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Hyper-holomorphic connections on vector bundles on hyper-Kähler manifolds

This is the final peer-reviewed author's accepted manuscript (postprint) of the following publication:

Published Version:

Hyper-holomorphic connections on vector bundles on hyper-Kähler manifolds / Meazzini, Francesco; Onorati, Claudio. - In: MATHEMATISCHE ZEITSCHRIFT. - ISSN 0025-5874. - STAMPA. - 303:1(In stampa/Attività in corso), pp. 17.1-17.34. [10.1007/s00209-022-03176-4]

Availability:

This version is available at: <https://hdl.handle.net/11585/914226> since: 2023-02-08

Published:

DOI: <http://doi.org/10.1007/s00209-022-03176-4>

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This is the final peer-reviewed accepted manuscript of:

Meazzini, F., Onorati, C. Hyper-holomorphic connections on vector bundles on hyper-Kähler manifolds. *Math. Z.* 303, 17 (2023)

The final published version is available online at <https://dx.doi.org/10.1007/s00209-022-03176-4>

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HYPER-HOLOMORPHIC CONNECTIONS ON VECTOR BUNDLES ON HYPER-KÄHLER MANIFOLDS

FRANCESCO MEAZZINI AND CLAUDIO ONORATI

ABSTRACT. We study infinitesimal deformations of autodual and hyper-holomorphic connections on complex vector bundles on hyper-Kähler manifolds of arbitrary dimension. In particular, we describe the DG Lie algebra controlling this deformation problem. Moreover, we prove associative formality for derived endomorphisms of a holomorphic vector bundle admitting a projectively hyper-holomorphic connection.

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INTRODUCTION

The notion of formality for (either commutative, or associative, or Lie) differential graded algebras has been used in several settings in order to obtain deep geometric results.

The first big step dates back to the work by Deligne–Griffiths–Morgan–Sullivan [DGMS75], where they proved that the de Rham algebra $(A_{\mathbb{R}}^*, d_{dR})$ of a compact Kähler manifold X is formal, hence deducing that the real homotopy type of X , controlled by the homotopy class of $(A_{\mathbb{R}}^*, d_{dR})$, is essentially determined by the cohomology algebra $H^*(X, \mathbb{R})$.

Using the same techniques of [DGMS75], Goldman and Millson [GM88] studied the moduli space of flat connections on a fixed complex vector bundle; this moduli space is hystorically a very interesting object being related to the character variety of representations of the fundamental group of the manifold and to the moduli space of Higgs bundles (which is an instance of the famous non-abelian Hodge theory). More precisely, if ∇ is a flat connection on E , then ∇ extends to a differential on the graded algebra $A^*(End(E))$ of complex valued C^∞ forms with coefficients in the endomorphism bundle $End(E)$, whose formality implies that the moduli space of certain representations of the fundamental group of a compact Kähler manifold admits at most quadratic singularities.

Another big step forward has been achieved by Kontsevich in [Kon03], where he proved that every finite dimensional Poisson manifold admits a canonical deformation quantization. This was obtained by showing the Lie formality of the Hochschild cohomology of the algebra A of smooth functions on a differentiable manifold with coefficients in A .

More recently, the papers [BZ18, BMM21] dealt with the so called *Kaledin–Lehn formality conjecture*, which mainly arose in the paper [KL07]. First it has been proved in [BZ18] that the homotopy class of derived endomorphisms $RHom(F, F)$ of a polystable coherent sheaf F on a K3 surface is associatively formal, then in [BMM21] it has been shown that $RHom(F, F)$ is Lie formal for every polystable coherent sheaf F on a smooth minimal surface of Kodaira dimension 0. In particular, both results imply that the moduli space of semistable sheaves on a K3 surface admits at most quadratic singularities.

Date. April 8, 2022.

2010 Mathematics Subject Classification. 14D05; 14D15; 14E30; 14J40.

Key words and phrases. Formality, irreducible holomorphic symplectic manifolds, hyper-holomorphic connections.

It is natural to ask if the same result holds for higher dimensional hyper-Kähler manifolds, but both the proofs mentioned above fail and the situation seems to become much more complicated. A milestone in such a higher dimensional setting is the paper [Ver96] where Verbitsky proved that the moduli space of stable vector bundles admitting a *projectively hyper-holomorphic connection* on a hyper-Kähler manifold has at most quadratic singularities. Roughly speaking, for a vector bundle E to have a projectively hyper-holomorphic connection means that the associated Azumaya algebra $End(E)$ deforms, as a holomorphic vector bundle, along the twistor family (cf. the definition of modular sheaf given in [Mar21]).

It is worth pointing out that on a K3 surface every stable holomorphic vector bundle admits such a connection, while on a higher dimensional hyper-Kähler manifold this turns out to be a particular restrictive assumption.

In the paper [O'Gr22a], O'Grady introduced the notion of *modular* sheaves, enlarging the class studied by Verbitsky to torsion free sheaves that are not necessarily locally free sheaves, and proving that for modular sheaves there exist a wall and chamber decomposition of the ample cone that behaves as in the classical K3 case.

In the literature one also finds few classes of sheaves on hyper-Kähler manifolds for which derived endomorphisms can be represented by a formal DG Lie algebra: the first class consists of some torsion sheaves supported on lagrangian submanifolds (see [Mla20]), while the second consists of so-called atomic sheaves (see [Bec22]).

One of the main focuses of the present paper is the study of the associative Dolbeault DG algebra $(A^{0,*}(End(E)), \bar{\partial})$ of C^∞ -valued differential forms with coefficients in the endomorphism bundle $End(E)$ of a holomorphic vector bundle E admitting a projectively hyper-holomorphic connection ∇ such that $\nabla^{0,1} + \bar{\partial}$. It is well known that $(A^{0,*}(End(E)), \bar{\partial})$ represents the homotopy class $RHom(E, E)$ (see e.g. [FIM12]). We prove the following result.

Theorem (Theorem 4.3). *Let E be a holomorphic vector bundle on a hyper-Kähler manifold and assume that E admits a projectively hyper-holomorphic connection. Then the Dolbeault DG algebra*

$$(A^{0,*}(End(E)), \bar{\partial})$$

is associatively formal.

The same result has been proved, with a different method, in [Bec22, Theorem 6.1] for powers of slope stable vector bundles admitting a projectively hyper-holomorphic connection. Our approach is completely different and highlights the hyper-Kähler structure.

When the holomorphic vector bundle bundle admits a flat connection, which is an example of a hyper-holomorphic connection, the same result is proved in [GM88, Section 9.2]. As a corollary we recover Verbitsky's quadraticity result. Our proof is easy, as it relies on the same ideas already pointed out in [DGMS75, GM88], where formality is obtained by either combining the de Rham differential d_{dR} with its adjoint d_{dR}^c , or by showing that ∇ and its $(0, 1)$ -part $\nabla^{0,1}$ satisfy similar properties whenever ∇ is a flat connection. Following this idea, in this paper we consider *autodual connections*, of which hyper-holomorphic connections are the metric case, which can be thought of as a generalisation of flat connections since they "become flat" after taking an appropriate quaternionic quotient (cf. Definition 3.4). Here is where the hyper-Kähler structure comes into play. Indeed this additional structure induces an action of the Lie group $SU(2)$ on the real tangent space of the manifold, and hence on all of its tensor products. Using this $SU(2)$ -action one can define a special class of Yang–Mills connections that have been called *autodual* by Kaledin–Verbitsky in [KV98]. Moreover, using Verbitsky's terminology [Ver96], an *hyper-holomorphic* connection can be defined as an autodual connection arising as the Chern connection of an hermitian metric.

Following the analogy with flat connections, we look for the DG Lie algebra controlling infinitesimal deformations of an autodual connection. As already recalled, if a connection ∇ is flat over E , then its deformations are controlled by the DG Lie algebra $(A^*(End(E)), [\nabla, -])$. Since autodual connections are analogous to flat connections on the quaternionic quotient, our first guess is to use such complex. More precisely, Verbitsky in [Ver07] describes the associative *quaternionic Dolbeault DG algebra*

$$(D^*(End(E)), [\nabla_+, -]),$$

which is the quotient of the de Rham DG algebra $A^*(End(E))$ with coefficients in $End(E)$ by an ideal defined using the $SU(2)$ -action (cf. Definition 3.4). Here the assumption on ∇ to be autodual ensures that

the induced operator $[\nabla_+, -]$ on $D^*(\text{End}(E))$ squares to zero, hence providing a differential on $D^*(\text{End}(E))$. We prove the following result.

Theorem (Theorem 5.8). *The infinitesimal autodual deformations of an autodual connection ∇ on a vector bundle E are controlled by the quaternionic Dolbeault DG Lie algebra*

$$(D^*(\text{End}(E)), [\nabla_+, -], [-, -]).$$

What we mean by an *autodual deformation* of an autodual connection is made precise in Section § 5, where we carefully define the corresponding deformation functor (cf. Definition 5.1).

The main properties of the quaternionic Dolbeault complex are studied in § 3. In Question 3.15 we ask whether this DG Lie algebra is formal. When the corresponding holomorphic vector bundle has a homotopy abelian DG Lie algebra, then we remark in Proposition 3.16 that this is the case for the quaternionic Dolbeault as well, hence being indeed formal. Nevertheless, the general behaviour is not known and we remark in Corollary 3.11 that the general machinery due to [DGMS75] does not apply in this case, so the formality problem is more subtle.

Finally, given an autodual connection ∇ on E , its $(0, 1)$ -part $\nabla^{0,1}$ defines a holomorphic structure on E . It is natural to wonder how the holomorphic deformations of $(E, \nabla^{0,1})$ are connected to the autodual deformations of (E, ∇) . Our answer to this question can be resumed as follows.

Theorem (Corollary 5.9). *Let E be a complex vector bundle on a hyper-Kähler manifold. Suppose E is endowed with a holomorphic structure $\bar{\partial}$ and a hyper-holomorphic connection $\nabla = \nabla^{1,0} + \bar{\partial}$. Then*

- (1) *for every holomorphic deformation $(E, \bar{\partial}')$ of $(E, \bar{\partial})$ there exists an autodual connection ∇' whose $(0, 1)$ -part is $\bar{\partial}'$,*
- (2) *there exists a 1:1 correspondence*

$$\{\text{first order deformations of } \bar{\partial}\} \longleftrightarrow \left\{ \begin{array}{l} \text{first order autodual deformations} \\ \text{of } \nabla \text{ whose } (0, 1)\text{-part is } \bar{\partial} \end{array} \right\}$$

We conclude by making the following remark. Moduli spaces of autodual connections has been constructed analytically and studied in [KV98]. In particular, in [KV98, Section 2.5] the authors construct a symplectic form on the holomorphic tangent space of such a moduli space. More generally they achieve these results for Yang–Mills connections on compact Kähler manifolds. In [KV98, Conjecture 8.1], the authors foresee that this symplectic form should come from an hyper-Kähler structure. From our point of view, an evidence for this conjecture seems to be given by Proposition 3.19 and [Ver96, Section 9]. More precisely, in loc. cit. Verbitsky defines a (singular) hyper-Kähler structure on the tangent space (in the Kuranishi family) of a holomorphic vector bundle admitting a hyper-holomorphic connection and our Proposition 3.19 states that the tangent space of the corresponding hyper-holomorphic connection is isomorphic to two copies of the said tangent space. In particular it has a hyper-Kähler structure as well.

Structure of the paper. In Section § 1 we provide an abstract presentation of the methods developed in [DGMS75]. More precisely, we introduce a class of associative DG algebras, endowed with an extra structure miming the main ingredients used by Deligne–Griffiths–Morgan–Sullivan. For this reason we call them *DGMS algebras*, see Definition 1.5. For the sake of completeness we state and prove an abstract formality result for DGMS algebras (cf. Theorem 1.8). Despite the fact that the proofs are essentially the same of [DGMS75], we found it useful to have an abstract account of the properties of this class of formal associative DG algebras, and we shall use them in different situations. We also briefly discuss the analog constructions in the Lie case.

In Section § 2 we recall basic definitions and results from the theory of irreducible holomorphic symplectic manifolds and autodual connections, while Section § 3 is devoted to a characterisation of autodual connections in terms of Maurer–Cartan equations, cf. Proposition 3.7. Here we also recall the notion of *quaternionic Dolbeault DG algebra* (cf. Definition 3.4), and we enlight its main properties (cf. Lemma 3.10, and Theorem 3.14), which will play an important role later on in the paper.

In Section § 4 we recall the classical theory of infinitesimal deformations of holomorphic vector bundles via DG Lie algebras and prove our formality statement, cf. Theorem 4.3. We also give some examples and contextualise our result with the existing literature.

Finally, in Section § 5 we study local properties of the moduli space of autodual connections on a fixed complex vector bundle. More precisely, we define the deformation functor associated to an autodual

connection and prove that it is naturally isomorphic to the deformation functor associated to the quaternionic Dolbeault DG Lie algebra via Maurer–Cartan equation modulo gauge action, cf. Theorem 5.8.

Acknowledgements. This work grew up from our attempt to understand Verbitsky’s work on hyperholomorphic connections, in particular his quadraticity result. We would like to thank him for his seminal papers on the subject, to which the present paper owes a lot.

We are grateful to Simone Diverio, Marco Manetti and Kieran O’Grady for useful conversations on the subject of this paper.

Both authors acknowledge support from Ateneo 2017 *Varietà speciali, spazi di moduli e teoria delle deformazioni*, that made possible the conference “hyper-Kähler varieties in Rome” organised in September 2021. The second author is also supported by the PRIN grant with CUP E84I19000500006.

1. DGMS ALGEBRAS

In this first section we work over a field \mathbb{K} of characteristic 0. The following algebraic data are inspired by the paper [DGMS75], so that the acronym DGMS in Definition 1.1 stands for Deligne–Griffiths–Morgan–Sullivan.

Definition 1.1. A DGMS vector space (A, d_0, d_1) is the datum of a graded \mathbb{K} -vector space $A = \bigoplus_{i \in \mathbb{Z}} A^i$ endowed with two \mathbb{K} -linear morphisms $d_0, d_1 \in \text{Hom}^1(A, A)$ of degree 1 satisfying the following properties:

- (1) $d_0^2 = d_1^2 = 0$,
- (2) $[d_0, d_1] = d_0 d_1 + d_1 d_0 = 0$,
- (3) the *strong $d_0 d_1$ -lemma* holds $\ker(d_0) \cap \ker(d_1) \cap (\text{Im}(d_0) + \text{Im}(d_1)) = \text{Im}(d_0 d_1)$.

In literature (for example in [GM88, Section 7]), the strong $d_0 d_1$ -lemma is often referred to as “principle of the two types”, since in all applications we always think at d_0 and d_1 as the $(1, 0)$ and the $(0, 1)$ part of a degree 1 differential d with respect to some additional structure.

Lemma 1.2. Let $A = \bigoplus_{j \in \mathbb{Z}} A^j$ be a graded vector space endowed with two differentials d_0 and d_1 . Under the hypothesis $[d_0, d_1] = 0$, the following conditions are equivalent.

- a:** Given an element $x \in A$ which is both d_0 -exact and d_1 -closed, then there exists $y \in A$ such that $x = d_0 d_1 y$.
- b:** $\ker(d_1) \cap \text{Im}(d_0) = \text{Im}(d_0 d_1)$.
- c:** The subcomplex $(\text{Im}(d_0), d_1)$ has trivial cohomology.

Similarly, the following conditions are equivalent.

- a*:** Given an element $x \in A$ which is both d_0 -closed and d_1 -exact, then there exists $y \in A$ such that $x = d_0 d_1 y$.
- b*:** $\ker(d_0) \cap \text{Im}(d_1) = \text{Im}(d_0 d_1)$.
- c*:** The subcomplex $(\text{Im}(d_1), d_0)$ has trivial cohomology.

Proof. Straightforward. □

In the following we shall denote by $H_{d_1}(A) = \frac{\ker(d_1)}{\text{Im}(d_1)}$ the cohomology of A with respect to d_1 , and similarly by $H_{d_0}(A) = \frac{\ker(d_0)}{\text{Im}(d_0)}$ the cohomology of A with respect to d_0 .

Lemma 1.3. Let A be a graded vector space endowed with two differentials d_0 and d_1 such that $[d_0, d_1] = 0$.

- If $\ker(d_1) \cap \text{Im}(d_0) = \text{Im}(d_0 d_1)$ then the differential induced by d_0 on $H_{d_1}(L)$ is trivial.
- If $\ker(d_0) \cap \text{Im}(d_1) = \text{Im}(d_0 d_1)$ then the differential induced by d_1 on $H_{d_0}(L)$ is trivial.

Proof. Consider a d_1 -closed element $x \in A$; notice that $d_0 x \in \ker(d_1) \cap \text{Im}(d_0)$, being $[d_0, d_1] = 0$. By hypothesis there exists $y \in A$ such that $d_0 x = d_0 d_1 y = -d_1 d_0 y$, so that $d_0 x \in \text{Im}(d_1)$ as required. The second item can be checked similarly. □

Notice that the standard $d_0 d_1$ -lemma $\ker(d_0) \cap \text{Im}(d_1) = \text{Im}(d_0 d_1)$ and the analogous $d_1 d_0$ -lemma $\ker(d_1) \cap \text{Im}(d_0) = \text{Im}(d_1 d_0)$ are not equivalent in general. The following result essentially states that the *strong $d_0 d_1$ -lemma* of Definition 1.1 is equivalent to require both the $d_0 d_1$ -lemma and the $d_1 d_0$ -lemma.

Lemma 1.4. *Let A be a graded vector space endowed with two differentials d_0 and d_1 . Assume that $[d_0, d_1] = 0$. Then the strong $d_0 d_1$ -lemma*

$$\ker(d_0) \cap \ker(d_1) \cap (\operatorname{Im}(d_0) + \operatorname{Im}(d_1)) = \operatorname{Im}(d_0 d_1)$$

holds if and only if all the items of Lemma 1.2 are satisfied.

Proof. We begin by showing that if the strong $d_0 d_1$ -lemma holds then $\ker(d_1) \cap \operatorname{Im}(d_0) = \operatorname{Im}(d_0 d_1)$. To this aim it is sufficient to show the only non trivial inclusion $\ker(d_1) \cap \operatorname{Im}(d_0) \subseteq \operatorname{Im}(d_0 d_1)$. Take a d_1 -closed element x , such that $x = d_0 y$ for some $y \in A$. Notice that

$$x = d_0 y \in \ker(d_0) \cap \ker(d_1) \cap (\operatorname{Im}(d_0) + \operatorname{Im}(d_1)).$$

By assumption there exists an element $z \in A$ such that $x = d_0 d_1 z$. Similarly one can prove that $\ker(d_0) \cap \operatorname{Im}(d_1) = \operatorname{Im}(d_0 d_1)$.

For the converse, assume that conditions **b** and **b*** of Lemma 1.2 are both satisfied. We need to show that

$$\ker(d_0) \cap \ker(d_1) \cap (\operatorname{Im}(d_0) + \operatorname{Im}(d_1)) \subseteq \operatorname{Im}(d_0 d_1).$$

Take an element $x \in A$ such that

$$\begin{cases} d_0 x = 0 \\ d_1 x = 0 \\ x = d_0 y_0 + d_1 y_1 \end{cases}$$

Now, since $0 = d_0 x = d_0 d_1 y_1$ we have $d_1 y_1 \in \ker(d_0) \cap \operatorname{Im}(d_1)$ and by condition **b** of Lemma 1.2 there exists $z_1 \in A$ such that $d_1 y_1 = d_0 d_1 z_1$. Similarly $d_0 y_0 \in \ker(d_1) \cap \operatorname{Im}(d_0)$ and by condition **b*** of Lemma 1.2 there exists $z_0 \in A$ such that $d_0 y_0 = d_0 d_1 z_0$. Hence $x = d_0 d_1 (z_0 + z_1)$ as required. \square

For the geometric applications of this paper, we will be interested in studying DGMS vector spaces that are endowed with an associative (not necessarily commutative) product, that is compatible with the differentials.

Recall that an associative DG algebra (A, \cdot, d) is a graded vector space $A = \bigoplus_{k \in \mathbb{Z}} A^k$ together with a graded product $\cdot : A^i \times A^j \rightarrow A^{i+j}$ and a differential $d : A^k \rightarrow A^{k+1}$ satisfying $d^2 = 0$ and the (graded) Leibniz rule:

$$d(a \cdot b) = d(a) \cdot b + (-1)^{\deg(a)} a \cdot d(b).$$

for every homogeneous elements $a, b \in A$.

Definition 1.5. An associative DGMS algebra (A, \cdot, d_0, d_1) is the datum of a DGMS vector space (A, d_0, d_1) such that both (A, \cdot, d_0) and (A, \cdot, d_1) are associative DG algebras.

Example 1.6 (de Rham algebra). Let $(A, \wedge, d_0 = d_{\text{dR}}, d_1 = d_{\text{dR}}^c)$ be the de Rham algebra of C^∞ -valued differential forms over a complex manifold endowed with the wedge product. Here d_{dR} is the de Rham differential and d_{dR}^c is its Hodge adjoint. Then by the $d_{\text{dR}} d_{\text{dR}}^c$ -lemma (together with the Hodge theorem – see [DGMS75]) and Lemma 1.4 we have that A is an associative DGMS algebra. Notice that in this case the associative product is graded commutative.

A morphism of associative DG algebras is simply a morphism of DG vector spaces that preserves the products. A morphism of associative DG algebras is called a *quasi-isomorphism* if the induced morphism in cohomology is a degreewise isomorphism.

Given an associative DG algebra (A, \cdot, d) , for every $a, b \in A$ we have

$$da = db = 0 \Rightarrow d(a \cdot b) = 0, \quad \text{and} \quad db = 0 \Rightarrow (da) \cdot b = d(a \cdot b),$$

so that the cohomology $H(A)$ inherits the product and it is an associative DG algebra (with trivial differential).

Definition 1.7. An associative DG algebra A is said to be *formal* if it is quasi isomorphic to its cohomology; i.e. if there exists another associative DG algebra M together with a pair of quasi-isomorphisms of associative DG algebras

$$(A, \cdot, d_A) \leftarrow (M, \cdot, d_M) \rightarrow (H_{d_A}(A), \cdot, 0).$$

Formality for DG algebras has many geometric consequences. For example Deligne, Griffiths, Morgan, Sullivan [DGMS75, Section 6] proved that the de Rham DG algebra $(A, \wedge, d_{\text{dR}})$ of a compact Kähler manifold X described in Example 1.6 is formal, hence showing that the real homotopy type of X is uniquely determined by its cohomology algebra $H^*(X, \mathbb{R})$.

The following formality result is largely inspired to [DGMS75, Section 6].

Theorem 1.8 (Formality for DGMS algebras). *Let (A, \cdot, d_0, d_1) be an associative DGMS algebra. Then (A, \cdot, d_0) is formal.*

Proof. Denote by $A_1 = \ker(d_1) \subseteq A$ the subspace of d_1 -closed elements. Notice that A_1 is an associative DG sub-algebra of A . Now consider the following morphisms of DG algebras

$$(A, \cdot, d_0) \xleftarrow{\iota} (A_1, \cdot, d_0) \xrightarrow{\rho} (H_{d_1}(A), \cdot, d_0);$$

here ι is the natural inclusion and ρ is the natural projection. By Lemma 1.3 the induced differential d_0 on $H_{d_1}(A)$ is trivial, so that it only remains to be shown that both ι and ρ induce isomorphisms in cohomology.

ι -step: Consider a d_0 -closed element $x \in A$ and notice that $d_1 x \in \ker(d_0) \cap \text{Im}(d_1)$. By the strong $d_0 d_1$ -lemma there exists $y \in A$ such that $d_1 x = d_0 d_1 y = -d_1 d_0 y$. Now define $\tilde{x} = x + d_0 y \in A_1$, ι maps the d_0 -cohomology class of \tilde{x} in the d_0 -cohomology class of x . This proves the surjectivity of ι in cohomology. For the injectivity take $x \in A_1$ such that $\iota(x) = x$ is d_0 -exact in A , so that $x \in \ker(d_1) \cap \text{Im}(d_0)$ and again by the strong $d_0 d_1$ -lemma we have $x = d_0 d_1 y$ for some $y \in A$ so that x is d_0 -exact also in A_1 .

ρ -step: Consider a class $[x] \in H_{d_1}(A)$ represented by a d_1 -closed element $x \in A$. Notice that $d_0 x \in \ker(d_1) \cap \text{Im}(d_0)$, being $[d_0, d_1] = 0$. By the $d_0 d_1$ -lemma there exists $y \in A$ such that $d_0 x = d_0 d_1 y$. Now consider the element $\tilde{x} = x + d_0 y \in \ker(d_1) \subseteq A_1$, which has the same d_0 -cohomology class as x in $H_{d_1}(A)$. This proves the surjectivity of ρ in cohomology. For the injectivity take $x \in A_1$ such that $\rho(x) = [x] = 0$ in $(H_{d_1}(A), d_0)$. Then $x \in \ker(d_0) \cap \text{Im}(d_1)$ since d_0 is trivial on $H_{d_1}(A)$; therefore by the strong $d_0 d_1$ -lemma there exists $y \in A$ such that $x = d_0 d_1 y$. Hence $[x] = [x'] = 0$ in $H_{d_0}(A_1)$ as required.

We have proven that (A, \cdot, d_0) is quasi-isomorphic to a DG algebra with trivial differential: i.e. (A, \cdot, d_0) is formal. \square

Remark 1.9. The proof of Theorem 1.8 shows that the cohomologies of any associative DGMS algebra with respect to the two differentials are the same, i.e. $H_{d_0}(A) \cong H_{d_1}(A)$. By the symmetry of Definition 1.1 we also proved that (A, \cdot, d_1) is formal. Moreover, it is straightforward to check that the isomorphism of graded vector spaces $H_{d_0}(A) \cong H_{d_1}(A)$ preserves the associative product so that (A, \cdot, d_0) and (A, \cdot, d_1) are quasi-isomorphic DG algebras.

The following result can be easily proved but it will lead to powerful applications.

Proposition 1.10. *Let (A, \cdot, d_0, d_1) be an associative DGMS algebra. Then $(A, \cdot, d_0 + d_1, d_1)$ is an associative DGMS algebra.*

Proof. For simplicity of exposition let us denote by $\delta_0 = d_0 + d_1$. It is immediate to see that

$$\delta_0^2 = d_1^2 = [\delta_0, d_1] = 0.$$

Moreover, $\delta_0 = d_0 + d_1$ is still a derivation. Let us prove the strong $\delta_0 d_1$ -lemma. We begin by showing $\ker(\delta_0) \cap \text{im}(d_1) \subseteq \text{im}(\delta_0 d_1)$. Fix an element $a \in A$ such that $\delta_0 a = 0$ and $a = d_1 b$. Then $d_0 a = \delta_0 a = 0$ so that by hypothesis there exists $c \in A$ such that $a = d_0 d_1 c = \delta_0 d_1 c$. By Lemma 1.4, we are only left with the proof of $\ker(d_1) \cap \text{im}(\delta_0) \subseteq \text{im}(\delta_0 d_1)$. To this aim, fix $a \in A$ such that $d_1 a = 0$ and $a = \delta_0 b$. Then define $a' = a - d_1 b$ and notice that

$$d_1 a' = 0 \quad \text{and} \quad a' = d_0 b.$$

Therefore there exists $c \in A$ such that $a' = d_0 d_1 c = \delta_0 d_1 c$. We have

$$a = \delta_0 d_1 c + \delta_1 b = d_1(b - \delta_0 c) \in \ker(\delta_0) \cap \text{im}(d_1) \subseteq \text{im}(\delta_0 d_1)$$

and the statement follows. \square

1.1. The Lie case. We briefly review some constructions in the Lie case. Fix a field \mathbb{K} of characteristic 0. Recall that a DG Lie algebra $(L, d, [-, -])$ is the data of a graded vector space $L = \bigoplus_{k \in \mathbb{Z}} L^k$ together with a graded bracket $[-, -]: L^i \times L^j \rightarrow L^{i+j}$ and a differential $d: L^k \rightarrow L^{k+1}$ satisfying $d^2 = 0$ and the following conditions

- (1) graded Leibniz rule: $d[a, b] = [da, b] + (-1)^{\deg(a)}[a, db]$,
- (2) graded skew-symmetry: $[a, b] + (-1)^{\deg(a)\deg(b)}[b, a] = 0$,
- (3) graded Jacobi identity: $[a, [b, c]] = [[a, b], c] + (-1)^{\deg(a)\deg(b)}[b, [a, c]]$,

for every homogeneous elements $a, b, c \in L$.

Notice that since $\text{char}(\mathbb{K}) = 0$ the above conditions also imply

- $[a, a] = 0$ for every homogeneous element a of even degree,
- Bianchi identity: $[a, [a, a]] = 0$ for every homogeneous element a of odd degree.

Example 1.11 (Dolbeault DG Lie algebra). Let $(E, \bar{\partial}_E)$ be a holomorphic vector bundle on a complex manifold X . Then

$$(A^{0,*}(End(E)), [\bar{\partial}_E, -], [-, -])$$

is the Dolbeault DG Lie algebra, where $A^{0,*}$ is the algebra of C^∞ -valued $(0, *)$ -forms, so that $A^{0,*}(End(E))$ are the $(0, *)$ -forms with values in the endomorphism bundle $End(E)$. Here

differential: $[\bar{\partial}_E, -]$ is the holomorphic structure on $End(E)$ induced by the fixed holomorphic structure on E ;

bracket: $[\alpha \otimes e, \beta \otimes f] = \alpha \wedge \beta [e, f]$, where $[e, f]$ is the usual commutator between holomorphic local sections of $End(E)$.

A morphism of DG Lie algebras is simply a morphism of DG vector spaces that preserves the brackets. We shall say that a morphism of DG Lie algebras is a *quasi-isomorphism* if the induced morphism in cohomology is a degreewise isomorphism.

Given a DG Lie algebra $(L, d, [-, -])$, for every $a, b \in L$ we have

$$da = db = 0 \Rightarrow d[a, b] = 0, \quad \text{and} \quad db = 0 \Rightarrow [da, b] = d[a, b],$$

so that the cohomology $H(L)$ inherits the bracket and is a DG Lie algebra (with trivial differential).

Definition 1.12. Let $L = (L, d, [-, -])$ be a DG Lie algebra. Then

- (1) A DG Lie algebra is called *formal* if it is quasi isomorphic to its cohomology as a DG Lie algebra.
- (2) A DG Lie algebra is called *homotopy abelian* if it is quasi isomorphic to an abelian DG Lie algebra.

The above definition plays a crucial role in several geometric application. As we will recall more precisely later on, the idea is that in characteristic 0 to any DG Lie algebra it is associated a deformation problem, and quasi isomorphic DG Lie algebras induce the same deformation problem. Hence a deformation problem corresponding to a formal (or homotopy abelian) DG Lie algebra enjoys particularly nice geometric properties, see e.g. Corollary 4.2.

Remark 1.13. Of course any associative DG algebra induces a DG Lie algebra, simply by defining the (graded) bracket as the (graded) commutator. On the other hand, as in the classical case, not every DG Lie algebra comes from an associative DG algebra. Therefore if an associative DG algebra is formal, then the induced DG Lie algebra is formal. The converse does not hold in general.

Notice that the Dolbeault DG Lie algebra of Example 1.11 has a bracket that comes from a natural associative product, so that we will often refer to it both as an associative DG algebra and as a DG Lie algebra.

One of the main tasks for many geometric applications to moduli spaces is to understand when the Dolbeault DG algebra is formal (either in the associative or in the Lie sense), see e.g. [AS18, BMM21, BZ18, KL07, Zha12]. In this paper we will provide sufficient conditions for the associative Dolbeault DG algebra to be formal.

Remark 1.14. It is easy to see that a DG Lie algebra L is homotopy abelian if and only if it is formal (in the Lie sense of Remark 1.13) and the bracket induced in cohomology is trivial. In fact, if L is homotopy abelian then up to quasi-isomorphisms we may assume that L has trivial bracket; then $L \rightarrow \frac{L}{\text{Im}(d_L)} \leftarrow H(L)$ is a pair of quasi-isomorphisms and A is formal. The converse is immediate.

One can define a DGMS *Lie algebra* as a DGMS vector space (L, d_0, d_1) with a Lie bracket $[-, -]$ such that both $(L, d_0, [-, -])$ and $(L, d_1, [-, -])$ are DG Lie algebras. Everything we said above can be rephrased verbatim for DGMS Lie algebras, with very little modifications. Our choice to work with associative algebras is motivated by the applications to study the local structure of moduli spaces of vector bundles.

1.2. Deformation functor associated to a DG Lie algebra. Let us briefly recall some well known facts about the approach to infinitesimal deformation theory via DG Lie algebras.

Definition 1.15. Let $(L, d, [-, -])$ be a DG Lie algebra, and fix an element $x \in L^1$.

- (1) x is a *classical* solution to the Maurer–Cartan equation if $d x + \frac{1}{2}[x, x] = 0$.
- (2) x is a *strong* solution to the Maurer–Cartan equation if

$$d x = 0 \quad \text{and} \quad [x, x] = 0.$$

Recall that to every homotopy class of DG Lie algebras L can be associated a deformation functor $\text{Def}_L : \text{Art}_{\mathbb{C}} \rightarrow \text{Sets}$ via Maurer–Cartan equation modulus gauge action, where $\text{Art}_{\mathbb{C}}$ denotes the category of local Artin \mathbb{C} -algebras with residue field \mathbb{C} , see e.g. [Man09, Man22].

The leading principle behind this approach states that every deformation problem defined by a deformation functor $\text{Def} : \text{Art}_{\mathbb{C}} \rightarrow \text{Sets}$ is controlled by a DG Lie algebra L ; i.e. $\text{Def} \cong \text{Def}_L$ (see e.g. [GM88]). A fundamental result is the homotopy invariance (cf. e.g. [Man22, Corollary 6.6.3]) which says that quasi isomorphic DG Lie algebras give rise to naturally isomorphic deformation functors. This clearly implies that the notion of formality is crucial in deformation theory: indeed if a DG Lie algebra L is formal then $\text{Def}_L \cong \text{Def}_{H(L)}$ so that one can reduce the study to the *strong* Maurer–Cartan solutions. These are going to characterise the autodual connections (cf. Lemma 3.1).

We will not recall in detail the technical gauge action defining the deformation functor associated to a DG Lie algebra L . Nevertheless, the non expert reader may think of it as a perturbation (depending on the differential of L) of the exponential adjoint action

$$\exp(L^0 \otimes \mathfrak{m}_B) \times \text{MC}(L^1 \otimes \mathfrak{m}_B) \rightarrow \text{MC}(L^1 \otimes \mathfrak{m}_B) \quad (e^{ad(a)}, b) \mapsto e^{ad(a)}(b) = \sum_{k \geq 0} \frac{(ad(a))^k}{k!}(b)$$

for any $B \in \text{Art}_{\mathbb{C}}$. Anyway, for a DG Lie algebra with trivial differential the gauge action is precisely given by such adjoint action. Hence for a formal DG Lie algebra the deformation functor is $\text{Def}_L \cong \text{Def}_{H(L)}$ and the latter is simply given by the quadratic cone modulo the exponential adjoint action

$$\text{Def}_{H(L)}(B) = \{b \in H^1(L) \otimes \mathfrak{m}_B \mid [b, b] = 0\} / \sim, \quad \text{for every } B \in \text{Art}_{\mathbb{C}}.$$

In the literature there exist several useful formality criteria for DG Lie algebras [Man15, BMM21].

Another useful way to concretely understand formality is the following. If a DG Lie algebra L is formal, then the maps

$$\text{Def}_L(\mathbb{C}[t]/(t^k)) \rightarrow \text{Def}_L(\mathbb{C}[t]/(t^2)) \quad \text{and} \quad \text{Def}_L(\mathbb{C}[t]/(t^3)) \rightarrow \text{Def}_L(\mathbb{C}[t]/(t^2))$$

have the same image for every $k \geq 3$. Essentially this means that there are only *quadratic obstructions* for “lifting” first order deformations to higher order ones. Moreover, if the bracket induced in the first cohomology $H^1(L) \cong \text{Def}_L(\mathbb{C}[t]/(t^2))$ is trivial then this obstructions vanish and the maps above are surjective; i.e. Def_L is unobstructed.

2. AUTODUAL AND HYPER-HOLOMORPHIC CONNECTIONS ON IHS MANIFOLDS

For background on the general theory of irreducible holomorphic symplectic manifolds we refer to [GHJ03].

Definition 2.1. A compact Kähler manifold X is called *irreducible holomorphic symplectic* if it is simply connected and $H^0(\Omega_X^2) = \mathbb{C} \cdot \sigma$, where σ is a holomorphic symplectic form.

By definition a symplectic form is non-degenerate, therefore σ induces a canonical isomorphism $\Theta_X \cong \Omega_X^1$, where Θ_X is the holomorphic tangent bundle of X . Moreover, the previous isomorphism being symplectic, we have that $\dim X = 2n$. The holomorphic volume form $\sigma^n \in H^0(\Omega_X^{2n})$ is also non-degenerate, so that $\Omega_X^{2n} = K_X$ is trivial. In particular, by Yau’s solution of Calabi’s conjecture ([Yau78]), any Kähler class is represented by the class associated to a Ricci-flat metric. More precisely, let us write $X = (M, I)$, where I is the complex structure, and let us fix a Kähler class ω on X . Then there exists a

Ricci-flat metric g on M such that $\omega(\cdot, \cdot) = g(I(\cdot), \cdot)$. Moreover, since (M, g, I) is also simply connected and irreducible symplectic, its holonomy group with respect to g is the symplectic group $\mathrm{Sp}(n)$ (recall that $2n = \dim X$). By the holonomy principle, there exist other two complex Kähler structures on (M, g) , denoted by J and K , that satisfies the usual quaternionic relations, i.e. $IJ = -JI = K$. The corresponding Kähler classes are $\omega = \omega_I$, ω_J and ω_K , and the symplectic form is $\sigma = \omega_J + i\omega_K$. The specification of the three complex Kähler structures I , J and K is called a *hyper-Kähler structure* on (M, g) . If $a, b, c \in \mathbb{R}$ are such that $a^2 + b^2 + c^2 = 1$, then the quasi-complex structure $L = aI + bJ + cK$ is integrable and Kähler. Viceversa, any complex Kähler structure L on (M, g) arising from the hyper-Kähler structure as before is called an *induced complex structure*. The set of induced complex structures is compactly encoded in the notion of the *twistor family* $\tau: \mathcal{X} \rightarrow \mathbb{P}^1$ (cf. [HKLR87, Section 3(F)]). The space \mathcal{X} is diffeomorphic to the product $M \times S^2$ (here S^2 is the differential sphere underlying \mathbb{P}^1) and has a natural integrable complex structure such that the projection τ is holomorphic. If $(a, b, c) \in S^2$, then $\tau^{-1}(a, b, c) = (M, aI + bJ + cK)$. Vice versa, the twistor family $\tau: \mathcal{X} \rightarrow \mathbb{P}^1$ recover the hyper-Kähler structure on M ([HKLR87, Theorem 3.3]). Notice that the other projection $q: \mathcal{X} \rightarrow X$ is not holomorphic.

In the following we fix once and for all a Kähler class ω on $X = (M, I)$. By the above discussion there is then a fixed hyper-Kähler structure on the associated (M, g) , which we shorten by writing $(X, \omega) = (M, g, I, J, K)$.

The three complex structures I , J and K act on the tangent bundle T_M and so also on the cotangent bundle T_M^* and all of its tensor products. In particular, there is a natural action of I , J and K on the cotangent algebra $\Lambda^* T_M^*$ induced by forcing the Leibniz rule. Since I , J and K satisfy the quaternionic relations, there is a well-defined action of the Lie algebra $\mathfrak{su}(2)$ on $\Lambda^* T_M^*$. Moreover, since the Lie group $\mathrm{SU}(2)$ is simply connected, the Lie algebra action integrates to an action of the Lie group. We resume here two important remarks due to Verbitsky.

Proposition 2.2 ([Ver96, Proposition 1.1, Proposition 1.2]). *Keep notations as above.*

- (1) *A k -form α is $\mathrm{SU}(2)$ -invariant if and only if $k = 2p$ and α is of type (p, p) with respect to any induced complex structure.*
- (2) *The action of $\mathrm{SU}(2)$ on $\Lambda^* T_M^*$ commutes with the laplacian operator. In particular it descends to an action on the cohomology $H^*(M, \mathbb{R})$.*

We recall here the main definitions and notations used in the rest of the paper. First of all, on the Kähler manifold $X = (M, g, I)$ with Kähler class ω we consider the Lefschetz operator

$$L_\omega: \Lambda^k T^*M \longrightarrow \Lambda^{k+2} T^*M$$

given by multiplying a cohomology class by the Kähler class ω , and its adjoint operator

$$\Lambda_\omega: \Lambda^k T^*M \longrightarrow \Lambda^{k-2} T^*M$$

defined via the metric g .

If d is the usual de Rham operator, then we denote by ∂ and $\bar{\partial}$ the Dolbeault operator associated to the choosen complex structure I .

If E is a complex vector bundle on $X = (M, g, I)$, then we denote by $\mathcal{A}^k(E)$ the sheaf of complex-valued C^∞ k -forms with coefficients in E , and by $A^k(E)$ the corresponding space of global sections. Furthermore, we denote by $\mathcal{A}_I^{p,q}(E)$ and $A_I^{p,q}(E)$ the sheaf and space of global section with respect to the complex structure I .

Recall that a *connection* on E is a \mathbb{C} -linear map

$$\nabla: A^0(E) \longrightarrow A^1(E)$$

satisfying the Leibniz rule

$$\nabla(fe) = dfe + f\nabla(e)$$

for every C^∞ function f and section e of E . Decomposing $A^1(E)$ in its $\pm i$ -eigenspaces with respect to I , we usually write $\nabla = \nabla^{1,0} + \nabla^{0,1}$ accordingly.

Extending ∇ to a degree 1 operator on the DG vector space $A^\bullet(E)$, one can easily check that ∇^2 is in fact $A^0(E)$ -linear and hence it defines an element $R = \nabla^2 \in A^2(\mathrm{End}(E))$, where $\mathrm{End}(E)$ is the endomorphism bundle of E .

Recall also that a *holomorphic structure* on E is a \mathbb{C} -linear map

$$\bar{\partial}_E: A^0(E) \longrightarrow A^{0,1}(E)$$

satisfying the analogous Leibniz rule and such that $\bar{\partial}_E^2 = 0$. (This definition of holomorphic structure on E is justified by the Koszul–Malgrange integrability theorem, [KM58].)

If $(E, \bar{\partial}_E)$ is a holomorphic vector bundle, a connection ∇ is compatible with the holomorphic structure if $\nabla^{0,1} = \bar{\partial}_E$. Finally recall that if E admits a hermitian metric, then the *Chern connection* on E is the unique connection that is compatible with both the holomorphic structure and the hermitian metric.

The Lefschetz operators L_ω and Λ_ω are extended to forms with coefficients in a complex vector bundle by acting with Id_E on the coefficient side.

The following definition is due to Kaledin and Verbitsky (see [KV98]).

Definition 2.3. A *Yang–Mills connection* ∇ on E is a connection such that its curvature ∇^2 is of type $(1, 1)$ and

$$\Lambda_\omega \nabla^2 = 0.$$

Remark 2.4. In general one can require that $\Lambda_\omega R = c \text{Id}$, and in this case one talks of Yang–Mills connections of charge c . Our choice to restrict to Yang–Mills connections of charge 0 will be clarified by Definition 2.8 and [Ver96, Lemma 2.1].

Remark 2.5. Let $(E, \bar{\partial}_E)$ be a hermitian holomorphic vector bundle, and let ∇ be a connection compatible with the holomorphic structure. If ∇^2 is of type $(1, 1)$ and $\Lambda_\omega \nabla^2 = c \text{Id}$, then c must be a multiple of $\mu(E) = \deg_\omega(E)/\text{rk}(E)$. In particular, holomorphic vector bundles having a hermitian Yang–Mills connection (compatible with the holomorphic structure) must have first Chern class of degree 0.

Remark 2.6. Notice that in the literature one usually talks about Yang–Mills hermitian metrics on a holomorphic vector bundle E , and the associated Chern connection is referred to as the Yang–Mills connection. On the other hand, the connections in Definition 2.3 are not necessary hermitian (nor the bundle is assumed holomorphic a priori). In [KV98] these connections are called *non-hermitian Yang–Mills*, but we find the name a bit misleading, since hermitian connections are in fact of this type. When referring to a Yang–Mills connection that is the Chern connection of a Yang–Mills metric, we simply call it a *hermitian Yang–Mills connection*.

Remark 2.7. If ∇ is a Yang–Mills connection on E , then $\nabla^{0,1}$ is a holomorphic structure on E and ∇ is tautologically compatible with it.

An historical-interesting set of examples of Yang–Mills connections is provided by flat connections, that is by those connections ∇ such that $\nabla^2 = 0$. Notice that such connections are in 1–1 correspondence with local systems on X .

As we will shortly see, the next definition provides a set of examples of Yang–Mills connections that is slighter bigger than flat connections.

Definition 2.8 ([Ver96, KV98]). Suppose that $X = (M, I)$ is an irreducible holomorphic symplectic manifold and (M, g, I, J, K) is the hyper-Kähler structure on X associated to a Kähler class ω .

- (1) Let E be a complex vector bundle on X and ∇ a connection on E . Then ∇ is called *autodual* if the curvature $\nabla^2 \in A^2(\text{End}(E))$ is $\text{SU}(2)$ -invariant.
- (2) Let $(E, \bar{\partial}_E)$ be a holomorphic vector bundle. A hermitian metric h on E is called *hyper-holomorphic* if the Chern connection is autodual. In this case, we call the Chern connection hyper-holomorphic.

Remark 2.9. The definition of autodual connection first appeared in [KV98], while the definition of hyper-holomorphic connection first appeared in [Ver96]. The main difference between the two is the fact that the latter is hermitian, while the former is not in general. Our formality result (see Theorem 4.3) relies heavily on the metric aspects of the connection; on the other hand, our discussion on deformations in Section 3 is not bounded to the metric and relates the existence of a hyper-holomorphic connection to the existence of (many) autodual connections.

Remark 2.10. We want to stress that the notion of autoduality is associated to the choice of a hyper-Kähler structure, that is to the choice of a Kähler class ω , and so one should talk of ω -autoduality (and ω -hyper-holomorphicity). Nevertheless, we will always work with a fixed Kähler structure, therefore we can safely drop the reference to ω from the notation.

Example 2.11. The first non-trivial example of vector bundle having a hyper-holomorphic connection is the holomorphic tangent bundle Θ_X . In fact, let (M, g, I, J, K) be the hyper-Kähler structure associated

to the fixed Kähler class ω on X . Then Θ_X comes with a natural hermitian form induced by g . If ∇_X is the associated Chern connection, then we need to show that ∇_X^2 is $SU(2)$ -invariant. By Proposition 2.2, this is equivalent to show that ∇_X^2 is of type $(1, 1)$ with respect to any induced complex structure L . On the other hand, the holomorphic tangent bundle $\Theta_{(M,g,L)}$ has a hermitian structure induced by g as well and its curvature (which coincides with ∇_X^2) is of type $(1, 1)$ with respect to L .

Lemma 2.12 ([KV98, Proposition 3.9]). *The following holds.*

- (1) *An autodual connection is a Yang–Mills connection.*
- (2) *A hyper-holomorphic hermitian metric is a Yang–Mills hermitian metric.*

Proof. First of all, by Proposition 2.2 we have that the curvature ∇^2 of an autodual connection ∇ is of type $(1, 1)$ with respect to any induced complex structure, in particular for I . Furthermore, by [Ver96, Lemma 2.1], any $SU(2)$ -invariant 2-forms α satisfies $\Lambda_\omega \alpha = 0$.

The last statement follows similarly (see [Ver96, Theorem 2.3]). \square

By Chern–Simon theory, the Chern classes of a holomorphic vector bundle E are computed in terms of the curvature of a connection ∇ on E . In particular, if ∇ is autodual, then $c_k(E)$ is $SU(2)$ -invariant for every k . The following result is a partial converse.

Proposition 2.13 ([Ver96]). *Let X be an irreducible holomorphic symplectic manifold with fixed Kähler form ω , and let $(E, \bar{\partial}_E)$ be a holomorphic vector bundle on E that is indecomposable. If there exists a hyper-holomorphic connection on E , then E is slope stable.*

Vice versa, if E is slope stable and $c_1(E)$ and $c_2(E)$ are $SU(2)$ -invariant, then there exists a connection on E that is hyper-holomorphic.

Proof. By the Donaldson–Uhlenbeck–Yau theorem, an indecomposable holomorphic vector bundle is slope stable if and only if it admits a unique Yang–Mills metric, and so a unique Chern connection of Yang–Mills type. Since hyper-holomorphic connections are Yang–Mills, the first statement follows.

The last statement follows from [Ver96, Theorem 2.5], where it is proved that, under the hypothesis of $SU(2)$ -invariance of the first two Chern classes, the Chern connection produced by the Donaldson–Uhlenbeck–Yau theorem is hyper-holomorphic. \square

We conclude this section with the following characterisation of autodual connections. Recall that if X is an irreducible holomorphic symplectic manifold and ω a Kähler class, then there is a twistor family $\tau: \mathcal{X} \rightarrow \mathbb{P}^1$ associated to the hyper-Kähler structure corresponding to ω . Let $q: \mathcal{X} \rightarrow X$ be the non-holomorphic projection.

Lemma 2.14 ([KV98, Lemma 5.1]). *Let E be a holomorphic vector bundle and ∇ an autodual connection on it. Then the connection $q^*\nabla$ on the vector bundle q^*E has curvature of type $(1, 1)$. In particular, $q^*\nabla^{0,1}$ is a holomorphic structure on q^*E .*

In other words, the lemma is saying that holomorphic vector bundles on X admitting an autodual connection are those for which the pullback q^*E is still holomorphic. In particular q^*E can be thought of as a family of holomorphic vector bundles on the twistor family, so that autodual vector bundles are those that “deform” along the twistor line.

3. THE QUATERNIONIC DOLBEAULT COMPLEX

3.1. A motivating example: flat connections. We start with the following examples which we hope will serve as a motivation for what we will say next. For a more detailed account we refer to [GM88].

Let us consider a compact Kähler manifold X and a complex vector bundle E endowed with a flat connection ∇ . Decomposing ∇ in its $(1, 0)$ and $(0, 1)$ parts, according to the complex structure of X , we see that the flatness condition can be written as

$$(\nabla^{0,1})^2 = 0, \quad (\nabla^{1,0})^2 = 0 \quad \text{and} \quad [\nabla^{0,1}, \nabla^{1,0}] = 0.$$

In particular, if we think of $\nabla^{0,1}$ as a differential on the graded vector space $A^*(E)$, i.e. it is a holomorphic structure on E , then the last two conditions can be compactly stated by saying that $\nabla^{1,0}$ is a strong solution (see Definition 1.15) to the Maurer–Cartan equation in the DG Lie algebra

$$(\text{End}_{\mathbb{C}}^*(A^*(E)), d = [\nabla^{0,1}, -], [-, -]).$$

Moreover, since ∇ is flat, there always exists a hermitian metric on E such that ∇ is the Chern connection of this metric. Using this observation, Goldman and Millson notice that the strong $\nabla^{0,1} \nabla^{1,0}$ -lemma holds (see [GM88, Proposition 7.3]). The proof of this result is not explicitly stated in loc. cit. but can be easily filled: using the parallel hermitian metric, one can write down the usual Nakano–Kodaira identities and the Hodge decomposition, so that the claim follows as in the classical case.

From our point of view, the triple

$$(A^*(E), \nabla^{0,1}, \nabla^{1,0})$$

is an example of a DGMS vector space, cf. Definition 1.1. One of the main results of [GM88] is the statement that the infinitesimal deformations of ∇ are controlled by the DG Lie algebra

$$(A^*(\text{End}(E)), [\nabla, -], [-, -]),$$

where $[-, -]$ as usual denote the graded commutator of the natural associative product (see [GM88, Proposition 6.6]). Now, by Proposition 1.10 and Theorem 1.8, it follows then that the associative DG algebra $(A^*(\text{End}(E)), [\nabla, -])$ is formal (in particular it is also Lie formal) and then the obstructions to deform ∇ are quadratic (see [GM88, Theorem 1] and its proof in [GM88, Section 7]).

3.2. Autodual connections and quaternionic Dolbeault complex. Recall that the hyper-Kähler structure on X transfers to a $\text{SU}(2)$ -action on the de Rham complex $A^*(E)$. In particular we see $A^*(E)$ as a complex $\text{SU}(2)$ -representation, which is equivalent to being a $\mathfrak{sl}(2)$ -representation; indeed $\mathfrak{su}(2)_{\mathbb{C}} = \mathfrak{sl}(2)$ and that $\text{SU}(2)$ is simply connected, so that the set of $\text{SU}(2)$ -representations is in bijection with the set of $\mathfrak{su}(2)$ -representations. We stress the fact that the action of $\text{SU}(2)$ on $A^*(E)$ is trivial on E .

The action of $\mathfrak{sl}(2)$ on $A^*(E)$ is easy to write down locally in terms of the actions of the generators corresponding to the three Kähler structures I, J and K given by the hyper-Kähler structure. In particular any irreducible subrepresentation of $A^k(E)$ has weight smaller or equal to k and any irreducible subrepresentation of $A^{0,k}(E)$ has weight k .

One can define an ideal $\mathfrak{J} = \bigoplus_k \mathfrak{J}^k$, where \mathfrak{J}^k is generated by the irreducible subrepresentations of $A^k(E)$ of weight strictly smaller than k . We refer to [Ver07] for the details on the definition of \mathfrak{J} and the fact that it is well-defined and well-behaved.

We shall denote the quotient by

$$A_+^*(E) := \frac{A^*(E)}{\mathfrak{J}}.$$

Notice that the Dolbeault complex $A^{0,*}(E)$ canonically embeds as a graded vector space in $A_+^*(E)$, since the quotient inherits the bi-graded structure $A_+^k(E) = \bigoplus_{p+q=k} A_+^{p,q}(E)$ and we have already remarked that any subrepresentation of $A^{0,k}(E)$ has weight exactly k .

Any connection ∇ on E induces a degree 1 operator ∇_+ on the graded algebra $A_+^*(E)$.

Lemma 3.1. *∇ is autodual if and only if ∇_+ is flat, i.e. $\nabla_+^2 = 0$.*

Proof. First of all, by Proposition 2.2, if ∇ is autodual, then the curvature ∇^2 is $\text{SU}(2)$ -invariant. In particular, it defines a 1-dimensional subrepresentation of weight 0 and hence it must belong to the ideal \mathfrak{J} . It follows that $\nabla_+^2 = 0$.

For the converse, notice that ∇^2 is a 2-form, hence the representation generated by it must have weight either 0 or 2. Since $\nabla_+^2 = 0$, it cannot have weight 2 and therefore it must be $\text{SU}(2)$ -invariant. \square

Let us define $D^*(E) = \bigoplus_k D^k(E)$, where

$$D^k(E) = \text{Sym}^k V \otimes_{\mathbb{C}} A^{0,k}(E),$$

where V is the irreducible 2-dimensional $\mathfrak{sl}(2)$ -representation. As a vector space, $D^k(E)$ is nothing but the direct sum of $k+1$ copies of $A^{0,k}(E)$. Moreover, the choice of a basis $\{x, y\}$ for V provides a bi-grading of $D^*(E)$

$$D^k(E) = \bigoplus_{p+q=k} D^{p,q}(E) = \bigoplus_{p+q=k} x^p y^q A^{0,p+q}(E),$$

where we are thinking of x and y as formal central variables.

Recall that if L is any induced complex structure on (M, g, I, J, K) , then L acts on A^* in a multiplicative way, i.e. $L(\alpha \wedge \beta) = L(\alpha) \wedge L(\beta)$. Our next result is due to Verbitsky and relates the two constructions introduced above.

Lemma 3.2. *There is a $SU(2)$ -equivariant isomorphism of bi-graded vector spaces*

$$\varphi: D^{*,*}(E) \longrightarrow A_+^{*,*}(E).$$

Proof. First notice that $A_+^k(E) = \bigoplus_{p+q=k} A_+^{p,q}(E)$, and by [Ver07, Proposition 2.7] we have $A_+^{p,q} \cong A^{0,p+q}$, so

that in particular $A_+^k(E)$ is isomorphic to $k+1$ copies of $A^{0,p+q}(E)$ as a vector space. Now, fix a basis $\{x, y\}$ of the irreducible 2-dimensional $\mathfrak{sl}(2)$ -representation V , and consider the isomorphism

$$\varphi^1: D^1(E) = V \otimes A^{0,1}(E) \longrightarrow A_+^1(E)$$

defined by

$$x \otimes (\eta \otimes e) \mapsto J(\eta) \otimes e \quad \text{and} \quad y \otimes \eta \mapsto \eta \otimes e.$$

Notice that φ^1 extends, thanks to the algebra structure and the multiplicativity action of $SU(2)$, to a map

$$\varphi^k: D^k(E) = \text{Sym}^k(V) \otimes A^{0,k}(E) \longrightarrow A_+^k(E),$$

hence providing a morphism of graded algebras $\varphi: D^*(E) \longrightarrow A_+^*(E)$, which is the required $SU(2)$ -equivariant isomorphism, cf. [Ver07, Proposition 2.9]. The inverse φ^{-1} is defined by

$$[\alpha \wedge \beta] \otimes e \mapsto x^{\deg(\alpha)} y^{\deg(\beta)} (J(\alpha) \wedge \beta) \otimes e,$$

for every homogeneous class $[\alpha \wedge \beta] \otimes e \in A_+^{\deg(\alpha), \deg(\beta)}(E)$. Here we are again tacitely using [Ver07, Proposition 2.7] to think the class of a (p, q) -form in $A_+^*(E)$ as a $(0, p+q)$ -form. \square

Remark 3.3. When E is endowed with an autodual connection, the explicit isomorphism φ of Lemma 3.2 together with Lemma 3.1 allow us to induce two differentials on $D^{*,*}(E)$. In fact for every $p, q \geq 0$:

- (1) $\nabla_+^{1,0}$ is naturally taken to the differential operator

$$x \nabla_J^{0,1}: x^p y^q A_I^{0,p+q}(E) \xrightarrow{J \otimes \text{id}} x^p y^q A_I^{p+q,0}(E) \xrightarrow{x \nabla^{1,0}} x^{p+1} y^q A_I^{p+q+1,0}(E) \xrightarrow{J^{-1} \otimes \text{id}} x^{p+1} y^q A_I^{0,p+q+1}(E)$$

so that

$$x \nabla_J^{0,1} := (J^{-1} \otimes \text{id}) \circ (x \nabla^{1,0}) \circ (J \otimes \text{id}) = \varphi^{-1} \circ \nabla_+^{1,0} \circ \varphi,$$

- (2) $\nabla_+^{1,0}$ is naturally taken to the differential operator

$$y \nabla^{0,1}: x^p y^q p A^{0,p+q}(E) \longrightarrow x^p y^{q+1} A^{0,p+q+1}(E)$$

so that

$$y \nabla^{0,1} = \varphi^{-1} \circ \nabla_+^{0,1} \circ \varphi.$$

Notice that by Lemma 3.1, assuming the connection to be autodual is equivalent to require that $D^{*,*}(E)$ is a double complex, i.e.

$$(\nabla^{0,1})^2 \equiv 0 \quad (\nabla_J^{0,1})^2 \equiv 0 \quad \nabla^{0,1} \nabla_J^{0,1} + \nabla_J^{0,1} \nabla^{0,1} \equiv 0.$$

Definition 3.4 (quaternionic Dolbeault complex). Let (M, g, I, J, K) be a hyper-Kähler manifold. Let E be a complex vector bundle on $X = (M, I)$ equipped with an autodual connection $\nabla = \nabla^{1,0} + \nabla^{0,1}$. We shall call $(D^*(E), x \nabla_J^{0,1} + y \nabla^{0,1})$ the *quaternionic Dolbeault complex*.

Remark 3.5. Notice that the quaternionic Dolbeault complex of Definition 3.4 can be also seen as the total complex of the double complex

$$D^{*,*}(E) = \left(\bigoplus_{k \in \mathbb{N}} \bigoplus_{p+q=k} D^{p,q}(E), x \nabla_J^{0,1}, y \nabla^{0,1} \right).$$

For reference purposes we explicitly state the next result, which essentially says that the isomorphism of Lemma 3.2 respects the double complex structure.

Proposition 3.6. *Suppose that ∇ is an autodual connection on E . There is a $SU(2)$ -equivariant isomorphism of double complexes*

$$\varphi: (D^{*,*}(E), x \nabla_J^{0,1}, y \nabla^{0,1}) \longrightarrow (A_+^{*,*}(E), \nabla_+^{0,1}, \nabla_+^{1,0}).$$

Proof. Immediate from Lemma 3.1, Lemma 3.2 and Remark 3.3. \square

Proposition 3.7. *If a connection ∇ on E is autodual then*

- (1) $\nabla^{0,1}$ is a holomorphic structure, and
 (2) $\nabla_J^{0,1} = (J^{-1} \otimes \text{id}) \circ \nabla^{1,0} \circ (J \otimes \text{id})$ is a strong solution of the Maurer–Cartan equation in the DG Lie algebra $(\text{End}_{\mathbb{C}}^*(A^{0,*}(E)), d = [\nabla^{0,1}, -], [-, -])$.

Proof. The statements are equivalent to the relations

$$(\nabla^{0,1})^2 \equiv 0 \quad (\nabla_J^{0,1})^2 \equiv 0 \quad \nabla^{0,1} \nabla_J^{0,1} + \nabla_J^{0,1} \nabla^{0,1} \equiv 0$$

already outlined in Remark 3.3. \square

Remark 3.8. Notice that the proposition above does not say that a solution of the Maurer–Cartan equation in $(\text{End}_{\mathbb{C}}^*(A^{0,*}(E)), [\nabla^{0,1}, -], [-, -])$ gives rise to an autodual connection. In fact, given such a solution δ , this is true if and only if the operator $\nabla_{\delta} := J \circ \delta \circ J^{-1} + \nabla^{0,1}$ is a connection on E .

When moreover the connection ∇ is hyper-holomorphic, i.e. it is the Chern connection of a hermitian metric, we have the further result due to Verbitsky. Similarly to before, let us define the differential $\nabla_J^{0,1}$ on $A^{0,*}(E)$ as the composition

$$\nabla_J^{0,1} = (J \otimes \text{id})^{-1} \circ \nabla^{1,0} \circ (J \otimes \text{id}).$$

Lemma 3.9 ([Ver96, Theorem 4.4]). *Assume that the connection ∇ is hyper-holomorphic. Then the strong $\nabla^{0,1} \nabla_J^{0,1}$ -lemma holds on $A^{0,*}(E)$.*

In particular $(A^{0,}(E), \nabla^{0,1}, \nabla_J^{0,1})$ is a DGMS vector space.*

Proof. In [Ver96, Theorem 4.4], Verbitsky proves a real version of the $\nabla^{0,1} \nabla_J^{0,1}$ -lemma, but the proof holds verbatim in this case.

More precisely, Verbitsky proves analogs of the classical Hodge–Nakano–Kodaira identities, so that the proof is symmetric in $\nabla^{0,1}$ and $\nabla_J^{0,1}$, i.e. the $\nabla_J^{0,1} \nabla^{0,1}$ -lemma holds as well. Therefore, the claim follows by Lemma 1.4. \square

3.3. Properties of the quaternionic Dolbeault complex. Let E be a complex vector bundle on an irreducible holomorphic symplectic manifold X and suppose that $\nabla = \nabla^{1,0} + \nabla^{0,1}$ is a hyper-holomorphic connection on E . In the rest of this section we will need the DGMS structure on the quaternionic Dolbeault complex, for this reason we restrict to hyper-holomorphic connections.

In this subsection we work with the quaternionic Dolbeault complex, see Definition 3.4. Denote by V the irreducible 2-dimensional $\mathfrak{sl}(2)$ -representation, and fix a basis $\{x, y\}$ of V . Then the quaternionic Dolbeault complex can be written as

$$(D^*(E), x\nabla_J^{0,1} + y\nabla^{0,1})$$

where $D^k(E) = A^{0,k}(E) \otimes_{\mathbb{C}} \mathbb{C}[x, y]_k$. Here $\mathbb{C}[x, y]_k \cong \text{Sym}^k(V)$ denotes the set of homogeneous polynomials of degree k in the formal central variables x and y .

Lemma 3.10. *Let X be an irreducible holomorphic symplectic manifold. Consider a complex vector bundle E on X , endowed with an hyper-holomorphic connection $\nabla = \nabla^{1,0} + \nabla^{0,1}$. Then*

$$H^k(D^*(E)) \cong H_{y\nabla^{0,1}}^k(A^{0,*}(E)) \otimes_{\mathbb{C}} \mathbb{C}[x, y]_k \cong H_{x\nabla_J^{0,1}}^k(A^{0,*}(E)) \otimes_{\mathbb{C}} \mathbb{C}[x, y]_k.$$

Proof. The proof is a standard spectral sequence argument. In fact, by Remark 3.3 the quaternionic Dolbeault complex is the total complex associated to the double complex

$$(D^{*,*}(E), x\nabla_J^{0,1}, y\nabla^{0,1}).$$

Taking cohomology with respect to the vertical differential $y\nabla^{0,1}$, the first page E_1 reads like

$$E_1^{p,q} = \begin{cases} x^p y^q H_{\nabla^{0,1}}^{p+q}(A^{0,*}(E)) & \text{if } q \geq 1 \\ x^p \ker(\nabla^{0,1}: A^{0,p} \rightarrow A^{0,p+1}) & \text{if } q = 0 \end{cases}$$

while the induced horizontal differentials vanish by Lemma 1.3 as soon as $q \geq 1$. Therefore the second page E_2 will be

$$E_2^{p,q} = \begin{cases} x^p y^q H_{\nabla^{0,1}}^{p+q}(A^{0,*}(E)) & \text{if } q \geq 1 \\ x^p H_{\nabla_J^{0,1}}^p(\ker(\nabla^{0,1}: A^{0,*} \rightarrow A^{0,*+1})) & \text{if } q = 0. \end{cases}$$

Now we want to show that

$$E_2^{p,0} = H_{\nabla_j^{0,1}}^p(\ker(\nabla_j^{0,1}: A^{0,*} \rightarrow A^{0,*+1})) \cong H_{\nabla_j^{0,1}}^p(A^{0,*}(E)) \cong H_{\nabla_j^{0,1}}^p(A^{0,*}(E)).$$

The last isomorphism immediately follows by Remark 1.9. Let us show the former. Suppose that a class $[a] \in H_{\nabla_j^{0,1}}^p(\ker(\nabla_j^{0,1}))$ is trivial, then $a = \nabla_j^{0,1} b$ for some $b \in A^{0,p-1}$ such that $\nabla_j^{0,1} b = 0$. In particular, the map

$$g: H_{\nabla_j^{0,1}}^p(\ker(\nabla_j^{0,1}: A^{0,*} \rightarrow A^{0,*+1})) \longrightarrow H_{\nabla_j^{0,1}}^p(A^{0,*}(E)) \quad [a] \mapsto [a]$$

is well-defined. To show the surjectivity of g , consider a class $[a] \in H_{\nabla_j^{0,1}}^p(A^{0,*}(E))$ and notice that $\nabla_j^{0,1} a \in \ker(\nabla_j^{0,1}) \cap \text{im}(\nabla_j^{0,1})$. Hence there exists an element $b \in A^{0,p-1}$ such that $\nabla_j^{0,1} a = \nabla_j^{0,1} \nabla_j^{0,1} b$, so that it is sufficient to consider $a' = a - \nabla_j^{0,1} b$ which satisfies

$$[a'] \in H_{\nabla_j^{0,1}}^p(\ker(\nabla_j^{0,1}: A^{0,*} \rightarrow A^{0,*+1})) \text{ and } [a'] = [a] \in H_{\nabla_j^{0,1}}^p(A^{0,*}(E)).$$

For the injectivity, let us consider an element $a \in A^{0,p}(E)$ such that $\nabla_j^{0,1} a = 0$ and $g[a] = 0$. This is equivalent to say that

$$\begin{cases} \nabla_j^{0,1} a = 0 \\ \nabla_j^{0,1} a = 0 \\ \exists b \in A^{0,p-1}(E) \text{ such that } a = \nabla_j^{0,1} b \end{cases}$$

so that $\nabla_j^{0,1} b \in \ker(\nabla_j^{0,1}) \cap \text{im}(\nabla_j^{0,1})$. Therefore there exists $c \in A^{0,p-2}(E)$ such that $\nabla_j^{0,1} b = \nabla_j^{0,1} \nabla_j^{0,1} c$. In particular we may define $b' = b - \nabla_j^{0,1} c$ so that

$$[a] = [\nabla_j^{0,1} b'] \in H_{\nabla_j^{0,1}}^p(\ker(\nabla_j^{0,1}: A^{0,*} \rightarrow A^{0,*+1}))$$

and the injectivity of g follows.

By the strong $\nabla_j^{0,1}$ -lemma, the spectral sequence degenerates at the second page E_2 , so that the k -th cohomology of the total complex is given by the direct sum

$$H_{x\nabla_j^{0,1} + y\nabla_j^{0,1}}^k(D^*(E)) = \bigoplus_{p+q=k} x^p y^q H_{y\nabla_j^{0,1}}^k(D^*(E)).$$

The same argument taking the first page with respect to the horizontal differential $x\nabla_j^{0,1}$ provides the latter isomorphism in the statement. \square

Corollary 3.11. *The triple $(D^{*,*}(E), y\nabla_j^{0,1}, x\nabla_j^{0,1})$ is not a DGMS vector space.*

Proof. If it were a DGMS vector space, then by Lemma 1.3 the associated spectral sequence would degenerate at E_1 , but we have seen in Lemma 3.10 that it degenerates at E_2 . \square

Recall that on the Dolbeault algebra $A^{0,*}(End(E))$ there is an associative product, defined as

$$(3.1) \quad (\alpha \otimes f) \cdot (\beta \otimes g) = \alpha \wedge \beta \otimes (f \circ g)$$

for every $\alpha, \beta \in A^{0,*}$ and every sections f and g of $End(E)$. In particular

$$(A^{0,*}(End(E)), \cdot, [\nabla_j^{0,1}, -])$$

is an associative DG algebra. This of course extends to an associative product on the quaternionic Dolbeault complex $D^*(End(E))$. It is therefore natural to ask if this product endows the quaternionic Dolbeault complex with a structure of associative DG algebra, i.e. if the differential of $D^*(End(E))$ behaves as a derivation.

Remark 3.12. Given a holomorphic vector bundle E and a connection ∇ on it, the connection $\tilde{\nabla}$ on $End(E)$ induced by E is $\tilde{\nabla} = [\nabla, -]$. More explicitly, for any section h of $End(E)$ we have

$$(\tilde{\nabla} h)(s) = \nabla h(s) - h(\nabla s).$$

We claim that $\tilde{\nabla}$ behaves like a derivation with respect to the associative product on $A^{0,*}(End(E))$.

In fact, let us take two sections f and g of $End(E)$ and a vector field ξ (i.e. ξ is a section of the complexified tangent bundle T_M). Then

$$\bullet \quad \tilde{\nabla}_\xi(f \circ g)(s) = \nabla_\xi((f \circ g)(s)) - (f \circ g)(\nabla_\xi(s))$$

- $\tilde{\nabla}_\xi(f)(g(s)) = \nabla_\xi((f \circ g)(s)) - f(\nabla_\xi(g(s)))$
- $\tilde{\nabla}_\xi(g)(s) = \nabla_\xi(g(s)) - g(\nabla_\xi(s))$.

and by the arbitrariness of s and ξ we deduce $\tilde{\nabla}(f \circ g) = \tilde{\nabla}(f)g + f\tilde{\nabla}(g)$.

Proposition 3.13. *Both differentials $[\nabla^{0,1}, -]$ and $[\nabla_J^{0,1}, -]$ act as derivations with respect to the associative product on $A^{0,*}(End(E))$. In particular, all of the following are associative DG algebras:*

$$(A^{0,*}(End(E)), \cdot, [\nabla^{0,1}, -]), \quad (A^{0,*}(End(E)), \cdot, [\nabla_J^{0,1}, -]), \\ (D^{0,*}(End(E)), \cdot, [x\nabla_J^{0,1} + y\nabla^{0,1}, -]).$$

Proof. It is sufficient to show that both differentials $[\nabla^{0,1}, -]$ and $[\nabla_J^{0,1}, -]$ act as derivations with respect to the product on $A^{0,*}(End(E))$. This is quite classical and can be checked directly for $[\nabla^{0,1}, -]$, so that the only non-trivial case is for $[\nabla_J^{0,1}, -]$. Recall that by Remark 3.12, $\tilde{\nabla}$ acts as a derivation and then so does

$$\tilde{\nabla}^{1,0} = \tilde{\nabla} - \tilde{\nabla}^{0,1} = \tilde{\nabla} - [\nabla^{0,1}, -].$$

Now, since J acts multiplicatively on $A^{0,*}$, we obtain that the conjugation

$$\tilde{\nabla}_J^{0,1} = (J^{-1} \otimes \text{id}) \circ [\nabla^{1,0}, -] \circ (J \otimes \text{id})$$

is a derivation with respect to the product of $A^{0,*}(End(E))$. Therefore, to conclude it is enough to show that $\tilde{\nabla}_J^{0,1} = [\nabla_J^{0,1}, -]$, which is straightforward. \square

Notation. Let E be a complex vector bundle. If a Chern connection ∇ on E induces a hyper-holomorphic connection $[\nabla, -]$ on $End(E)$, then ∇ is called *projectively hyper-holomorphic*.

Theorem 3.14. *Consider a complex vector bundle E endowed with a projectively hyper-holomorphic connection ∇ . Then $(A^{0,*}(End(E)), \nabla^{0,1})$ is a formal associative algebra.*

Proof. By Lemma 3.9 and Proposition 3.13, the triple $(A^{0,*}(End(E)), \nabla^{0,1}, \nabla_J^{0,1})$ is an associative DGMS algebra. Therefore the claim follows from Theorem 1.8. \square

As we already remarked in Corollary 3.11, the quaternionic Dolbeault algebra is not a DGMS algebra. Nevertheless, following the analogy with the case of flat connections studied in [GM88], it is natural to ask whether it is formal or not (we will clarify better this analogy in Section 5).

Question 3.15. *Is $(D^*(End(E)), [x\nabla_J^{0,1} + y\nabla^{0,1}, -])$ a formal associative algebra?*

We conclude by highlighting an interesting relation between the classical Dolbeault DG Lie algebra $(A^{0,*}(End(E)), \nabla^{0,1})$ and the quaternionic Dolbeault DG Lie algebra $(D^*(End(E)), [x\nabla_J^{0,1} + y\nabla^{0,1}, -])$.

Proposition 3.16. *The classical Dolbeault DG Lie algebra is homotopy abelian if and only if quaternionic Dolbeault DG Lie algebra is homotopy abelian.*

Proof. First suppose $(D^*(End(E)), [x\nabla_J^{0,1} + y\nabla^{0,1}, -])$ is homotopy abelian. There is an injective morphism

$$g: (A^{0,*}(End(E)), \nabla^{0,1}) \longrightarrow (D^*(End(E)), [x\nabla_J^{0,1} + y\nabla^{0,1}, -])$$

given by the multiplication with the central variable y . This map is injective in cohomology by Lemma 1.3. Therefore the conclusion follows by the standard homotopy abelianity transfer (see e.g. [KKP08, IM13, Man15]).

For the converse, define the *extended quaternionic Dolbeault complex* $(eD^*(End(E)), [x\nabla_J^{0,1} + y\nabla^{0,1}, -])$, as

$$eD^k(End(E)) = \bigoplus_{p+q=k} x^p y^q A^{0,k}(End(E))$$

where $p, q \in \mathbb{Z}$ can be negative. There is a natural injective morphism of associative algebras

$$f: (D^*(End(E)), [x\nabla_J^{0,1} + y\nabla^{0,1}, -]) \longrightarrow (eD^*(End(E)), [x\nabla_J^{0,1} + y\nabla^{0,1}, -]).$$

Since $(eD^{*,*}(End(E)), [y\nabla^{0,1}, -], [x\nabla_J^{0,1}, -])$ is a DGMS algebra, it is easy to check that

$$H_{[x\nabla_J^{0,1} + y\nabla^{0,1}, -]}^k(eD^{*,*}(End(E))) = \bigoplus_{p+q=k} \text{Ext}^k(E, E)$$

(cf. Lemma 1.3). In particular, f is injective in cohomology.

Now, if $(A^{0,*}(End(E)), \nabla^{0,1})$ is homotopy abelian, it is easy to see that also $eD^*(End(E))$ is homotopy abelian. In fact it is formal (Proposition 1.10 and Theorem 1.8) and the associative product is commutative in cohomology, since it is induced by the commutative product on the cohomology of $A^{0,*}(End(E))$. \square

Remark 3.17. Concerning Proposition 3.16, it is important to point out that the strong $y \nabla^{0,1} x \nabla_j^{0,1}$ -lemma fails for the quaternionic Dolbeault bi-complex exactly at the hedge of the bi-complex, i.e. either at $D^{0,*}(End(E))$ or at $D^{*,0}(End(E))$. This is due to the fact that the indices are supposed to be positive. We can then fix this defect by considering the *extended quaternionic Dolbeault complex* introduced in the proof above. $(eD^*(End(E)), [x \nabla_j^{0,1} + y \nabla^{0,1}, -])$, where

$$eD^k(End(E)) = \bigoplus_{p+q=k} x^p y^q A^{0,k}(End(E)).$$

Notice that here $p, q \in \mathbb{Z}$ can be negative.

It is easy to check now that the strong $y \nabla^{0,1} x \nabla_j^{0,1}$ -lemma holds on $(eD^{*,*}(End(E)), [y \nabla^{0,1}, -], [x \nabla_j^{0,1}, -])$ (just use Lemma 3.9 and the fact that the variable x and y are central). In particular, the extended quaternionic Dolbeault complex is a formal associative algebra by Proposition 1.10 and Theorem 1.8.

3.4. Deformation functor of the quaternionic Dolbeault DG Lie algebra. To state the next result, let us recall that every DG Lie algebra $(L, d, [-, -])$ induces a deformation functor $\text{Def}_L : \text{Art}_{\mathbb{C}} \rightarrow \text{Sets}$ defined by

$$\text{Def}_L(B) = \frac{\text{MC}(L \otimes_{\mathbb{C}} \mathfrak{m}_B)}{\sim},$$

where \mathfrak{m}_B is the maximal ideal of $B \in \text{Art}_{\mathbb{C}}$, see § 1.2. We shall adopt the standard notation $\mathbb{C}[\epsilon] = \mathbb{C}[t]/(t^2)$ for the so-called algebra of dual numbers. The *tangent space* of the deformation functor Def_L is by definition

$$T^1 \text{Def}_L = \text{Def}_L(\mathbb{C}[\epsilon]).$$

If E is a complex vector bundle on X endowed with a projectively hyper-holomorphic connection ∇ , we shall denote by $\text{Def}_{D^*(End(E))}$ the deformation functor associated to the quaternionic Dolbeault DG Lie algebra, whose Lie bracket is given by the graded commutator of the associative product, see Proposition 3.13.

Proposition 3.18. *Let E be a complex vector bundle and $\nabla = \nabla^{1,0} + \nabla^{0,1}$ a projectively hyper-holomorphic connection. Consider the vector bundle $End(E)$ with the induced hyper-holomorphic connection $[\nabla, -]$. Then the span of DG Lie algebras*

$$(A^{0,*}(End(E)), [\nabla^{0,1}, -]) \xleftarrow{\hat{\pi}_y} D^*(End(E)) \xrightarrow{\hat{\pi}_x} (A^{0,*}(End(E)), [\nabla_j^{0,1}, -])$$

given by evaluation maps induces natural transformations of deformation functors

$$\text{Def}_{(A^{0,*}(End(E)), [\nabla^{0,1}, -])} \xleftarrow{\pi_y} \text{Def}_{D^*(End(E))} \xrightarrow{\pi_x} \text{Def}_{(A^{0,*}(End(E)), [\nabla_j^{0,1}, -])}$$

that are surjective for every $B \in \text{Art}_{\mathbb{C}}$.

Proof. First notice that the maps π_x and π_y are induced by the natural projections of DG Lie algebras

$$(A^{0,*}(End(E)), [\nabla^{0,1}, -]) \xleftarrow{\hat{\pi}_y} D^*(End(E)) \xrightarrow{\hat{\pi}_x} (A^{0,*}(End(E)), [\nabla_j^{0,1}, -])$$

where π_x (respectively, π_y) is given by evaluating $x = 1, y = 0$ (respectively, $x = 0, y = 1$) in the quaternionic Dolbeault complex.

Now, $[\nabla, -]$ is hyper-holomorphic on $End(E)$ by hypothesis. Therefore, as in the proof of Theorem 1.8, it follows that the natural injection

$$(\ker([\nabla_j^{0,1}, -]), [\nabla^{0,1}, -]) \hookrightarrow (A^{0,*}(End(E)), [\nabla^{0,1}, -])$$

is a quasi-isomorphism of DG Lie algebras, hence inducing a natural isomorphism

$$\text{Def}_{(\ker([\nabla_j^{0,1}, -]), [\nabla^{0,1}, -])} \cong \text{Def}_{(A^{0,*}(End(E)), [\nabla^{0,1}, -])}.$$

This means that in order to prove surjectivity of π_x it is sufficient to show the following implication

$$b_B \in \text{Def}_{(\ker([\nabla_J^{0,1}, -]), [\nabla^{0,1}, -])}(B) \implies y b_B \in \text{Def}_{D^*(\text{End}(E))}(B)$$

for every $B \in \text{Art}_{\mathbb{C}}$. To this aim, fix an element b_B as above and consider the equalities

$$[x \nabla_J^{0,1} + y \nabla^{0,1}, y b_B] + \frac{1}{2} [y b_B, y b_B] = y^2 \left([\nabla^{0,1}, b_B] + \frac{1}{2} [b_B, b_B] \right) = 0,$$

where we used that b_B is in the kernel of $[\nabla_J^{0,1}, -]$ and that it satisfies the Maurer–Cartan equation in the DG Lie algebra $(A^{0,*}(\text{End}(E)) \otimes \mathfrak{m}_B, [\nabla^{0,1}, -] \otimes \text{id}_{\mathfrak{m}_B})$ by assumption. Therefore $y b_A$ satisfies the Maurer–Cartan equation in the DG Lie algebra

$$(D^*(\text{End}(E)) \otimes \mathfrak{m}_B, [x \nabla_J^{0,1} + y \nabla^{0,1}, -] \otimes \text{id}_{\mathfrak{m}_B})$$

as required. A similar argument shows the surjectivity of the map π_y . \square

Proposition 3.19. *Let E be a complex vector bundle and $\nabla = \nabla^{1,0} + \nabla^{0,1}$ a projectively hyper-holomorphic connection. Then:*

- (1) *there exists a natural transformation of deformation functors*

$$\text{Def}_{D^*(\text{End}(E))} \xrightarrow{\pi_y \times \pi_x} \text{Def}_{(A^{0,*}(\text{End}(E)), [\nabla^{0,1}, -])} \times \text{Def}_{(A^{0,*}(\text{End}(E)), [\nabla_J^{0,1}, -])}$$

that is an isomorphism on tangent spaces,

- (2) *there is a natural isomorphism of deformation functors*

$$\theta : \text{Def}_{(A^{0,*}(\text{End}(E)), [\nabla^{0,1}, -])} \xrightarrow{\cong} \text{Def}_{(A^{0,*}(\text{End}(E)), [\nabla_J^{0,1}, -])}.$$

Proof. The existence of the natural transformation of item (1) follows by Proposition 3.18. It is an isomorphism on $B = \mathbb{C}[\epsilon]$ by Lemma 3.10. The last claim is a consequence of the homotopy invariance of deformation functors (cf. § 1.2) and of Remark 1.9, being

$$(A^{0,*}(\text{End}(E)), [\nabla^{0,1}, -]) \quad \text{and} \quad (A^{0,*}(\text{End}(E)), [\nabla_J^{0,1}, -])$$

quasi-isomorphic DG Lie algebras. \square

4. DEFORMATIONS OF HOLOMORPHIC VECTOR BUNDLES

4.1. Background on deformations of sheaves. To any coherent sheaf \mathcal{F} on a smooth complex projective manifold X it is associated the homotopy class of DG Lie algebras of derived endomorphisms $\text{RHom}(\mathcal{F}, \mathcal{F})$. In particular such class can be described by different quasi-isomorphic representatives (cf. e.g. [FIM12, Mea18]) but the associated deformation functor $\text{Def}_{\text{RHom}(\mathcal{F}, \mathcal{F})}$ does not depend on this choice, see § 1.2. It is well known that the deformation functor $\text{Def}_{\mathcal{F}}$ describing infinitesimal deformations of \mathcal{F} is naturally isomorphic to $\text{Def}_{\text{RHom}(\mathcal{F}, \mathcal{F})}$, see [AS18, BZ18, FIM12, IM19, Mea18]. This turns out to be a very powerful tool since the geometric properties of certain moduli spaces of sheaves on X can be understood, locally around $[\mathcal{F}]$, by the algebraic properties of $\text{RHom}(\mathcal{F}, \mathcal{F})$. For instance, it has been proven that for any polystable coherent sheaf \mathcal{F} on X the class of DG Lie algebras $\text{RHom}(\mathcal{F}, \mathcal{F})$ is formal when X is a K3 surface (cf. [BZ18]) and even more generally whenever X is a minimal surface of Kodaira dimension 0 (cf. [BMM21]).

For future reference we state here a very useful technical tool, whose proof can be found either in [FMM12] or in [FIM12].

Proposition 4.1. *Let X be a smooth and projective variety and let $(E, \bar{\partial}_E)$ be a holomorphic vector bundle on X . Then the Dolbeault algebra $(A^{0,*}(\text{End}(E)), [\bar{\partial}_E, -], [-, -])$ represents the homotopy class $\text{RHom}(E, E)$.*

As a consequence of § 1.2 and Proposition 4.1 one has the following geometric interpretation, which nowadays is folklore, and for which a good account can be found in the seminal paper [GM90]. Let us denote by $\text{Def}(E, \bar{\partial}_E)$ the Kuranishi family of a holomorphic vector bundle $(E, \bar{\partial}_E)$.

Corollary 4.2. *Keep notations as before.*

- (1) *If $(A^{0,*}(\text{End}(E)), [\bar{\partial}_E, -], [-, -])$ is Lie formal, then $\text{Def}(E, \bar{\partial}_E)$ is an intersection of quadrics.*
(2) *If $(A^{0,*}(\text{End}(E)), [\bar{\partial}_E, -], [-, -])$ is homotopy abelian, then $\text{Def}(E, \bar{\partial}_E)$ is smooth.*

With the above result in mind, the aim of § 4.2 will be to provide sufficient conditions for

$$(A^{0,*}(End(E)), [\bar{\partial}_E, -], [-, -])$$

to be associatively (hence Lie) formal. Notice that the implications of Corollary 4.2 are strong, indeed a priori there is no reason to expect the above conditions to be equivalent. In particular homotopy abelianity is stronger than smoothness. Nevertheless, if $(E, \bar{\partial}_E)$ is polystable with respect to any polarisation and X is a smooth projective surface it has been proved in [BMM22] that formality is equivalent to quadraticity (in fact, it has been proven a more general statement for coherent polystable sheaves satisfying certain conditions on a complex projective scheme of arbitrary dimension, cf. [BMM22, Theorem 1.2]).

4.2. Formality results for vector bundles with a projectively hyper-holomorphic connections. Let $X = (M, I)$ be an irreducible holomorphic symplectic manifold with Kähler class ω , and (M, g, I, J, K) the associated hyper-Kähler structure. Let E be a complex vector bundle endowed with a hyper-holomorphic connection $\nabla = \nabla^{1,0} + \nabla^{0,1}$. Recall that in particular $\nabla^{0,1}$ is a holomorphic structure on E . As in Section § 3 (cf. Remark 3.3) we shall denote by

$$\nabla_j^{0,1}: A^{0,*}(E) \rightarrow A^{0,*+1}(E)$$

the associated twisted differential.

Motivated by the deformation theory of a holomorphic vector bundle $(E, \nabla^{0,1})$, we now look at its endomorphism bundle. Recall that the Chern connection ∇ on an hermitian vector bundle E is called projectively hyper-holomorphic if the induced connection on $End(E)$ is hyper-holomorphic.

Theorem 4.3. *Consider a complex vector bundle E endowed with a projectively hyper-holomorphic connection ∇ . Then:*

- (1) $(A^{0,*}(End(E)), \cdot, [\nabla_j^{0,1}, -], [\nabla^{0,1}, -])$ is an associative DGMS algebra,
- (2) $(A^{0,*}(End(E)), \cdot, [\nabla^{0,1}, -])$ is a formal associative DG algebra.

Proof. By Lemma 3.9 the Dolbeault complex is a DGMS vector space. Hence it is sufficient to show that the differentials act as derivations with respect to the natural associative product of $A^{0,*}(End(E))$, which follows by Proposition 3.13. The last statement is then an immediate consequence of Theorem 1.8. \square

Proposition 4.4 ([Ver96, Theorem 11.1]). *Let $(E, \bar{\partial}_E)$ be a stable holomorphic vector bundle on X and consider the hermitian Yang–Mills metric induced by the Donaldson–Yau–Uhlenbeck theorem. Then the Chern connection on E is projectively hyper-holomorphic if and only if*

$$\Delta(E) := 2r c_2(E) - (r-1)c_1(E)^2$$

is $SU(2)$ -invariant.

Example 4.5. The Chern connection of any line bundle is projectively hyper-holomorphic.

Example 4.6. Let X a K3 surface, and E be a stable holomorphic vector bundle. The Yang–Mills Chern connection on E provided by Donaldson–Uhlenbeck–Yau theorem is projectively hyper-holomorphic. Essentially this is due to the fact that in dimension 2 any 2-form α such that $\Lambda_\omega \alpha = 0$ is $SU(2)$ -invariant, see [Ver96, Proposition 11.2].

Remark 4.7. Hermitian holomorphic vector bundles on X whose Chern connection is projectively hyper-holomorphic are examples of modular vector bundles, see [O’Gr22a, Definition 1.1]. As already remarked by O’Grady [O’Gr22a, Remark 1.3], the two definitions agree when X is deformation equivalent to a Hilbert scheme of 2 points on a K3 surface, or when X is deformation equivalent to the so-called OG10 manifold. Nevertheless it is not known in general whether this is always the case or not: in particular, there are no examples of stable modular vector bundles that do not admit projectively hyper-holomorphic connections.

Theorem 4.8. *Let X be an irreducible holomorphic symplectic manifold X and ω a Kähler class on X . If $(E, \bar{\partial}_E)$ is a stable holomorphic vector bundle on X such that $\Delta(E)$ is $SU(2)$ -invariant, then the associative Dolbeault DG algebra $(A^{0,*}(End(E)), \cdot, [\bar{\partial}_E, -])$ is formal.*

Proof. By Proposition 4.4, the hypotheses imply that E admits a projectively hyper-holomorphic connection. Then the associative formality of the Dolbeault DG algebra follows by Theorem 4.3. \square

By Remark 1.9 we get that $H_{[\bar{\partial}_E, -]}^\bullet(A^{0,*}(End(E))) \cong H_{[\nabla_J^{0,1}, -]}^\bullet(A^{0,*}(End(E)))$. This should be compared to [Ver96, Corollary 8.2], where it is shown that the vector spaces $H^k(End(E))$ do not depend on the induced complex structure, when E is a projectively hyper-holomorphic hermitian vector bundle.

Remark 4.9 (Polystable vector bundles). If $E = \bigoplus_{k=1}^m E_k$ is a polystable vector bundle, i.e. each E_k is stable, then the Donaldson–Uhlenbeck–Yau Yang–Mills Chern connection $\nabla = \sum_{k=1}^m \nabla_k$ can be projectively hyper-holomorphic even if the single connections (E_k, ∇_k) are not. In this case Theorem 4.3 still applies, but Proposition 4.4 does not a priori. In fact the $SU(2)$ -invariance of $\Delta(E)$ does not imply the $SU(2)$ -invariance of each $\Delta(E_k)$ and we cannot conclude that the Donaldson–Uhlenbeck–Yau Yang–Mills Chern connection ∇ is projectively hyper-holomorphic. In fact, for this to be true, one has to further assume that each summand ∇_k is so.

In the following we state some geometric consequences of Theorem 4.8. If $(E, \bar{\partial}_E)$ is a holomorphic vector bundle, we denote by $\text{Def}(E, \bar{\partial}_E)$ the Kuranishi space of infinitesimal holomorphic deformations of E (cf. [GM90]).

The first consequence is a shorter proof of a result due to Verbitsky, [Ver96, Theorem 11.2].

Corollary 4.10 (Verbitsky’s quadraticity theorem). *Let X be an irreducible holomorphic symplectic manifold X and ω a Kähler class on X . If $(E, \bar{\partial}_E)$ is a stable holomorphic vector bundle that admits a projectively hyper-holomorphic connection, then $\text{Def}(E, \bar{\partial}_E)$ is an intersection of quadrics.*

Proof. This is a direct consequence of the formality of Theorem 4.3 and Corollary 4.2. \square

Remark 4.11. Verbitsky’s proof of quadraticity of $\text{Def}(E, \bar{\partial}_E)$ is very technical and heavily uses the differential and Hodge theory of $A^{0,*}(End(E))$. Nevertheless his main tool can be tracked back to the $\nabla_J^{0,1}$ -lemma, which is also our main tool to prove formality.

Another consequence is the following well known result (see [Kim87]).

Corollary 4.12. *Let X be an irreducible holomorphic symplectic manifold X and ω a Kähler class on X . Let $(E, \bar{\partial}_E)$ be a stable holomorphic vector bundle that admits a projectively hyper-holomorphic connection. If moreover $\text{Ext}^2(E, E) = \mathbb{C}$, then $\text{Def}(E, \bar{\partial}_E)$ is smooth.*

Proof. First of all, by Theorem 4.3 the algebra $(A^{0,*}(End(E)), \cdot, [\bar{\partial}_E, -])$ is formal. Moreover, recall that $H^\bullet(A^{0,*}(End(E))) = \text{Ext}^\bullet(E, E)$. By assumption $\text{Ext}^2(E, E) = \mathbb{C}$, so that in particular the cap product defined on $\text{Ext}^1(E, E) = H_{\bar{\partial}}^1(A^{0,*}(End(E)))$ is skew-symmetric and $\text{Def}(E, \bar{\partial}_E)$ is smooth (cf. § 1.2). \square

Notice that in Corollary 4.12, the formal DG Lie algebra $A^{0,*}(End(E))$ need not to be homotopy abelian in general.

Remark 4.13 (Moduli space of semistable vector bundles on K3 surfaces). We already noticed in Example 4.6 that every polystable vector bundle on a K3 surface admits a hyper-holomorphic connection. Moreover, if $(E, \bar{\partial}_E)$ is stable then $\text{Ext}^2(E, E) \cong \text{Hom}(E, E) = \mathbb{C}$. Hence we recover the well known fact that the moduli space of semistable holomorphic vector bundles on a K3 surface is quadratic [BZ18, BMM22], and it is smooth at those points that can be represented by a stable holomorphic vector bundle.

Corollary 4.14. *Let X be an irreducible holomorphic symplectic manifold X and ω a Kähler class on X . Let $(E, \bar{\partial}_E)$ be a stable holomorphic vector bundle that admits a projectively hyper-holomorphic connection. If moreover there exists a smooth projective variety Z such that $\text{Ext}^*(E, E) \cong H^*(Z, \mathbb{C})$, then*

$$(A^{0,*}(End(E)), [\bar{\partial}_E, -], [-, -])$$

is a homotopy abelian DG Lie algebra. In particular $\text{Def}(E, \bar{\partial}_E)$ is smooth.

Proof. By Theorem 4.8, the associative Dolbeault DG algebra $(A^{0,*}(End(E)), \cdot, [\bar{\partial}_E, -])$ is formal. Hence to prove homotopy abelianity is enough to show that the associative product is graded commutative in cohomology, see Remark 1.14. On the other hand, the associative cap product on $H^*(Z, \mathbb{C})$ is graded commutative so that the claim follows by a standard Eckmann–Hilton argument, [EH62]. \square

Corollary 4.15 ([BZ18, Proposition 1.4]). *Let X and Y be two projective irreducible holomorphic symplectic manifolds and $\Phi: D^b(X) \rightarrow D^b(Y)$ a Fourier–Mukai equivalence between their derived categories. Suppose that $(E, \bar{\partial}_E)$ is a hermitian holomorphic vector bundle admitting a projectively hyper-holomorphic connection. Then $\text{Def}(\Phi(E), \bar{\partial}_{\Phi(E)})$ is given by an intersection of quadrics.*

Proof. By Theorem 4.8 the Dolbeault associative DG algebra $(A^{0,*}(End(E)), \cdot, [\bar{\partial}_E, -])$ is formal. On the other hand, by [BZ18, Proposition 1.4] the associative formality of derived endomorphisms is preserved under Fourier–Mukai equivalences. The statement follows. \square

Example 4.16 (Tangent bundle). In Example 2.11 we have seen that the Chern connection of the holomorphic tangent bundle Θ_X of an irreducible holomorphic symplectic manifold X is hyper-holomorphic with respect to the hermitian metric induced by X . Then the Dolbeault algebra $A^{0,*}(End(\Theta_X))$ is formal and the Kuranishi space $Def(\Theta_X)$ is quadratic.

Example 4.17 (Vector bundles on Fano varieties of lines). This example is due to O’Grady (see [O’Gr22a, Section 2.1]). Let $Y \subset \mathbb{P}(V_6)$ be a smooth cubic fourfold and $X = F(Y) \subset G = G(2, V_6)$ its Fano variety of lines. It is known that X is an irreducible holomorphic symplectic manifold of type $K3^{[2]}$ ([BD85]). The Plücker embedding of G in $\mathbb{P}(\bigwedge^2 V_6)$ provides X with a canonical polarisation H and, if X is very general, it follows that $Pic(X) = \mathbb{Z}H$. Let Q be the tautological bundle on G parametrising the quotient spaces of V_6 ; then Q has rank 4 and first Chern class equal to the Plücker class. One can check (e.g. Example (2) in [O’Gr22a, Section 2.1]) that $\Delta(E) = c_2(X)$ is $SU(2)$ -invariant. Moreover, E is stable. In particular, E admits a projectively hyper-holomorphic connection and $Def(E)$ is quadratic.

Since Q is generated by global sections, one can check that also E is generated by global sections (in particular one can compute that $H^0(X, E) \cong H^0(G, Q) = V_6$ – we thank E. Fatighenti for this remark). The elementary transform of E is a vector bundle F on X of rank 2 that is isomorphic to the restriction to X of the tautological bundle on G of the subspaces of V_6 . It is easy to check by hand that F is stable and that $\Delta(F) = \frac{3}{2}h^2 - \frac{1}{2}c_2(X)$ is not $SU(2)$ -invariant. Nevertheless, by Corollary 4.15, also $A^{0,*}(End(F))$ is formal, and hence $Def(F)$ is quadratic. From a geometric point of view these examples are easily understood: both E and F are rigid vector bundles, so that their deformation spaces consist of just a point.

Example 4.18. In [O’Gr22b], O’Grady constructs a class of slope stable locally free sheaves on a generalised Kummer fourfold whose discriminant is $SU(2)$ -invariant. Therefore, by Theorem 4.8, the associated Dolbeault algebra is formal. Notice that also in this case the locally free sheaf is rigid.

4.2.1. Other examples. Constructing examples of projectively hyper-holomorphic connections on holomorphic vector bundles is in general a very difficult task. In fact, the only tool we have now is Proposition 4.4 applied to stable holomorphic vector bundles. The biggest set of theoretical examples is provided by Markman in [Mar21]. Markman’s examples are divided in three classes:

- (1) vector bundles of the form $\Phi(\mathcal{O}_X)$, where Φ is a Fourier–Mukai transform;
- (2) vector bundles of the form $\Phi(\mathcal{O}_x)$, where Φ is as before and $x \in X$ is a point;
- (3) vector bundles of the form $\Phi(\mathcal{L})$, where $\Phi: D^b(Z) \rightarrow D^b(X)$ a Fourier–Mukai equivalence, $Z \subset X$ is a lagrangian submanifold that deforms with X in codimension 1 and \mathcal{L} is a power of the anti-canonical bundle of Z .

All these examples, when stable, have a smooth Kuranishi space (actually, their Dolbeault DG Lie algebra is homotopy abelian), as it follows from [BZ18, Proposition 1.4] (see also Corollary 4.15).

The first two classes of examples are rigid, so that from a geometric point of view they are not very interesting. Markman explicitly constructs stable vector bundles belonging to these two classes of examples.

The third class of examples is much more interesting, because would provide examples of non-rigid vector bundles. In [Mar21, Example 3.11], Markman lists three known geometric cases where a lagrangian submanifold $Z \subset X$ deforms with X in codimension 1. The most interesting geometric example is given by sheaves of the form $\Phi(i_* \mathcal{O}_{F(Y)})$, where V is a smooth cubic fourfold, Y is a linear section of V , $F(Y)$ and $F(V)$ are the respective Fano varieties of lines, and $i: F(Y) \rightarrow F(V)$. Unfortunately, it is still unknown whether such a sheaf is locally free and whether it is stable. Nevertheless, when stable and locally free such a sheaf has a homotopy abelian Dolbeault DG Lie algebra by Theorem 4.8 and Corollary 4.14. We remark that the formality of torsion sheaves of the form $i_* \mathcal{L}$ as above has been proved by Mladenov in [Mla20], see also [Mla19, Theorem 0.1.3].

5. DEFORMATIONS OF AUTODUAL CONNECTIONS

To begin with, our aim is to define the deformation functor associated to an autodual connection ∇ on a complex vector bundle on an irreducible holomorphic symplectic manifold.

First of all, if $B \in \text{Art}_{\mathbb{C}}$ is any local artinian \mathbb{C} -algebra with residue field \mathbb{C} , we define the $\text{SU}(2)$ -action on $A^*(\text{End}(E)) \otimes_{\mathbb{C}} B$ as the natural $\text{SU}(2)$ -action on $A^*(\text{End}(E))$ and as the identity on B .

Definition 5.1 (Infinitesimal deformation of an autodual connection). Let $X = (M, I)$ be an irreducible holomorphic symplectic manifold and (M, g, I, J, K) the hyper-Kähler structure associated to a Kähler class ω . Let E be a complex vector bundle on X and ∇ an autodual connection on E . A deformation of ∇ over $B \in \text{Art}_{\mathbb{C}}$ is a B -linear graded map

$$\nabla_B : A^*(E) \otimes_{\mathbb{C}} B \rightarrow A^{*+1}(E) \otimes_{\mathbb{C}} B$$

satisfying the following conditions:

- (1) ∇_B satisfies the Leibniz rule

$$\nabla_B(\alpha \otimes e \otimes b) = (d\alpha) \otimes e \otimes b + (-1)^k \alpha \wedge \nabla_B(e \otimes b),$$

where α is a k -form, e is a section of E and $b \in B$.

- (2) $\nabla_B \otimes_B \mathbb{C} = \nabla$,

- (3) $\nabla_B^2 \in A^2(\text{End}(E)) \otimes_{\mathbb{C}} B$ is $\text{SU}(2)$ -invariant.

We refer to a ∇_B satisfying item (1) of Definition 5.1 as a B -connection. Item (2) can be understood as the commutativity of the diagram of B -modules

$$\begin{array}{ccc} A^*(E) \otimes_{\mathbb{C}} B & \xrightarrow{\nabla_B} & A^{*+1}(E) \otimes_{\mathbb{C}} B \\ \downarrow & & \downarrow \\ A^*(E) & \xrightarrow{\nabla} & A^{*+1}(E) \end{array}$$

where the B -module structure of $A^{0,*}(E)$ is induced by the projection $B \rightarrow B/\mathfrak{m}_B \cong \mathbb{C}$ that annihilates the maximal ideal \mathfrak{m}_B . Finally, notice that the composition $\nabla_B^2 = \nabla_B \circ \nabla_B$ is $A^0 \otimes_{\mathbb{C}} B$ -linear, so that item (3) is well defined and corresponds to the autoduality property.

Remark 5.2. We may prove a completely analogous statement to Proposition 3.7 simply by working over B instead of \mathbb{C} in order to characterise autodual deformations in terms of strong Maurer–Cartan solutions.

Remark 5.3. Notice that a B -deformation ∇_B of ∇ is equivalent to the data of an A^0 -linear

$$\hat{\nabla}_B : A^0(E) \rightarrow A^1(E) \otimes_{\mathbb{C}} \mathfrak{m}_B.$$

In fact, if such $\hat{\nabla}_B$ is given, then there is a unique way to recover the B -deformation ∇_B by extending

$$\nabla \otimes 1 + \hat{\nabla}_B : A^0(E) \rightarrow A^1(E) \otimes_{\mathbb{C}} B.$$

via B -linearity and the Leibniz rule.

Definition 5.4 (Equivalence of deformations). If E is a complex vector bundle over X and $B \in \text{Art}_{\mathbb{C}}$, then we denote by $E \otimes_{\mathbb{C}} B$ the vector bundle over $X_B = X \times \text{Spec}(B)$. If $\mathcal{G}(E)$ is the gauge group of E and $\mathcal{G}(E)_B$ is the gauge group of $E \otimes B$, then we define $\mathcal{G}(E)_B^0$ the kernel

$$\mathcal{G}(E)_B^0 = \ker(\mathcal{G}(E)_B \longrightarrow \mathcal{G}(E))$$

induced by the quotient map $B \rightarrow B/\mathfrak{m}_B \cong \mathbb{C}$.

If $\nabla_{B,1}$ and $\nabla_{B,2}$ are two B -connections, then we say that they are *equivalent* if there exists an element $g_B \in \mathcal{G}(E)_B^0$ such that the following diagram

$$\begin{array}{ccc} A^*(E) \otimes_{\mathbb{C}} B & \xrightarrow{g_B} & A^*(E) \otimes_{\mathbb{C}} B \\ \nabla_{B,1} \downarrow & & \downarrow \nabla_{B,2} \\ A^{*+1}(E) \otimes_{\mathbb{C}} B & \xrightarrow{g_B} & A^{*+1}(E) \otimes_{\mathbb{C}} B \end{array}$$

commutes.

In the diagram above, the automorphism g_B is extended to the complex $A^*(E) \otimes B$ by A^0 -linearity.

Remark 5.5. The definition above is classical, but let us explain it. First of all, recall that the gauge group $\mathcal{G}(E)$ is the group of transformations of E as a vector bundle over X (same for $\mathcal{G}(E)_B$). Classically two connections (resp. B -connections) over E (resp. E_B) are said to be equivalent if they are conjugated by a gauge transformation. The choice to act by the subgroup $\mathcal{G}(E)_B^0$ is motivated by the fact that we want an equivalence between two deformations of ∇ to be the identity when quotiented by the maximal ideal (i.e. when restricted to the central fibre).

Remark 5.6. The group $\mathcal{G}(E)_B^0$ is classically known in deformation theory, and it coincides with the nilpotent Lie group $\exp(A^0(\text{End}(E)) \otimes_{\mathbb{C}} \mathfrak{m}_B)$ (see e.g. [GM88, Section 6.1]).

In particular, from our point of view it is important to remark that $\exp(A^0(\text{End}(E)) \otimes_{\mathbb{C}} \mathfrak{m}_B)$ is also the group of gauge transformations of the quaternionic Dolbeault DG Lie algebra $D^*(\text{End}(E)) \otimes_{\mathbb{C}} B$ (cf. Section § 1.2).

Definition 5.7 (Deformation functor associated to an autodual connection). Let X be an irreducible holomorphic symplectic manifold with a fixed Kähler class ω . Let E be a complex vector bundle on X endowed with an autodual connection ∇ . The deformation functor associated to ∇ is defined by

$$\text{Def}_{\nabla}: \text{Art}_{\mathbb{C}} \rightarrow \text{Sets} \quad \text{Def}_{\nabla}(B) = \{\text{autodual deformations of } \nabla \text{ over } B\} / \sim,$$

where \sim denotes the equivalence relation given in Definition 5.4.

Given an autodual connection ∇ on E , we denote by $\text{Def}_{D^*(\text{End}(E))}$ the deformation functor associated to the quaternionic Dolbeault DG Lie algebra

$$(D^*(\text{End}(E)), x[\nabla_J^{0,1}, -] + y[\nabla^{0,1}, -], [-, -])$$

as in Section § 3.

The main result of this section is the following.

Theorem 5.8. *Let X be an irreducible holomorphic symplectic manifold with a fixed Kähler class ω . Let E be a complex vector bundle on X . If ∇ is an autodual connection, then there is a natural isomorphism of deformation functors*

$$\Phi: \text{Def}_{D^*(\text{End}(E))} \rightarrow \text{Def}_{\nabla}.$$

Proof. Fix $B \in \text{Art}_{\mathbb{C}}$. A Maurer–Cartan element

$$x \xi_1 \otimes b_1 + y \xi_2 \otimes b_2 \in \text{MC}(D^*(\text{End}(E)) \otimes_{\mathbb{C}} \mathfrak{m}_B, [x \nabla_J^{0,1} + y \nabla^{0,1}, -] \otimes \text{id}_{\mathfrak{m}_B})$$

satisfies the equation

$$\begin{aligned} & x^2 \left([\nabla_J^{0,1}, \xi_1] \otimes b_1 + \frac{1}{2} [\xi_1, \xi_1] \otimes b_1^2 \right) + y^2 \left([\nabla^{0,1}, \xi_2] \otimes b_2 + \frac{1}{2} [\xi_2, \xi_2] \otimes b_2^2 \right) + \\ & + x y \left([\nabla_J^{0,1}, \xi_2] \otimes b_2 + [\nabla^{0,1}, \xi_1] \otimes b_1 + [\xi_1, \xi_2] \otimes b_1 b_2 \right) = 0. \end{aligned}$$

This can be rephrased as the following conditions

- $\xi_2 \otimes b_2 \in \text{MC}(A^{0,*}(\text{End}(E)) \otimes_{\mathbb{C}} \mathfrak{m}_B, [\nabla^{0,1}, -] \otimes \text{id}_{\mathfrak{m}_B})$,
- $\xi_1 \otimes b_1 \in \text{MC}(A^{0,*}(\text{End}(E)) \otimes_{\mathbb{C}} \mathfrak{m}_B, [\nabla_J^{0,1}, -] \otimes \text{id}_{\mathfrak{m}_B})$,
- $[\nabla_J^{0,1} + \xi_1 \otimes b_1, \nabla^{0,1} + \xi_2 \otimes b_2] = 0$.

where in the last equality we used $[\nabla_J^{0,1}, \nabla^{0,1}] = 0$, being ∇ autodual by hypothesis. Once again, we can repackage the above information as follows

- $\nabla^{0,1} + \xi_2 \otimes b_2$ is a holomorphic deformation of $\nabla^{0,1}$,
- $\nabla_J^{0,1} + \xi_1 \otimes b_1$ satisfies the *strong* Maurer–Cartan equation in the DG Lie algebra

$$(A^{0,*}(\text{End}(E)) \otimes_{\mathbb{C}} \mathfrak{m}_B, [\nabla^{0,1} + \xi_2 \otimes b_2, -] \otimes \text{id}_{\mathfrak{m}_B}).$$

Hence it is uniquely defined the A^0 -linear map

$$\hat{\nabla}_B = \xi_2 \otimes b_2 + (J \otimes \text{id}) \circ (\xi_1 \otimes b_1) \circ (J^{-1} \otimes \text{id}): A^0(E) \longrightarrow A^1(E) \otimes_{\mathbb{C}} \mathfrak{m}_B$$

which in turn gives us the definition of the B -deformation $\nabla_B = \nabla + \hat{\nabla}_B$ as explained by Remark 5.3. Notice that the items above are equivalent to require that ∇_B is autodual, see Proposition 3.7.

We defined a natural transformation from the Maurer–Cartan functor, i.e.

$$\hat{\Phi}: \text{MC}_{D^*(\text{End}(E))} \longrightarrow \text{Def}_{\nabla}.$$

It is not difficult to check that such a natural transformation is surjective.

To conclude we need to understand how the natural transformation f behaves with respect to the respective gauge transformations. First of all, recall from the definition that $D^0(End(E)) = A^0(End(E))$ and so the gauge group acting on $MC(D^*(End(E)) \otimes_{\mathbb{C}m_B})$ coincides with the group $\exp(D^0(End(E)) \otimes m_B)$. On the other hand, the last group is the same as the group of gauge equivalences of a B -deformation of ∇ as defined in Definition 5.4. To conclude the proof, we claim that

$$\hat{\Phi}(x \xi_1 \otimes b_1 + y \xi_2 \otimes b_2) \sim \hat{\Phi}(x \xi'_1 \otimes b'_1 + y \xi'_2 \otimes b'_2)$$

if and only if

$$(x \xi_1 \otimes b_1 + y \xi_2 \otimes b_2) \sim (x \xi'_1 \otimes b'_1 + y \xi'_2 \otimes b'_2).$$

From this it follows both that $\hat{\Phi}$ descends to a natural transformation

$$\Phi: \text{Def}_{D^*(End(E))} \longrightarrow \text{Def}_{\nabla}$$

and that Φ is injective, hence an isomorphism.

On the other hand the claim holds by definition. In fact Definition 5.4 is given so that it coincides with the natural gauge action in the deformation theory of a DG Lie algebra (see Remark 5.6). \square

If E is a complex vector bundle and ∇ is a hyper-holomorphic connection, then $(E, \nabla^{0,1})$ is a holomorphic structure (that is polystable by the Donaldson–Uhlenbeck–Yau Theorem). From this point of view it is natural to ask what is the interplay between holomorphic deformations of $(E, \nabla^{0,1})$ and autodual deformations of (E, ∇) .

Corollary 5.9. *Let E be a complex vector bundle on an irreducible holomorphic symplectic manifold with a fixed kähler class. Suppose E is endowed with a holomorphic structure $\bar{\partial}$ and a hyper-holomorphic connection $\nabla = \nabla^{1,0} + \bar{\partial}$. Then*

- (1) *for every holomorphic deformation $(E, \bar{\partial}')$ of $(E, \bar{\partial})$ there exists an autodual connection ∇' whose $(0,1)$ -part is $\bar{\partial}'$,*
- (2) *there exists a 1:1 correspondence*

$$\{\text{First order deformations of } \bar{\partial}\} \longleftrightarrow \left\{ \begin{array}{l} \text{First order autodual deformations of } \nabla \\ \text{whose } (0,1)\text{-part is } \bar{\partial} \end{array} \right\}.$$

Proof. Let us start from item (1). Infinitesimal deformations of the holomorphic vector bundle $(E, \bar{\partial})$ are controlled by the DG Lie algebra

$$(A^{0,*}(End(E)), [\bar{\partial}, -], [-, -])$$

by Proposition 4.1. On the other hand, deformations of an autodual connection are controlled by the DG Lie algebra

$$(D^*(End(E)), x[\nabla_J^{0,1}, -] + y[\bar{\partial}, -], [-, -])$$

by Theorem 5.8. The projection

$$\hat{\pi}_y: D^*(End(E)) \longrightarrow A^{0,*}(End(E))$$

defined as the evaluation at $x = 0, y = 1$ is a morphism of DG Lie algebras, so that we have the induced natural transformation

$$\text{Def}_{\nabla} \cong \text{Def}_{D^*(End(E))} \xrightarrow{\pi_y} \text{Def}_{(E, \bar{\partial})}.$$

The claim is equivalent to prove that π_y is surjective, which is exactly the statement of Proposition 3.18.

Let us now turn to item (2). First order deformations are parametrised by elements in the tangent space of a deformation functor. Recall that by Proposition 3.19 there is a natural transformation

$$\text{Def}_{\nabla} \cong \text{Def}_{D^*(End(E))} \longrightarrow \text{Def}_{(A^{0,*}(End(E)), [\nabla^{0,1}, -])} \times \text{Def}_{(A^{0,*}(End(E)), [\nabla_J^{0,1}, -])}$$

that is an isomorphism on tangent spaces, and moreover

$$T^1 \text{Def}_{(A^{0,*}(End(E)), [\nabla^{0,1}, -])} \cong T^1 \text{Def}_{(A^{0,*}(End(E)), [\nabla_J^{0,1}, -])}.$$

The claim follows. \square

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