1^{X_{\rho_0}}(\pi_{x_{\rho_0}}^{(1)}(y), \pi_{x_{\rho_0}}^{(2)}(z), \pi_{x_{\rho_0}}^{(2)}(v), \pi_{x_{\rho_0}}^{(1)}(u)) \end{aligned}$$

as $n \rightarrow \infty$. Indeed we can choose $V^{k-1} \in \text{Gr}_{d-k-1}(E)$ transverse to $x_{\rho_n}^{d-k+1}$ for all n big enough such that (see Proposition 3.11)

$$\text{gcr}_1^{X_{\rho_n}}(\pi_{x_{\rho_n}}^{(1)}(y), \pi_{x_{\rho_n}}^{(2)}(z), \pi_{x_{\rho_n}}^{(2)}(v), \pi_{x_{\rho_n}}^{(1)}(u)) = \text{gcr}_{d-k-1}(A_n, B_n, C_n, D_n)$$

for

$$\begin{aligned} A_n &:= (a_{\rho_n}^k \cap x_{\rho_n}^{d-k+1}) \oplus x_{\rho_n}^{d-k-2}, & B_n &:= (b_{\rho_n}^{k+1} \cap x_{\rho_n}^{d-k+1}) \oplus V^{k-1}, \\ C_n &:= (c_{\rho_n}^{k+1} \cap x_{\rho_n}^{d-k+1}) \oplus V^{k-1}, & D_n &:= (d_{\rho_n}^k \cap x_{\rho_n}^{d-k+1}) \oplus x_{\rho_n}^{d-k-2}. \end{aligned}$$

Assume now that ρ_0 does not satisfy property C_k , let $x, y, z \in \partial_\infty \Gamma$ be pairwise distinct points violating property C_k for ρ_0 , and choose u, v satisfying Equation (4). The failure of transversality implies that

$$\text{gcr}_1^{X_{\rho_0}}(\pi_{x_{\rho_0}}^{(1)}(y), \pi_{x_{\rho_0}}^{(2)}(z), \pi_{x_{\rho_0}}^{(2)}(v), \pi_{x_{\rho_0}}^{(1)}(u)) = \infty.$$

Since transversality is an open condition, there is $w_0 \in \partial_\infty \Gamma$ such that $y, w_0, z, v, u \in \partial_\infty \Gamma \setminus \{0\}$ are in that cyclic order and $\pi_{x_{\rho_0}}^{(1)}(w) \pitchfork \pi_{x_{\rho_0}}^{(2)}(v)$ for all $w \in (w_0, y)_z$, so that $\text{gcr}_1^{X_{\rho_0}}(\pi_{x_{\rho_0}}^{(1)}(w), \pi_{x_{\rho_0}}^{(2)}(z), \pi_{x_{\rho_0}}^{(2)}(v), \pi_{x_{\rho_0}}^{(1)}(u))$ is defined for all such w . Then the monotonicity of the cross ratio associated to $\pi_{x_{\rho_n}}$, implying that

$$\begin{aligned} & \text{gcr}_1^{X_{\rho_n}}(\pi_{x_{\rho_n}}^{(1)}(w), \pi_{x_{\rho_n}}^{(2)}(z), \pi_{x_{\rho_n}}^{(2)}(v), \pi_{x_{\rho_n}}^{(1)}(u)) \\ & > \text{gcr}_1^{X_{\rho_0}}(\pi_{x_{\rho_0}}^{(1)}(y), \pi_{x_{\rho_0}}^{(2)}(z), \pi_{x_{\rho_0}}^{(2)}(v), \pi_{x_{\rho_0}}^{(1)}(u)) \end{aligned}$$

³Recall from Notation 2.3 that $(u, x)_y$ is the interval in $\partial_\infty \Gamma \setminus \{u, x\}$ not containing y

for all $w \in (w_0, y)_z$, implies that also

$$\text{gcr}_1^{X_{\rho_0}}(\pi_{x_{\rho_0}}^{(1)}(w), \pi_{x_{\rho_0}}^{(2)}(z), \pi_{x_{\rho_0}}^{(2)}(v), \pi_{x_{\rho_0}}^{(1)}(u)) = \infty.$$

which in turn yields that property C_k is violated on the whole open interval $(w_0, y)_z \subset \partial_\infty \Gamma$, a contradiction to strong irreducibility. \square

4.3. Reducible representations and Fuchsian locii. We will now discuss properties H_k and C_k for reducible representations. The following is well known and easy to check:

Lemma 4.19. *Let $\rho : \Gamma \rightarrow \text{SL}(L_1 \oplus L_2)$ be reducible. If ρ is k -Anosov, then the dimension k_i of the intersection $x_i^{k_i} := x^k \cap L_i$ is constant, $x^k = x_1^{k_1} \oplus x_2^{k_2}$, the restriction $\rho|_{L_i}$ is k_i -Anosov, and $x \mapsto x_i^{k_i}$ is the associated boundary map.*

Proof. First note that, since the subspaces L_i are invariant, for all $\gamma \in \Gamma$ the subspace γ_+^k splits as the direct sum $(\gamma_+^k \cap L_1) \oplus (\gamma_+^k \cap L_2)$. As the functions $y \mapsto \dim(y^k \cap L_i)$ are both upper-semicontinuous and the set of fixed points is dense in $\partial_\infty \Gamma$, it follows that those maps are constant. This yields the decomposition $x^k = x_1^{k_1} \oplus x_2^{k_2}$ everywhere. Since ξ^k is dynamics preserving, we get that the maps $x \mapsto x_i^{k_i}$ are also dynamics preserving. Moreover it follows easily that k_i -th root gap of the representation $\rho|_{L_i}$ is not smaller than the k -th root gap of ρ . Thus $\rho|_{L_i}$ is k_i -Anosov with boundary map $x \mapsto x_i^{k_i}$. \square

Proposition 4.20. *Let $\rho : \Gamma \rightarrow \text{SL}(L_1 \oplus L_2)$ be $\{k-1, k, k+1\}$ -Anosov and reducible. Assume that $(k-1)_1 = k_1 - 1$. Then ρ has property H_k if and only if $(k+1)_1 = k_1 + 1$ and $\rho|_{L_1}$ has property H_{k_1} .*

Proof. Let $d_1 = \dim L_1$. Observe that, under our assumption $x^k \cap z^{d-k+1} = x_1^{k_1} \cap z_1^{d_1-k_1+1} \subset L_1$. As a result the sum

$$x^{k-1} + \left(x^k \cap z^{d-k+1} + y^k \cap z^{d-k+1} \right) + z^{d-k-1}$$

can only be direct if $L_2 \subset x^{k-1} + z^{d-k-1}$ and $\rho|_{L_1}$ has property H_{k_1} . The converse implication is clear. \square

The analogue statement for property C_k is proven in the same way. We state it for future reference:

Proposition 4.21. *Let $\rho : \Gamma \rightarrow \text{SL}(L_1 \oplus L_2)$ be reducible and $\{k-1, k, k+1, k+2\}$ -Anosov. Assume that $(k-1)_1 = k_1 - 1$. If $(k+1)_1 = k_1 + 1$, $(k+2)_1 = k_1 + 2$ and $\rho|_{L_1}$ has property C_{k_1} , then ρ has property C_k .*

Observe that if $(k-1)_1 \neq k_1 - 1$, then necessarily $(k-1)_2 = k_2 - 1$, so Proposition 4.20 and Proposition 4.21 can be applied to L_2 .

An easy way to obtain many examples of Anosov representations is to deform representations in the so-called Fuchsian loci, the set of representations obtained as composition of holonomies of hyperbolizations with $\text{SL}(\mathbb{R}^2)$ -representations. We fix here the notation for such representations:

Example 4.22 (Fuchsian Loci). Denote by $\tau_{d_i} : \mathrm{SL}(\mathbb{R}^2) \rightarrow \mathrm{SL}(\mathbb{R}^{d_i})$ the d_i -dimensional irreducible representation⁴ of $\mathrm{SL}(\mathbb{R}^2)$ and set

$$\tau_{(d_1, \dots, d_j)} := \tau_{d_1} \oplus \dots \oplus \tau_{d_j}$$

for positive integers $d_1 \geq d_2 \geq \dots \geq d_j$ with $d = d_1 + \dots + d_j$. Let $\rho_{hyp} : \Gamma \rightarrow \mathrm{SL}(\mathbb{R}^2)$ be a discrete and faithful representation. We call the set of representations obtained as composition $\tau_{\underline{d}} \circ \rho_{hyp}$ as ρ_{hyp} varies in the Teichmüller space a *Fuchsian locus*, or the \underline{d} -Fuchsian locus for the specified multi-index $\underline{d} = (d_1, \dots, d_j)$.

It is easy to verify that the irreducible representation satisfies property H_k, C_k for all k , as in this case the equivariant boundary map is the well studied Veronese curve. As a result we obtain:

Corollary 4.23. *In the notation of Example 4.22, a representation of the form $\rho = \tau_{(d_1, \dots, d_m)} \circ \rho_{hyp}$ has property H_k if and only if $d_1 - d_2 > 2k$; if $d_1 - d_2 > 2k + 2$ the representation additionally has property C_k .*

4.4. Θ -positive representations. Another (conjectural) class of higher rank Teichmüller theories are the so-called Θ -positive representations, as introduced by Guichard and Wienhard [GW16]. For the purposes of this paper we will only be concerned with Θ -positive representations into $\mathrm{SO}(p, q)$ where we assume $q > p$. When considering $\mathrm{SO}(p, q)$ as a subgroup of $\mathrm{SL}(p + q, \mathbb{R})$, Θ -positive representations are (conjecturally) $\{1, \dots, p - 1\}$ -Anosov.⁵

We will not need the precise definition of Θ -positive representations, and as it would require introducing many concepts from Lie theory which are not important for our paper, we refer to [GW16, Section 4.5]; the only important property of such representations that will be relevant here is a precise form of positivity of the associated boundary map which we now recall. For this we choose a basis of $\mathrm{SL}(p + q, \mathbb{R})$ such that the quadratic form Q of signature p, q is represented by the matrix

$$\begin{pmatrix} 0 & 0 & K \\ 0 & J & 0 \\ K^t & 0 & 0 \end{pmatrix}$$

where

$$K = \begin{pmatrix} 0 & 0 & (-1)^{p-1} \\ 0 & \dots & 0 \\ -1 & 0 & 0 \end{pmatrix} \text{ and } J = \begin{pmatrix} 0 & 0 & 1 \\ 0 & -\mathrm{Id}_{q-p} & 0 \\ 1 & 0 & 0 \end{pmatrix}.$$

In this section we will denote by \mathcal{F} the subset of the partial flag manifold associated to $\mathrm{SL}(p + q, \mathbb{R})$ consisting of subspaces of dimension $\{1, \dots, p -$

⁴this is uniquely defined up to conjugation

⁵From now on, when we write ' Θ -positive representations into $\mathrm{SO}(p, q)$ ' we additionally assume that they are $\{1, \dots, p - 1\}$ -Anosov. Conjecturally Anosovness already follows from positivity [GW16, Conjecture 5.4].

$1, q+1, \dots, q+p-1\}$ such that the first $p-1$ subspaces are isotropic for Q and the others are their orthogonals with respect to Q . We will furthermore denote by Z and X the partial flags in \mathcal{F} such that $Z^l = \langle e_1, \dots, e_l \rangle$ and $X^l = \langle e_d, \dots, e_{d-l+1} \rangle$, in particular $X^k \cap Z^{d-k+1} = e_{d-k+1}$. Here, as above, l ranges in the set $\{1, \dots, p-1, q+1, \dots, q+p\}$.

Given a positive real number v , and an integer $1 \leq k \leq p-2$ we define $E_k(v)$ as the matrix that differs from the identity only in the positions $(k, k+1)$ and $(d-k, d-k+1)$ where it is equal to v . Instead, for $k=p-1$ we choose a vector $v \in \mathbb{R}^{q-p+2}$ which is positive for the quadratic form associated to J and has positive first entry. For each such v we define

$$E_{p-1}(v) = \begin{pmatrix} \text{Id}_{p-2} & 0 & 0 & 0 & 0 \\ 0 & 1 & v^t & q_J(v) & 0 \\ 0 & 0 & \text{Id}_{q-p+2} & Jv & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & \text{Id}_{p-2} \end{pmatrix}.$$

In order to define the properties of Θ -positive representations that we will need, we will use the following reduced expression of the longest element w_0 of the Weyl group $W(\Theta) = W_{B_{p-1}}$, i.e. the Weyl group associated to the root system B_{p-1} : Let S be a standard generating set in standard order of $W_{B_{p-1}}$, i.e. we write $S = \{s_1, \dots, s_{p-1}\}$, where s_{p-1} corresponds to reflection along the only long root in a set of simple roots. Let $S_e \subset S$ be the elements with even index and $S_o \subset S$ the elements with odd index. Denote the product of all the elements of S_e by a and the product of all elements of S_o by b . Then w_0 can be expressed as $w_0 = (ab)^{\frac{h}{2}}$, where h is the Coxeter number, [Bou02, pp.150-151] (see also [DS20, Lemma 4.3]). Note that for the root system of type B_{p-1} , $p \geq 3$ the Coxeter number is always even.

We now consider the unipotent subgroup U_Θ of the stabilizer in $\text{SO}(p, q)$ of the partial flag Z ; our next goal is to define its *positive semigroup* $U_\Theta^{>0}$ (cfr. [GW16, Theorem 4.5]). We denote by $c_J(\mathbb{R}^{q-p+2}) \subset \mathbb{R}^{q-p+2}$ the set of vectors that are positive for the quadratic form associated to J and have positive first entry. Then we set

$$V_\Theta := \{\bar{v} = (v_1, \dots, v_{p-2}, v_{p-1})^t \in \mathbb{R}^q \mid v_1, \dots, v_{p-2} \in \mathbb{R}_{>0}, v_{p-1} \in c_J(\mathbb{R}^{q-p+2})\}.$$

Given $\bar{v} \in V_\Theta$ we set

$$ab(\bar{v}) = \left(\prod_{j \leq p-1, j \text{ even}} E_j(v_j) \right) \cdot \left(\prod_{j \leq p-1, j \text{ odd}} E_j(v_j) \right)$$

For $\bar{v}_1, \dots, \bar{v}_{\frac{h}{2}} \in V_\Theta$ we define the *positive element* $P(\bar{v}_1, \dots, \bar{v}_{\frac{h}{2}})$ as the product

$$P(\bar{v}_1, \dots, \bar{v}_{\frac{h}{2}}) = ab(\bar{v}_1) \dots ab(\bar{v}_{\frac{h}{2}})$$

The positive semigroup $U_\Theta^{>0}$ consists precisely of the positive elements defined above (cfr. [GW16, Theorem 4.5]). This allows to recall the notion

of positivity for triples of flags associated to $\mathrm{SO}(p, q)$ (cfr. [GW16, Definition 4.6]): a triple $(A, B, C) \in \mathcal{F}^3$ is Θ -positive if there exists an element $g \in \mathrm{SO}_0(p, q)$ and a positive element $P(\bar{v}_1, \dots, \bar{v}_{\frac{h}{2}})$ such that

$$(gA, gB, gC) = (X, P(\bar{v}_1, \dots, \bar{v}_{\frac{h}{2}})X, Z).$$

Definition 4.24 ([GW16, Definition 5.3]). A representation $\rho : \Gamma \rightarrow \mathrm{SO}(p, q)$ is Θ -positive if and only if it admits a positive equivariant boundary map $\xi : \partial\Gamma \rightarrow \mathcal{F}$; that is, for every positively oriented triple $(z, y, x) \in \partial\Gamma$, the triple $(\xi(z), \xi(y), \xi(x))$ is positive.

It was proven in [PSW19a, Theorem 10.1] that Θ -positive representations $\rho : \Gamma \rightarrow \mathrm{SO}(p, q)$ have property H_k for $1 \leq k < p - 2$. They also satisfy property C_k in a slightly smaller range:

Proposition 4.25. *Let $\rho : \Gamma \rightarrow \mathrm{SO}(p, q)$ be Θ -positive. For every $1 \leq k \leq p - 3$ the representation ρ has property C_k .*

Proof. We set $d = p + q$. In order to verify that the representation ρ has property C_k , it is enough to verify that, for every positively and for every negatively oriented triple (x, y, z) the sum $z^{d-k-2} + (z^{d-k+1} \cap y^k) + x^{k+1}$ is direct.

Since this last property is invariant by the $\mathrm{SL}(p + q, \mathbb{R})$ -action, and thus in particular by the $\mathrm{SO}_0(p, q)$ -action, it is enough to verify that for each positive element $P(\bar{v}_1, \dots, \bar{v}_{\frac{h}{2}})$ the triple $(X, P(\bar{v}_1, \dots, \bar{v}_{\frac{h}{2}})X, Z)$ is such that the sum

$$Z^{d-k-2} + (Z^{d-k+1} \cap P(\bar{v}_1, \dots, \bar{v}_{\frac{h}{2}})X^k) + X^{k+1}$$

is direct, and the analogue result for the triple $(X, P(\bar{v}_1, \dots, \bar{v}_{\frac{h}{2}})^{-1}X, Z)$.

In turn this is equivalent to verify that for every admissible choice of $\bar{v}_1, \dots, \bar{v}_{\frac{h}{2}} \in V_\Theta$ and every $1 \leq k \leq p - 3$ the coefficient in position $(d - k - 1, d - k + 1)$ of the matrices $P(\bar{v}_1, \dots, \bar{v}_{\frac{h}{2}})$ and $P(\bar{v}_1, \dots, \bar{v}_{\frac{h}{2}})^{-1}$ doesn't vanish.

This follows readily from the definitions: indeed, given unipotent matrices A, B it holds

$$\begin{aligned} (AB)_{d-k-1, d-k} &= A_{d-k-1, d-k} + B_{d-k-1, d-k}, \\ (AB)_{d-k, d-k+1} &= A_{d-k, d-k+1} + B_{d-k, d-k+1}, \\ (AB)_{d-k-1, d-k+1} &= A_{d-k-1, d-k+1} + A_{d-k-1, d-k}B_{d-k, d-k+1} + B_{d-k-1, d-k+1}. \end{aligned}$$

In particular, if $ab(\bar{v}_i), i = 1, \dots, \frac{h}{2}$ is the matrix introduced in the definition of positive elements, it holds

$$\begin{aligned} (ab(\bar{v}_i))_{d-k-1, d-k} &= v_{k-1}, \\ (ab(\bar{v}_i))_{d-k, d-k+1} &= v_k, \end{aligned}$$

and

$$\begin{aligned} (ab(\bar{v}_i)^{-1})_{d-k-1, d-k} &= -v_{k-1}, \\ (ab(\bar{v}_i)^{-1})_{d-k, d-k+1} &= -v_k, \end{aligned}$$

One readily checks by induction, using the fact that $h \geq 2$, that the relevant coefficients don't vanish: indeed it is sum of positive numbers of

which at least one is non-zero. To be more precise, in the case of $P(\bar{v}_1, \dots, \bar{v}_{\frac{h}{2}})$ all coefficients in positions $(d-k-1, d-k)$, $(d-k, d-k+1)$ and $(d-k-1, d-k+1)$ in all the matrices whose product gives $P(\bar{v}_1, \dots, \bar{v}_{\frac{h}{2}})$ are either positive or zero; in the case of $P(\bar{v}_1, \dots, \bar{v}_{\frac{h}{2}})^{-1}$ all coefficients in positions $(d-k-1, d-k)$, $(d-k, d-k+1)$ in all the matrices whose product gives $P(\bar{v}_1, \dots, \bar{v}_{\frac{h}{2}})^{-1}$ are negative or zero and thus all the coefficients in position $(d-k-1, d-k+1)$ are positive because they are sums of products of pairs of the previous coefficients. \square

5. POSITIVELY RATIOED REPRESENTATIONS

We now turn to the study of positively ratioed representations. The following definition is essentially due to Martone-Zhang ([MZ19]):

Definition 5.1. We say that a k -Anosov representation $\rho : \Gamma \rightarrow \mathrm{SL}(E)$ is k -positively ratioed if for all cyclically ordered quadruples (x, y, z, w) of points in $\partial_\infty \Gamma$

$$\mathrm{gcr}_k(x^k, y^{d-k}, z^{d-k}, w^k) > 1.$$

Remark 5.2. Our definition of k -positively ratioed representation is slightly stronger than the one in [MZ19]: A representation is positively ratioed in the sense of Martone Zhang if it is a k -Anosov representation $\rho : \Gamma \rightarrow \mathrm{SL}(E)$ such that

$$\log |\mathrm{gcr}_k(x^k, y^{d-k}, z^{d-k}, w^k) \mathrm{gcr}_{d-k}(x^{d-k}, y^k, z^k, w^{d-k})| > 0.$$

To see that a k -positively ratioed representation is positively ratioed in the sense of Martone-Zhang, it is enough to observe that

$$\mathrm{gcr}_{d-k}(x^{d-k}, y^k, z^k, w^{d-k}) = \mathrm{gcr}_k(y^k, x^{d-k}, w^{d-k}, z^k),$$

as well as that (y, x, w, z) are cyclically ordered in $\partial_\infty \Gamma$ if (x, y, z, w) are.

Representations satisfying properties H_k, H_{d-k} are k -positively ratioed:

Theorem 5.3. *If $\rho : \Gamma \rightarrow \mathrm{SL}(E)$ satisfies properties H_k and H_{d-k} , then ρ is k -positively ratioed.*

Proof. Note that property H_{d-k} implies that ξ^{d-k} has C^1 -image (Proposition 4.2). Let $\Phi_y \in T_{y^{d-k}} \xi^{d-k} \setminus \{0\}$. We claim that

$$d_{y^{d-k}} \mathrm{gcr}_k(x^k, y^{d-k}, \cdot, w^k)(\Phi_y) \neq 0$$

for all pairwise distinct $x, y, w \in \partial_\infty \Gamma$: Fix such x, y, w . We find a basis (e_1, \dots, e_d) of E such that

$$y^j = \langle e_1, \dots, e_j \rangle, \quad j = d-k-1, d-k, d-k+1.$$

According to Proposition 4.2 the curve

$$y_t^{d-k} := \langle e_1, \dots, e_{d-k-1}, e_{d-k} + t e_{d-k+1} \rangle, \quad t \in (-\epsilon, \epsilon)$$

is tangent to $T_{y^{d-k}}\xi^{d-k}$ at $y^{d-k} = y_0^{d-k}$, therefore

$$d_{y^{d-k}}\text{gcr}_k(x^k, y^{d-k}, \cdot, w^k)(\Phi_y) \neq 0 \iff \left. \frac{d}{dt} \right|_{t=0} \text{gcr}_k(x^k, y^{d-k}, y_t^{d-k}, w^k) \neq 0.$$

Set $Y := y^{d-k+1}/y^{d-k-1}$ and recall from Definition 4.6 the k -th \mathbb{RP}^1 -projection

$$P_y = \partial_\infty \Gamma \rightarrow \mathbb{P}(y^{d-k+1}/y^{d-k-1}).$$

Corollary 3.12 yields that

$$\text{gcr}_k(x^k, y^{d-k}, y_t^{d-k}, w^k) = \text{pcr}(P_y(x), P_y(y), [y_t^{d-k}]_Y, P_y(w)).$$

Property H_k guarantees that $P_y(x), P_y(w), P_y(y)$ are pairwise distinct (Proposition 4.7). Moreover the derivative of the C^1 -curve $[y_t]_Y$ is not 0, as $\mathbb{P}(y^{d-k+1}/y^{d-k-1}) \simeq \mathbb{P}(\langle e_{d-k}, e_{d-k+1} \rangle)$ and $[y_t]_Y$ is the projectivization of the path $t \mapsto e_{d-k} + te_{d-k+1}$. Therefore it follows from Lemma 3.2 that

$$\left. \frac{d}{dt} \right|_{t=0} \text{pcr}(P_y(x), P_y(y), [y_t^{d-k}]_Y, P_y(w)) \neq 0$$

which is equivalent to $\left. \frac{d}{dt} \right|_{t=0} \text{gcr}_k(x^k, y^{d-k}, y_t^{d-k}, w^k) \neq 0$ and proves the claim.

Now, let $y \rightarrow \Phi_y \in T_{y^{d-k}}\xi^{d-k} \setminus \{0\}$ be a continuous map defined on a connected component of $\partial_\infty \Gamma \setminus \{x, w\}$, choose Φ_y so that (x, y, y_t, w) are cyclically ordered for a curve y_t^{d-k} with derivative Φ_y and $t > 0$.

The regularity of the cross ratio implies that the never vanishing map

$$y \mapsto d_{y^{d-k}}\text{gcr}_k(x^k, y^{d-k}, \cdot, w^k)(\Phi_y)$$

is continuous on connected components of $\partial_\infty \Gamma \setminus \{x, w\}$, its sign is thus constant on each component. The cocycle identity, Lemma 3.7 (3), implies that for cyclically ordered $x, y, z, w \in \partial_\infty \Gamma$, the cross ratio $\text{gcr}_k(x, y, z, w)$ is smaller than one if the sign of the derivative is negative, and is bigger than 1 if it is positive. Since, for $z_n \rightarrow w$, we deduce from the continuity of the cross ratio and Lemma 3.7 (3) that $\text{gcr}_k(x, y, z_n, w) \rightarrow \infty$, it cannot be $\text{gcr}_k(x, y, z, w) < 1$ for all cyclically ordered $x, y, z, w \in \partial_\infty \Gamma$ and thus $\text{gcr}_k(x, y, z, w) > 1$. \square

6. PROOF OF THE COLLAR LEMMA

Given non-trivial elements $g, h \in \Gamma$, we denote, as usual, by $g_\pm, h_\pm \in \partial_\infty \Gamma$ the respective attractive and repulsive fix points, and we call the pair $g, h \in \Gamma \setminus \{e\}$ *linked* if (g_-, h_-, g_+, h_+) are cyclically ordered - for $\Gamma = \pi_1(S_g)$ this holds if and only if the corresponding closed geodesics for some (and thus any) choice of hyperbolic metric intersect in S_g . Note that this in particular asks that the four points are distinct. Clearly $g, h \in \Gamma$ are linked if and only if $g, h^{-1} \in \Gamma$ are linked. Throughout the section $g, h \in \Gamma$ will always denote a linked pair.

This section is devoted to the proof of Theorem 1.1 from the Introduction, which we restate here for the reader's convenience:

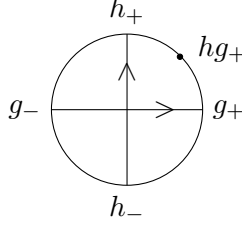


FIGURE 5. The relative positions of the fixed points of linked $g, h \in \Gamma$.

Theorem 6.1. *If $\rho : \Gamma \rightarrow \mathrm{SL}(E)$ satisfies properties $H_{k-1}, H_k, H_{k+1}, H_{d-k-1}, H_{d-k}, H_{d-k+1}$ and C_{k-1}, C_k . Then for every linked pair $g, h \in \Gamma$*

$$(6) \quad \frac{\lambda_1 \dots \lambda_k}{\lambda_d \dots \lambda_{d-k+1}}(g_\rho) > \left(1 - \frac{\lambda_{k+1}}{\lambda_k}(h_\rho)\right)^{-1}.$$

The proof is divided in three steps: In the first step we use the cross ratio $\mathrm{pcr}_{h_-^{d-k-1}}$ and the connection to the cross ratio gcr_{d-k} to bound the right hand side of (6) from above by

$$\mathrm{gcr}_{d-k}(h_-^{d-k}, h_+^k, gh_+^k, (g_+^k \cap h_-^{d-k+1}) \oplus h_-^{d-k-1}).$$

The main step of the proof is the second step, where we show that moving $(g_+^k \cap h_-^{d-k+1}) \oplus h_-^{d-k-1}$ to g_+^{d-k} does not decrease the value of gcr_{d-k} . In the third step we use the fact that the representation is positively ratioed to further increase the value by replacing h_-^{d-k} with g_-^{d-k} .

Step 1: Relating the eigenvalue gap with a Grassmannian cross ratio. In this section we will consider the two dimensional vector space $H := h_-^{d-k+1}/h_-^{d-k-1}$ and study the k -th \mathbb{RP}^1 projection based at h_-

$$P_{h_-} : \partial_\infty \Gamma \rightarrow \mathbb{P}\left(h_-^{d-k+1}/h_-^{d-k-1}\right)$$

introduced in Definition 4.6.

Proposition 6.2. *Assume that ρ has property H_k . Then*

$$\left(1 - \frac{\lambda_{k+1}}{\lambda_k}(h_\rho)\right)^{-1} < \mathrm{pcr}(P_{h_-}(h_-), P_{h_-}(h_+), P_{h_-}(gh_+), P_{h_-}(g_+)).$$

Proof. Since h_ρ induces a linear map of the two dimensional vector space H with eigenvalues $\lambda_k(h_\rho), \lambda_{k+1}(h_\rho)$, we deduce from Proposition 3.4 that

$$\frac{\lambda_k(h_\rho)}{\lambda_{k+1}(h_\rho)} = \mathrm{pcr}(P_{h_-}(h_-), P_{h_-}(g_+), P_{h_-}(hg_+), P_{h_-}(h_+)).$$

Applying the symmetries of the projective cross ratio, namely (1), (8) and again (1) from Lemma 3.1, we get

$$\left(1 - \frac{\lambda_{k+1}}{\lambda_k}(h_\rho)\right)^{-1} = \text{pcr}(P_{h_-}(h_-), P_{h_-}(h_+), P_{h_-}(hg_+), P_{h_-}(g_+)).$$

Since by hyperbolic dynamics $h_-, h_+, hg_+, gh_+, g_+$ are in that cyclic order on $\partial_\infty\Gamma$ ([LZ17, Lemma 2.2]) and P_{h_-} preserves the order (Proposition 4.9), we get

$$\begin{aligned} & \text{pcr}(P_{h_-}(h_-), P_{h_-}(h_+), P_{h_-}(hg_+), P_{h_-}(g_+)) \\ & < \text{pcr}(P_{h_-}(h_-), P_{h_-}(h_+), P_{h_-}(gh_+), P_{h_-}(g_+)), \end{aligned}$$

which proves the claim. \square

We conclude the first step with:

Corollary 6.3. *Let ρ satisfy property H_k . Then*

$$\left(1 - \frac{\lambda_{k+1}}{\lambda_k}(h_\rho)\right)^{-1} < \text{gcr}_{d-k}\left(h_-^{d-k}, h_+^k, gh_+^k, \left(g_+^k \cap h_-^{d-k+1}\right) \oplus h_-^{d-k-1}\right)$$

Proof. By the lemma above it is enough to show that

$$\begin{aligned} & \text{pcr}(P_{h_-}(h_-), P_{h_-}(h_+), P_{h_-}(gh_+), P_{h_-}(g_+)) \\ & = \text{gcr}_{d-k}\left(h_-^{d-k}, h_+^k, gh_+^k, \left(g_+^k \cap h_-^{d-k+1}\right) \oplus h_-^{d-k-1}\right). \end{aligned}$$

This however is a consequence of the relation of the projective cross ratio on $\mathbb{P}(h_-^{d-k+1}/h_-^{d-k-1})$ and gcr_{d-k} as in Corollary 3.12. \square

Step 2: Replacing $\left(g_+^k \cap h_-^{d-k+1}\right) \oplus h_-^{d-k-1}$ with g_+^{d-k} . Recall that for pairwise distinct points $x, y, z \in \partial_\infty\Gamma$ we denote by $(x, y)_z$ the connected component of $\partial_\infty\Gamma \setminus \{x, y\}$ that does *not* contain z (Notation 2.3). We fix throughout the section an orientation on $S^1 \simeq \partial_\infty\Gamma$ such that the ordered triples (h_-, x, g_+) for $x \in (h_-, g_+)_{g_-}$ are positively oriented.

As already in the proof of Theorem 5.3, instead of proving directly that replacing $\left(g_+^k \cap h_-^{d-k+1}\right) \oplus h_-^{d-k-1}$ with g_+^{d-k} does not decrease the cross ratio, we will show that this is true infinitesimally, where hyperconvexity properties give us good control, and deduce the statement through the fundamental theorem of calculus.

More specifically we consider the map

$$\begin{aligned} \eta : (h_-, g_+)_{g_-} & \rightarrow \text{Gr}_{d-k}(E), \\ x & \mapsto \left(x^{d-k+1} \cap g_+^k\right) \oplus x^{d-k-1}. \end{aligned}$$

This continuously interpolates between $\left(g_+^k \cap h_-^{d-k+1}\right) \oplus h_-^{d-k-1}$ and g_+^{d-k} :

Lemma 6.4. *Assume that ρ satisfies property H_k . Then $\eta(x) \rightarrow g_+^{d-k}$ for $x \rightarrow g_+$.*

Proof. This follows from Proposition 2.13, as property H_k guarantees that

$$g_-^k \pitchfork \left((x^{d-k+1} \cap g_+^k) \oplus x^{d-k-1} \right)$$

for all $x \in \partial_\infty \Gamma \setminus \{g_\pm\}$. \square

The goal of the second step is then to prove the following:

Proposition 6.5. *If $\rho : \Gamma \rightarrow \mathrm{SL}(E)$ satisfies properties $H_{k-1}, H_k, H_{k+1}, H_{d-k-1}, H_{d-k+1}$ and C_{k-1}, C_k . Then*

$$x \mapsto \mathrm{gcr}_{d-k} \left(h_-^{d-k}, h_+^k, gh_+^k, \eta(x) \right)$$

is non-decreasing for $x \in (h_-, g_+)_{g_-}$ moving towards g_+ .

As already mentioned we want to prove the infinitesimal version of Proposition 6.5; however, while it follows from property H_{d-k-1} and H_{d-k+1} respectively that ξ^{d-k-1} and ξ^{d-k+1} have C^1 images, and the same is true for the curve

$$\begin{aligned} \xi_{g_+}^{d-k+1} : \partial_\infty \Gamma \setminus \{g_+\} &\rightarrow \mathbb{P}(g_+^k) \\ x &\mapsto x^{d-k+1} \cap g_+^k, \end{aligned}$$

there might not be a way to reparametrize $\partial_\infty \Gamma$ to make both ξ^{d-k-1} and $\xi_{g_+}^{d-k+1}$ simultaneously differentiable. Consequently the image of η might not be a C^1 submanifold of $\mathrm{Gr}_{d-k}(E)$.

Remark 6.6. If $k = 1$, i.e. in the 'projective setting', the curve $x \mapsto \eta(x) = g_+^1 \oplus x^{d-2}$ has already C^1 -image. Thus the proof simplifies slightly as we can directly prove Proposition 6.5, with the same proof as Lemma 6.9.

We overcome this difficulty by considering η as the diagonal in the surface $\Sigma \subset \mathrm{Gr}_{d-k}(E)$ which is the image of the map

$$\begin{aligned} \xi_{g_+}^{d-k+1} \oplus \xi^{d-k-1} : ((h_-, g_+)_{g_-})^2 &\rightarrow \mathrm{Gr}_{d-k}(E) \\ (z, w) &\mapsto \xi_{g_+}^{d-k+1}(z) \oplus \xi^{d-k-1}(w). \end{aligned}$$

Since ρ is k -Anosov such map is well defined, and since both $\xi_{g_+}^{d-k+1}$ and ξ^{d-k-1} have C^1 image, the surface Σ is indeed a C^1 submanifold of $\mathrm{Gr}_{d-k}(E)$. For a point $x \in (h_-, g_+)_{g_-}$, we will denote by Φ_x (resp. Ψ_x) in $T_{\eta(x)} \mathrm{Gr}_{d-k}(E)$ a chosen vector tangent to the horizontal (resp. vertical) leaf to the surface Σ . We will furthermore assume that the sign of these vectors is induced by the orientation of the interval $(h_-, g_+)_{g_-}$.

Lemma 6.7. *If $\rho : \Gamma \rightarrow \mathrm{SL}(E)$ satisfies properties H_{d-k-1}, H_{d-k+1} , then the image of η is a Lipschitz submanifold of $\mathrm{Gr}_{d-k}(E)$, i.e. locally the graph of a Lipschitz map. Whenever defined, the derivative of η is a non-negative linear combination of the vectors Φ_x and Ψ_x .*

Proof. If we choose smooth parametrizations $\varphi, \psi : [0, 1] \rightarrow (h_-, g_+)_{g_-}$ such that

$$\xi^{d-k-1} \circ \psi : [0, 1] \rightarrow \mathrm{Gr}_{d-k-1}(E), \quad \xi_{g_+}^{d-k+1} \circ \varphi : [0, 1] \rightarrow \mathbb{P}(g_+^k)$$

are smooth maps, then

$$\begin{aligned} F : [0, 1]^2 &\rightarrow \text{Gr}_{d-k}(E) \\ (s, t) &\mapsto (\xi_{g_+}^{d-k+1} \circ \varphi(s)) \oplus (\xi^{d-k-1} \circ \psi(t)). \end{aligned}$$

gives a C^1 parametrization of the surface Σ .

By construction φ and ψ are strictly monotone maps, thus in particular invertible. As a result, denoting by $\Delta \subset ((h_-, g_+)_{g_-})^2$ the diagonal, we have that $D := (\varphi^{-1}, \psi^{-1})(\Delta) \subset [0, 1]^2$ is the graph of a monotone map, in particular a Lipschitz submanifold. Since $\eta((h_-, g_+)_{g_-}) = F(D)$ is the C^1 image of a Lipschitz submanifold, it has itself Lipschitz image. The claim about the derivative follows from the analogue claim on the curve $D \subset [0, 1]^2$, which is the graph of a monotone map. \square

In particular it follows from Rademacher's theorem that η has almost everywhere a well defined derivative, and the fundamental theorem of calculus applies. As a result Proposition 6.5 follows as soon as the next two lemmas are established.

Lemma 6.8. *Let, as above, Φ_x denote the tangent to the horizontal leaf of the surface Σ at $\eta(x)$. Then properties $H_{k-1}, H_k, H_{d-k+1}, C_{k-1}$ guarantee that*

$$(7) \quad d_{\eta(x)} \text{gcr}_{d-k}(h_-^{d-k}, h_+^k, gh_+^k, \cdot)(\Phi(x)) \geq 0.$$

Proof. In order to verify the claim it is enough to show that, for a smooth curve $x_t : (-\epsilon, \epsilon) \rightarrow \text{Gr}_{d-k}(E)$ with $x_0 = \eta(x)$, and $\dot{x}_0 = \Phi_x$ it holds

$$(8) \quad \left. \frac{d}{dt} \right|_{t=0} \text{gcr}_{d-k}(h_-^{d-k}, h_+^k, gh_+^k, x_t) \geq 0.$$

We will prove this in two steps, first we will reduce the verification to checking monotonicity of a suitable projective cross ratio along a preferred path x_t , as expressed in Equation (10), then we will use hyperconvexity of the $(k-1)$ -th $\mathbb{R}\mathbb{P}^2$ -projection to check that Equation (10) holds true.

Recall that $\Phi_x \in T_{\eta(x)}\text{Gr}_{d-k}(E)$ is tangent to the horizontal leaf given by $\xi_{g_+}^{d-k+1}(w) \oplus x^{d-k-1}$, as w varies in $(h_-, g_+)_{g_-}$. As a result, we can assume that x^{d-k-1} is always contained in x_t , furthermore since the tangent to $\xi_{g_+}^{d-k+1}$ at x is the tangent to the projective line $\mathbb{P}(x^{d-k+2} \cap g_+^k)$ (Proposition 4.2), we can choose x_t contained in x^{d-k+2} .

This is helpful in reducing to a projective cross ratio: if we denote by \overline{X}_g the space $\overline{X}_g = (x^{d-k+2} \cap g_+^k) \oplus x^{d-k-1}$ and by X_g its two dimensional quotient $X_g := \overline{X}_g / x^{d-k-1}$, and apply the cocycle identity of gcr_{d-k} and

Corollary 3.12, we get

$$(9) \quad \begin{aligned} & \text{gcr}_{d-k} \left(h_-^{d-k}, h_+^k, gh_+^k, x_t \right) = \\ & \text{gcr}_{d-k} \left(h_-^{d-k}, h_+^k, gh_+^k, x_0 \right) \text{gcr}_{d-k} \left(x_0, h_+^k, gh_+^k, x_t \right) = \\ & \text{gcr}_{d-k} \left(h_-^{d-k}, h_+^k, gh_+^k, x_0 \right) \text{pcr}([x_0]_{X_g}, [h_+^k \cap \bar{X}_g]_{X_g}, [gh_+^k \cap \bar{X}_g]_{X_g}, [x_t]_{X_g}). \end{aligned}$$

Property H_k implies that the quantity $\text{gcr}_{d-k} \left(h_-^{d-k}, h_+^k, gh_+^k, x_0 \right)$ is always positive: it is never zero, it is continuous in $x \in (h_-, g_+)_{g_-}$ and it is positive close to h_- (Corollary 6.3). As a result, in order to prove the lemma, it is enough to show that

$$(10) \quad \left. \frac{d}{dt} \right|_{t=0} \text{pcr}([x_0]_{X_g}, [h_+^k \cap \bar{X}_g]_{X_g}, [gh_+^k \cap \bar{X}_g]_{X_g}, [x_t]_{X_g}) \geq 0.$$

We will verify Equation (10) showing that, for t small, the four points $([x_0]_{X_g}, [h_+^k \cap \bar{X}_g]_{X_g}, [gh_+^k \cap \bar{X}_g]_{X_g}, [x_t]_{X_g})$ are in this cyclic order on the line $\mathbb{P}(X_g)$. To this goal, set $X := x^{d-k+2}/x^{d-k-1}$ and recall that it follows from Proposition 4.17 that, since ρ satisfies properties H_{k-1}, C_{k-1} , the $(k-1)$ -th $\mathbb{R}\mathbb{P}^2$ projection $\pi_x : \partial_\infty \Gamma \rightarrow \mathcal{F}(X)$ defines a hyperconvex curve.

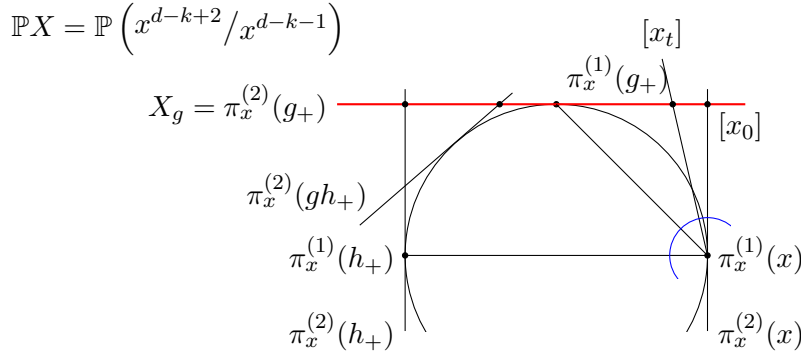


FIGURE 6. Hyperconvexity of π_x in an affine chart. We assume $t > 0$, i.e. x_t moves towards g_+ . The blue half circle identifies with $\mathbb{P}(X/\pi_x^{(1)}(x))$.

Note that $X_g = \pi_x^{(2)}(g_+)$ and thus $[x_0]_{X_g} = \pi_x^{(2)}(g_+) \cap \pi_x^{(2)}(x)$. Then hyperconvexity of π_X implies that, for t small enough, the four points

$$\left([\pi_x^{(2)}(gh_+) \cap \pi_x^{(2)}(g_+)], [\pi_x^{(2)}(h_+) \cap \pi_x^{(2)}(g_+)], [x_0], [\pi_x^{(1)}(g_+)] \right)$$

are in that cyclic order on $\mathbb{P}(X_g) = \mathbb{P}(\pi_x^{(2)}(g_+^k))$ - cfr. Figure 6.

By assumption ρ satisfies properties H_{k-1}, H_{d-k+1} , and thus is $(k-1)$ -positively ratioed (Theorem 5.3); in particular for the linear approximation $L_x : (-\epsilon, \epsilon) \rightarrow \text{Gr}_{d-k-1}(E)$ of ξ^{d-k+1} at x (recall Definition 4.3) which is defined by $[x_t]_{X_g} = [L_x(t)]_X \cap \pi_x^{(2)}(g_+)$, we have

$$\left. \frac{d}{dt} \right|_{t=0} \text{gcr}_{k-1}(h_+^{k-1}, x^{d-k+1}, L_x(t), g_+^{k-1}) > 0,$$

and thus $\left(\pi_x^{(1)}(h_+), \pi_x^{(2)}(x), [L_x(t)]_X, \pi_x^{(1)}(g_+) \right)$ for $t > 0$ descend to points in that cyclic order on $\mathbb{P}(X/\pi_x^{(1)}(x))$ (cfr. Corollary 3.12). Using $[x_t]_{X_g} = [L_x(t)]_X \cap \pi_x^{(2)}(g_+)$, and the hyperconvexity of π_x we derive that, for all t positive and small enough,

$$\left([\pi_x^{(2)}(gh_+) \cap \pi_x^{(2)}(g_+)], [\pi_x^{(2)}(h_+) \cap \pi_x^{(2)}(g_+)], [x_0], [x_t], [\pi_x^{(1)}(g_+)] \right)$$

are in that cyclic order on $\mathbb{P}(X_g) = \mathbb{P}(\pi_x^{(2)}(g_+))$ - cfr. again Figure 6.

Thus for all t positive and small enough, we can derive from the properties of the projective cross ratio (cfr. Lemma 3.1(9)) that

$$\begin{aligned} & \text{pcr}^{X_g}([x_0], [h_+^k \cap \overline{X}_g], [gh_+^k \cap \overline{X}_g], [x_t]) > 1 \\ \implies & \left. \frac{d}{dt} \right|_{t=0} \text{pcr}^{X_g}([x_0], [h_+^k \cap \overline{X}_g], [gh_+^k \cap \overline{X}_g], [x_t]) \geq 0. \quad \square \end{aligned}$$

Lemma 6.9. *Let, as above Ψ_y denote the tangent to the vertical leaf of the surface Σ at $\eta(y)$. Then properties $H_k, H_{k+1}, H_{d-k-1}, C_k$ guarantee that*

$$d_{\eta(y)} \text{gcr}_{d-k}(h_-^{d-k}, h_+^k, gh_+^k, \cdot)(\Psi_y) \geq 0.$$

Proof. The proof is analogous to the proof of Lemma 6.8. To avoid confusion with the proof of that lemma we write now $y \in (h_-, g_+)_{g_-}$. As above it is enough to show that for a chosen curve $y_t : (-\epsilon, \epsilon) \rightarrow \text{Gr}_{d-k}(E)$ with $y_0 = \eta(y)$, $\dot{y}_0 = \Psi_y$,

$$(11) \quad \left. \frac{d}{dt} \right|_{t=0} \text{gcr}_{d-k}(h_-^{d-k}, h_+^k, gh_+^k, y_t) \geq 0.$$

Observe that we can choose y_t in the pencil⁶ $\mathbb{P}\left(y^{d-k+1}/y^{d-k-2} \oplus (y^{d-k+1} \cap g_+^k)\right)$: indeed we can choose y_t as the direct sum of the line $y^{d-k+1} \cap g_+^k$ and a linear approximation of ξ^{d-k-1} at y .

If we set

$$\begin{aligned} Y &:= y^{d-k+1}/y^{d-k-2} \\ Y_g &:= y^{d-k+1}/\left((y^{d-k+1} \cap g_+^k) \oplus y^{d-k-2}\right) \end{aligned}$$

⁶Recall Definition 4.3

we can use the same argument as in the first step of the proof of Lemma 6.8 to deduce that it is enough to show that

$$(12) \quad \frac{d}{dt} \Big|_{t=0} \text{pcr}^{Y_g}([y_0], [h_+^k \cap y^{d-k+1}], [gh_+^k \cap y^{d-k+1}], [y_t]) \geq 0.$$

Since ρ satisfies properties H_k, C_k , the k -th $\mathbb{R}\mathbb{P}^2$ -projection $\pi_y : \partial_\infty \Gamma \rightarrow \mathcal{F}(Y)$ is hyperconvex (Proposition 4.17). Since $\mathbb{P}(Y_g) \simeq \mathbb{P}(Y/\pi_y^{(1)}(g_+))$, hyperconvexity implies that

$$\left([\eta(y)]_{Y_g} = [\pi_y^{(1)}(y)]_{Y_g}, [\pi_y^{(2)}(g_+)]_{Y_g}, [\pi_y^{(1)}(gh_+)]_{Y_g}, [\pi_y^{(1)}(h_+)]_{Y_g} \right)$$

are in that cyclic order on $\mathbb{P}(Y_g) \simeq \mathbb{P}(Y/\pi_y^{(1)}(g_+))$ - compare Figure 7.

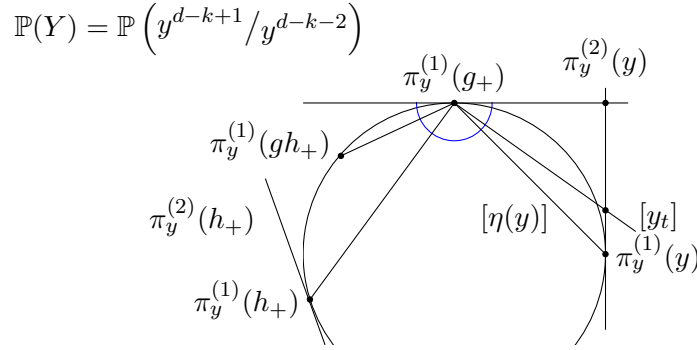


FIGURE 7. Hyperconvexity of π_Y , where $t > 0$, i.e. y_t 'moves towards' g_+ . The blue half circle can be identified with $\mathbb{P}(Y_g)$.

Moreover for the linear approximation L_y of ξ^{d-k-1} at y defined by $[L_y(t)]_Y = [y_t]_Y \cap \pi_y^{(2)}(y)$, it holds

$$\frac{d}{dt} \Big|_{t=0} \text{gcr}_{k+1}(h_+^{k+1}, y^{d-k-1}, L_y(t), g_+^{k+1}) > 0$$

because ρ satisfies properties H_{k+1}, H_{d-k-1} and thus is $(k+1)$ -positively ratioed. This implies that, for $t > 0$, the points

$$\left(\pi_y^{(2)}(g_+) \cap \pi_y^{(2)}(y), [L_y(t)], \pi_y^{(1)}(y), \pi_y^{(2)}(h_+) \cap \pi_y^{(2)}(y) \right)$$

are in that cyclic order on $\mathbb{P}(\pi_y^{(2)}(y))$ (see Corollary 3.12). Since $[L_y(t)]_Y = [y_t]_Y \cap \pi_y^{(2)}(y)$, we derive for any sufficiently small positive t that

$$\left([\eta(y)]_{Y_g} = [y^{d-k-1}]_{Y_g}, [y_t]_{Y_g}, [\pi_y^{(2)}(g_+)]_{Y_g}, [\pi_y^{(1)}(gh_+)]_{Y_g}, [\pi_y^{(1)}(h_+)]_{Y_g} \right)$$

are in that cyclic order on $\mathbb{P}(Y_g) \simeq \mathbb{P}(Y/\pi_y^{(1)}(g_+))$ - compare Figure 7. This finishes the proof, as we can now derive with Lemma 3.1(9) that Equation (12) holds. \square

Step 3: Conclusion. We know from Corollary 6.3 that

$$\left(1 - \frac{\lambda_{k+1}}{\lambda_k}(h_\rho)\right)^{-1} < \text{gcr}_{d-k} \left(h_-^{d-k}, h_+^k, gh_+^k, \left(g_+^k \cap h_-^{d-k+1} \right) \oplus h_-^{d-k-1} \right),$$

and from Proposition 6.5 that

$$x \mapsto \text{gcr}_{d-k} \left(h_-^{d-k}, h_+^k, gh_+^k, \left(g_+^k \cap x^{d-k+1} \right) \oplus x^{d-k-1} \right)$$

is non-decreasing for $x \in (h_-, g_+)_{g_-}$ moving towards g_+ . Thus

$$\left(1 - \frac{\lambda_{k+1}}{\lambda_k}(h_\rho)\right)^{-1} < \text{gcr}_{d-k} \left(h_-^{d-k}, h_+^k, gh_+^k, g_+^{d-k} \right).$$

Moreover ρ is $(d-k)$ -positively ratioed, because it satisfies properties H_k, H_{d-k} (Theorem 5.3). Since h_-, g_-, h_+, gh_+, g_+ are in that cyclic order, this yields via the cocycle identity (Lemma 3.7 (2)) that

$$\text{gcr}_{d-k} \left(h_-^{d-k}, h_+^k, gh_+^k, g_+^{d-k} \right) < \text{gcr}_{d-k} \left(g_-^{d-k}, h_+^k, gh_+^k, g_+^{d-k} \right).$$

Theorem 6.1 follows then from Corollary 3.10, stating that

$$\text{gcr}_{d-k}(g_-^{d-k}, h_+^k, gh_+^k, g_+^{d-k}) = \frac{\lambda_1 \cdots \lambda_k}{\lambda_{d-k+1} \cdots \lambda_d}(g_\rho).$$

7. A COUNTEREXAMPLE TO THE STRONG COLLAR LEMMA

The goal of the section is to prove Theorem 1.12 from the introduction, which we recall for the reader's convenience (here $\Gamma_{1,1}$ is the fundamental group of the once punctured torus):

Theorem 7.1. *There is a one parameter family of positive representations $\rho_x : \Gamma_{1,1} \rightarrow \text{PSL}(3, \mathbb{R})$, for $x \in (0, \infty)$, and $\gamma, \delta \in \Gamma_{1,1}$ such that*

$$\ell_{\alpha_1}(\rho_x(\gamma)) = \ell_{\alpha_1}(\rho_x(\delta)) \rightarrow 0$$

as x goes to zero.

Proof. We realize the once punctured torus as the quotient of a square modulo the identification of parallel sides, in such a way that the puncture is the image of the vertices. We fix the triangulation of such surface whose sides are the positive diagonal, and the two sides of the square. Following Fock-Goncharov positive representations of $\Gamma_{1,1}$ are uniquely determined by 6 shear invariants (corresponding to the three sides of the triangulation) and 2 triple ratios [FG06]. We will set all shear invariants to be zero, while the triple ratios will degenerate (in opposite directions) along the sequence.

Given three flags $([A^1], \langle A^1, A^2 \rangle), ([B^1], \langle B^1, B^2 \rangle), ([C^1], \langle C^1, C^2 \rangle) \in \mathcal{F}(\mathbb{R}^3)$ and an identification $\wedge^3 \mathbb{R}^3 \simeq \mathbb{R}$ their *triple ratio* is defined by

$$\tau(A, B, C) = \frac{A^1 \wedge A^2 \wedge B^1}{A^1 \wedge A^2 \wedge C^1} \cdot \frac{B^1 \wedge B^2 \wedge C^1}{B^1 \wedge B^2 \wedge A^1} \cdot \frac{C^1 \wedge C^2 \wedge A^1}{C^1 \wedge C^2 \wedge B^1}.$$

It is immediate to check that the value of $\tau(A, B, C)$ doesn't depend on the choices involved. Moreover given two flags $A, C \in \mathcal{F}(\mathbb{R}^3)$ and two transverse

lines $[B^1], [D^1] \in \mathbb{P}(\mathbb{R}^3)$. The *shears* are defined by (compare [Par15, Section 2.6])

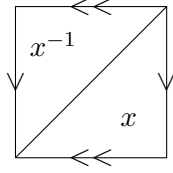
$$\sigma(A, [B^1], C, [D^1]) := (\log(-\text{pcr}_{A_1}(A, B_1, D_1, C_1)), \log(-\text{pcr}_{C_1}(C, B_1, D_1, A_1))).$$

In our example we will assume that all the shears are equal to 0, this corresponds to the points being in harmonic position.

Observe that given two flags A, C and two lines $[B^1], [D^1]$, the shear has the form $\sigma(A, [B^1], C, [D^1]) = (0, 0)$ if and only if there exists a basis e_1, e_2, e_3 with

$$\begin{aligned} A &= ([e_1], \langle e_1, e_2 \rangle) \\ B_1 &= [(1, -1, 1)^T] \\ C &= ([e_3], \langle e_3, e_2 \rangle) \\ D_1 &= [(1, 1, 1)^T] \end{aligned}$$

We can then consider the positive representation $\rho_x : \Gamma_{1,1} \rightarrow \text{PSL}(3, \mathbb{R})$ of the fundamental group $\Gamma_{1,1}$ of the once punctured torus whose Fock-Goncharov parameters are given by the triangle invariant x, x^{-1} and all whose shears are fixed equal to $(0, 0)$.



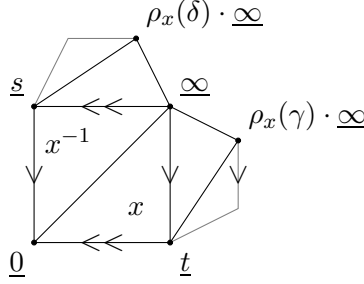
We denote by $\gamma \in \Gamma_{1,1}$ the element realizing the identification of the vertical sides, and by $\delta \in \Gamma_{1,1}$ the element realizing the identification of the horizontal sides. Up to conjugating the representation we can assume that the two endpoints of the diagonal are associated to the standard flags

$$\begin{aligned} \underline{\infty} &:= ([e_1], \langle e_1, e_2 \rangle) \\ \underline{0} &:= ([e_3], \langle e_3, e_2 \rangle). \end{aligned}$$

In order to compute representatives of $\rho_x(\gamma)$ and $\rho_x(\delta)$ we need to compute the flags $\underline{t}, \underline{s}$ determined by

$$\begin{aligned} \tau(\underline{\infty}, \underline{s}, \underline{0}) &= x^{-1} \\ \tau(\underline{0}, \underline{t}, \underline{\infty}) &= x \end{aligned}$$

As well as the lines in the images $\gamma(\underline{\infty}^1), \delta(\underline{\infty}^1)$, which are uniquely determined by our requirements on the shears.



It is easy to check that with our assumptions we have

$$\begin{aligned} \underline{t} &= \left(\left[\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right], \left\langle \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ -x \end{pmatrix} \right\rangle \right) & \rho_x(\gamma) \cdot \underline{\infty}^1 &= \begin{pmatrix} 2x^{-1} + 2 \\ 2 \\ 1 \end{pmatrix} \\ \underline{s} &= \left(\left[\begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} \right], \left\langle \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ -x \end{pmatrix} \right\rangle \right) & \rho_x(\delta) \cdot \underline{\infty}^1 &= \begin{pmatrix} 2x^{-1} + 2 \\ -2 \\ 1 \end{pmatrix}. \end{aligned}$$

One directly checks that the matrices for the elements $\rho_x(\gamma), \rho_x(\delta)$ are

$$\begin{aligned} \rho_x(\gamma) &= \sqrt[3]{x^{-1}} \begin{pmatrix} 2x + 2 & 2x + 2 & 1 \\ 2x & 2x + 1 & 1 \\ x & x + 1 & 1 \end{pmatrix} \\ \rho_x(\delta) &= \sqrt[3]{x^{-1}} \begin{pmatrix} 2x + 2 & -2x - 2 & 1 \\ -2x & 2x + 1 & -1 \\ x & -x - 1 & 1 \end{pmatrix}. \end{aligned}$$

The characteristic polynomials of these two matrices are both given by

$$\chi(\lambda) = \lambda^3 - \lambda^2(4x^{-\frac{1}{3}} + 4x^{\frac{2}{3}}) + \lambda(4x^{\frac{1}{3}} + 4x^{-\frac{2}{3}}) - 1.$$

We want to consider the limit as $x \rightarrow 0$. To simplify the equations we substitute $y = x^{-\frac{1}{3}}$. Hence we get

$$(13) \quad \lambda_1(y) + \lambda_2(y) + \lambda_3(y) = 4(y + y^{-2})$$

$$(14) \quad \lambda_1(y)\lambda_2(y) + \lambda_1(y)\lambda_3(y) + \lambda_2(y)\lambda_3(y) = 4(y^2 + y^{-1})$$

$$(15) \quad \lambda_1(y)\lambda_2(y)\lambda_3(y) = 1.$$

The eigenvalues are then necessarily positive (cfr. Proposition 1.5) and are ordered so that $\lambda_1(y) \geq \lambda_2(y) \geq \lambda_3(y)$. Hence Equation (13) yields that for $y \rightarrow \infty$ we have $\lambda_1(y) \rightarrow \infty$ and thus by Equation (15) $\lambda_3(y) \rightarrow 0$. Dividing Equation (13) by y we see that for every $\epsilon > 0$ there exists $N_\epsilon \in \mathbb{R}$ such that $\lambda_1(y)/y > 2 - \epsilon$ for all $y \geq N_\epsilon$.

We claim that $k := \liminf \lambda_2(y)/y > 0$: if $\liminf \lambda_2(y)/y = 0$ Equation (14) implies, by dividing with y^2 , that $\limsup \lambda_1(y)/y = \infty$. In this case

Equation (13) would yield that $\liminf \lambda_2(y)/y = -\infty$; a contradiction. This argument yields also $\limsup \lambda_1(y)/y < \infty$, and thus $\limsup \lambda_2(y)/y < \infty$. Hence if we pass to an increasing sequence $\{y_n\} \subset \mathbb{R}$ such that the limits $A := \lim_{n \rightarrow \infty} \lambda_1(y_n)/y_n$, $B := \lim_{n \rightarrow \infty} \lambda_2(y_n)/y_n$ exist, then those limits have to satisfy $A + B = 4$ and $AB = 4$, i.e. $A = 2 = B$. In particular it follows that $\lim_{y \rightarrow \infty} \lambda_1(y)/y = 2$, $\lim_{y \rightarrow \infty} \lambda_2(y)/y = 2$. This yields $\lim_{y \rightarrow \infty} \lambda_1(y)/\lambda_2(y) = 1$.

Finally, as $\rho_x(\gamma), \rho_x(\delta)$ have the same characteristic polynomial, which satisfies $\lambda_1(x)/\lambda_2(x) \rightarrow 1$ for $x \rightarrow 0$, we get the claim. \square

Observe that, as the representation ρ_x has unipotent boundary holonomy it is not restriction of a Hitchin representation of the double of the surface. It is however easy to choose small shears $\sigma(x)$ so that the associated sequence ρ'_x of representations has loxodromic boundary holonomy and can therefore be doubled to a Hitchin representation [LM09, Section 9.2].

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