The Signature of Cusped Hyperbolic 4-Manifolds

(Article begins on next page)

03 May 2024

THE SIGNATURE OF CUSPED HYPERBOLIC 4–MANIFOLDS

ALEXANDER KOLPAKOV, STEFANO RIOLO, AND STEVEN T. TSCHANTZ

ABSTRACT. In this note we show that every integer is the signature of a non–compact, oriented, hyperbolic 4–manifold of finite volume, and give some partial results on the "geography" of such manifolds. The main ingredients are a theorem of Long and Reid, and the explicit construction of a hyperbolic 24–cell manifold with some special topological properties.

> *Few things are harder to put up with than the annoyance of a good example.*

> – Mark Twain

1. Introduction

In the recent survey [13] on hyperbolic 4–manifolds, Martelli asks whether one can find a cusped hyperbolic 4–manifold with non–vanishing signature (see [13, Section 4] for other open questions). The main purpose of this note is to prove the following:

Theorem 1.1. *Every integer is the signature of a cusped hyperbolic 4–manifold.*

All manifolds in the paper are assumed connected and oriented unless otherwise stated. Hyperbolic manifolds are understood to be complete and of finite volume. Non–compact hyperbolic manifolds are called *cusped*.

Closed hyperbolic 4–manifolds have vanishing signature, while for cusped manifolds this property holds virtually (in a strong sense, see Corollary 2.2). The latter fact follows from a result of Long and Reid [12] which plays an important role in this paper. It is worth noting that for cusped manifolds the signature is not necessarily multiplicative under finite coverings.

As a byproduct of our construction, we obtain some results on the "geography problem" for cusped hyperbolic 4–manifolds. The latter asks about realising a given pair of integers as the Euler characteristic $\chi(M)$ and signature $\sigma(M)$ of a cusped hyperbolic 4–manifold M. Indeed, Theorem 1.1 is a consequence of the following:

Theorem 1.2. *For every pair of positive integers m, n with m odd, there exists a cusped hyperbolic 4–manifold M with $\sigma(M) = \pm n$ and $\chi(M) = mn$.*

Recall that hyperbolic 4–manifolds have positive Euler characteristic by the generalised Gauß–Bonnet formula.

1.1. **Consequences and questions.** As shown by Ratcliffe and Tschantz [18], every positive integer is realised as $\chi(M)$ for some cusped hyperbolic 4–manifold M. However, all the manifolds constructed in [18] (as well as their covers) happen to have vanishing signature, as well as any other cusped hyperbolic 4–manifold that we could find in the literature. Combining this fact (or Corollary 2.2) with Theorem 1.2, we obtain that for every integer n there exists a cusped hyperbolic 4–manifold M with $\sigma(M) = n$ and $\chi(M)$ arbitrarily big.

On the other hand (Proposition 2.3), every cusped hyperbolic 4–manifold M satisfies

$$\chi(M) > 0.03493 \cdot |\sigma(M)|.$$

It thus seems reasonable trying to minimise χ for any fixed value of $|\sigma|$. For $\sigma = 0$, the minimum possible $\chi = 1$ is realised by [18]. Theorem 1.2 implies the following fact.

Corollary 1.3. *For every positive integer n, there exists a cusped hyperbolic 4–manifold with $\chi(M) = \sigma(M) = n$.*

We shall call the quantity

$$\alpha(M) = \sigma(M)/\chi(M)$$

the slope of M. By the above inequality, the slope of a cusped hyperbolic 4–manifold is always bounded, and a natural "geography" problem is to determine which slopes can be realised. Theorem 1.2 gives a partial answer:

Corollary 1.4. *For every odd integer m, there exist infinitely many cusped hyperbolic 4–manifolds with slope $1/m$.*

In particular, the maximum slope realised by our construction equals 1. Note that a well–known conjecture dating back to Gromov's work on bounded cohomology [4, §8.A4] states that every *closed* aspherical 4–manifold M satisfies $|\alpha(M)| \leq 1$, which is known as Winkelnkemper's inequality [7].

In the setting of our work, the following questions arise naturally.

Question 1.5. Can we describe the set of pairs $(\chi(M), \sigma(M))$ for all possible cusped hyperbolic 4–manifolds M? In other words, what is the geography of cusped hyperbolic 4–manifolds?

Question 1.6. What is the maximum slope of a cusped hyperbolic 4–manifold?

1.2. **On the proof.** Our proof of Theorem 1.2 is constructive and rather simple. We explicitly build a cusped hyperbolic 4–manifold M satisfying $\chi(M) = \sigma(M) = 1$ and such that for every $m, n \geq 1$ with m odd, there exists an mn–sheeted covering $M_{m,n} \to M$ with $\sigma(M_{m,n}) = n$.

An essential tool is an adaptation of the Atiyah–Patodi–Singer formula for cusped hyperbolic 4–manifolds by Long and Reid (cf. Theorem 2.1), combined with the results of Ouyang [16], thanks to which the signature can be expressed only in terms of the oriented homeomorphism classes of the cusp sections.

Similar to [18, 19], the manifold M is obtained by gluing the sides of the ideal right-angled 24–cell. In particular, $\chi(M) = 1$. The side pairing is performed in

order to have one cusp with section a "quarter twist" flat 3–manifold F_4, while the remaining cusps have 3–torus sections. Then Long and Reid's signature formula gives $\sigma(M) = \pm 1$.

Moreover, there exist homomorphisms $\pi_1(M) \to \mathbb{Z}$ that map to zero some generators of the parabolic subgroup of the F_4–cusp, in a way to get an n–sheeted cyclic covering $M_n \to M$ under which σ is multiplicative, and an m–sheeted cyclic covering $M_{m,n} \to M_n$ under which σ does not change. The latter condition is satisfied if m is odd: in this case, the manifold $M_{m,n}$ has exactly n cusps of type F_4, all coherently oriented, while the remaining ones have 3–torus sections. This implies $\sigma(M_{m,n}) = \pm n$.

As in [19], the starting point to find M is an extensive computer search. Despite the fact that M is produced by computer, it has a relatively simple structure and all the aforementioned properties can be verified by hand. However, finding such a starting manifold M by hand is conceivably impossible within any reasonable time if one wants to search through all or a sufficiently large number of side pairings.

We would like to stress the fact that the manifold M used in our present construction does not appear to be special: we only concentrate on it because of its simple structure that makes our proofs verifiable by hand. Another construction of Tschantz's involving 24–cells (the details of which are rather technical and impossible to verify without computer aid) together with some arithmetic tools and ad hoc tricks allows us to produce $\sim m^m$ commensurability classes of manifolds with $\chi \leq m$ for any fixed value of σ and m large enough, cf. [2, 3]. Presenting the details here, however, would obfuscate our main goal, that is proving Theorem 1.1 in a relatively simple way. This result is the subject of a future work [11].

1.3. **Structure of the paper.** Some general facts on the geography of cusped hyperbolic 4–manifolds are given in Section 2. The proof of Theorem 1.2 follows in Section 3.

2. Preliminaries

Recall that all manifolds in this paper are connected and oriented, unless otherwise stated. All homology and cohomology groups are understood with integer coefficients.

2.1. **Signature and geography.** Let X be a compact 4–manifold with boundary, and let $[X, \partial X] \in H_4(X, \partial X) \cong \mathbb{Z}$ be its fundamental class.

The cup product on $H^2(X, \partial X)$ defines the following symmetric bilinear form, called the *intersection form* of X:

$$H^2(X, \partial X) \times H^2(X, \partial X) \to \mathbb{Z}, \quad (\alpha, \beta) \mapsto \alpha \smile \beta \, ([X, \partial X]).$$

By the Poincaré–Lefschetz duality, the radical of the intersection form is the kernel of the natural map $H^2(X, \partial X) \to H^2(X)$.

Let q_+ and q_- be the positive and negative inertia indices of the associated quadratic form over $\mathbb{R}$. Then the *signature* of X is defined as

$$\sigma(X) = q_+ - q_- \in \mathbb{Z}.$$

The notion of "geography" for 4–manifolds appears to be classical and has been studied in different contexts by many authors (see [20] for a detailed survey). For M a 4–manifold, the *geography map* can be defined as $M \mapsto (\chi(M), \sigma(M))$. The *slope* of M is $\alpha(M) = \sigma(M)/\chi(M)$. Note that in [20] the slope and geography map are defined for manifolds with complex structures and thus expressed via Chern numbers: we slightly modify the definitions in our setting.

Here and below we shall be interested in the class of cusped hyperbolic 4–manifolds, and the behaviour of the geography and slope maps on it.

2.2. **Signature of hyperbolic** 4–**manifolds.** If M is a closed hyperbolic 4–manifold, then it follows from the Hirzebruch signature theorem theorem that $\sigma(M) = 0$, since by a theorem of Chern the first Pontryagin class vanishes [17, Theorem 11.3.3] (as it more generally does for locally conformally flat manifolds, cf. [12]).

Let now M be a cusped hyperbolic 4–manifold. Since M is homeomorphic to the interior of a compact 4–manifold X with boundary, then by the Poincaré–Lefschetz duality we have a well-defined intersection form on $H_2(M) \cong H^2(X, \partial X)$ and signature $\sigma(M) := \sigma(X)$.

In [12] Long and Reid provided an adaptation of the Atiyah–Patodi–Singer formula [1] for cusped hyperbolic 4–manifolds.

Theorem 2.1 (Long–Reid)**.** *Let M be a hyperbolic 4–manifold with m cusps $C_1, \ldots, C_m$, and let S_i be a horospherical section of C_i. Then*

$$\sigma(M) = -\sum_{i=1}^{m} \eta(S_i).$$

Here η is the so-called *eta invariant* of a closed oriented Riemannian 3–manifold, see [1, 12]. Same as the signature, η changes its sign when the orientation of the manifold is reversed, and thus vanishes on achiral manifolds. Since cusped hyperbolic manifolds have virtually torus cusps [15, Theorem 3.1], we have the following corollary.

Corollary 2.2. *For every cusped hyperbolic 4–manifold M there is a finite covering $M' \to M$ such that $\sigma(M'') = 0$ for every finite covering $M'' \to M'$.*

This shows that, in particular, constructing cusped hyperbolic manifolds with given signatures likely cannot be done by considering some sort of "generic" or "random" coverings of a given particular manifold. We shall concentrate on using cyclic coverings as in this case preserving the topological type of cusps in the covering is relatively easy.

There are precisely six closed orientable flat 3–manifolds up to homeomorphism [5]. We denote them in the order given by Hantzsche and Wendt [5] as follows: the 3–torus F_1, the "half-twist" manifold F_2, the "third-twist" manifold F_3, the "quarter-twist" manifold F_4, the "sixth-twist" manifold F_5, and the Hantzsche–Wendt manifold F_6. For $i = 1, \ldots, 5$, the manifold F_i is a mapping torus over $S^1 \times S^1$ with monodromy of order 1, 2, 3, 4, and 6, respectively.

As shown by Ouyang [16], the η–invariant of a flat 3–manifold does not depend on the chosen flat metric, and thus represents a topological invariant for such manifolds. More precisely [16], we have:

$$\eta(F_1) = \eta(F_2) = \eta(F_6) = 0,$$

$$\eta(F_3) = \pm\frac{2}{3}, \quad \eta(F_5) = \pm\frac{4}{3}, \quad \eta(F_4) = \pm 1.$$

In particular, a hyperbolic 4–manifold M whose unique non–torus cusp has F_4 section has signature ± 1. Moreover, $\sigma(\widetilde{M}) = \pm n$ for any n–sheeted regular covering $\widetilde{M} \to M = \widetilde{M}/G$ with $G < \mathrm{Isom}^+(\widetilde{M})$ acting transitively on the F_4–cusps of $\widetilde{M}$.

2.3. The slope is bounded.
The previous facts together with the volume estimates of Kellerhals [8] imply the following lower bound, that we believe however to be far from sharp.

Proposition 2.3. *Every cusped hyperbolic 4–manifold M satisfies*

$$|\alpha(M)| < 28.62869.$$

Proof. From Formula (4.6) in [8, Example 2] we have $\mathrm{Vol}(M) > 0.61293 \cdot k$, where k is the number of cusps of M. By Theorem 2.1 and the values of $\eta(F_i)$ listed above, we have $\frac{4}{3} \cdot k \geq |\sigma(M)|$. Then the claimed inequality follows by applying the Gauß–Bonnet formula $\mathrm{Vol}(M) = \frac{4\pi^2}{3} \cdot \chi(M)$. $\qquad\square$

3. Proofs

In the following subsection we prove Theorem 1.2. The essential geometric construction used in our proof (Theorem 3.1) is postponed to a separate subsection.

3.1. The proof.
A *hyperbolic 24–cell manifold* is a hyperbolic 4–manifold which can be obtained by gluing isometrically in pairs the sides of an ideal right-angled 24–cell. Such a manifold M satisfies $\chi(M) = 1$.

Recall that the fundamental group of a flat quarter-twist 3–manifold F_4 is generated by two translations t_1 and t_2, and a rototranslation a whose rotational part has order 4. Note that t_1, t_2 and $t_3 = a^4$ generate the translation lattice of F_4.

Given a hyperbolic 4–manifold M with a cusp C of type F_4, let $\pi_1(C) = \langle t_1, t_2, a \rangle < \pi_1(M)$ denote the corresponding parabolic subgroup.

In the next subsection we shall prove the following theorem, that is the cornerstone of our construction.

Theorem 3.1. *There exist an orientable hyperbolic 24–cell manifold M with one cusp C of type F_4 and all the other cusps of type F_1, and two surjective homomorphisms $h, v \colon \pi_1(M) \to \mathbb{Z}$ such that $\pi_1(C) = \langle t_1, t_2, a \rangle \subset \ker(h)$, while $v(t_1) = v(t_2) = 0$ and $v(a) = 1$.*

We are ready to prove Theorem 1.2 assuming Theorem 3.1.

Since $\eta(F_4) = \pm 1$ and $\eta(F_1) = 0$, by Theorem 2.1 $\sigma(M) = 1$ up to reversing the orientation on M.

For $n \geq 1$, let $p_n \colon \mathbb{Z} \to \mathbb{Z}/n\mathbb{Z}$ be the reduction mod n, and $M_n \to M$ be the cyclic n–sheeted covering associated with $h_n := p_n \circ h$. Since $\pi_1(C) \subset \ker(h_n)$, the manifold M_n has n cusps of type F_4. Moreover, there is an orientation-preserving isometry of M_n that is cyclically permuting said cusps. All the remaining cusps of M_n have type F_1. Thus $\sigma(M_n) = n$ by Theorem 2.1, and $\chi(M_n) = n \cdot \chi(M) = n$.

Now, fix $m, n \geq 1$ and let $M_{m,n} \to M_n$ be the cyclic m–sheeted covering associated with the restriction $v_{m,n}$ of $p_m \circ v$ to $\ker(h_n)$. Since $v_{m,n}(t_1) = v_{m,n}(t_2) = 0$ and $v_{m,n}(a) = 1$, the subgroup $\pi_1(C) \cap \ker(v_{m,n})$ of $\pi_1(M_{m,n})$ is generated by t_1, t_2 and a^m, and does not contain a^k for any positive $k < m$. If m is odd (or, equivalently, $m \equiv \pm 1 \mod 4$), the associated n cusps of $M_{m,n}$ have type F_4. As before, the latter are coherently oriented, and all the remaining cusps are of type F_1. Thus $\sigma(M_{m,n}) = n$ by Theorem 2.1, and $\chi(M_{m,n}) = m \cdot \chi(M_n) = mn$.

The proof of Theorem 1.2 is thus complete assuming Theorem 3.1.

3.2. **The construction.** Here we prove Theorem 3.1.

The manifold M is specified by the side pairing of a regular ideal 24–cell, with vertices given in Table 1, by the correspondence between the vertices of paired sides provided in Table 2. We refer the reader to [17, Section 11.1] for more details on how to build hyperbolic 24–cell manifolds by using Poincaré's fundamental polytope theorem.

Alternatively, we can give the side pairing by specifying the matrices for each side pairing map. Since side 1 is paired to side 2, the side pairing map that carries side 2 to side 1 is the inverse of that for the map from side 1 to side 2, similarly for sides 3 and 4, etc. The matrices g_i for sides $1, 3, 5, 6, 7, 8, 9, 10, 11, 12, 21$, and 22 are given in Table 3. These twelve matrices generate the fundamental group of M and the defining relations of this group are determined from the ridge cycles as shown in Table 4. There are 96 ridges in cycles of length 4, so there are 24 defining relations.

The manifold M is orientable with homology groups

$$H_0(M) = \mathbb{Z}, \ H_1(M) = \mathbb{Z}^3, \ H_2(M) = \mathbb{Z}^5, \ H_3(M) = \mathbb{Z}^2, \ H_4(M) = 0.$$

Moreover, M has three cusps: two of type F_1, and the other of type F_4. In order to facilitate a manual verification, the gluing of the 24 cubes (the vertex links of the 24–cell) producing the respective cusp sections are provided in Figures 1, 2 and 3.

The cusp C of type F_4 is the link of the vertex cycle consisting of vertices v_{17}, $v_{18}, v_{19}, v_{20}, v_{21}, v_{22}, v_{23}$, and v_{24}. The flat 3–manifold for the link of C is realised as a gluing of 8 cubes giving a presentation for $\pi_1(C)$ with 24 generators that
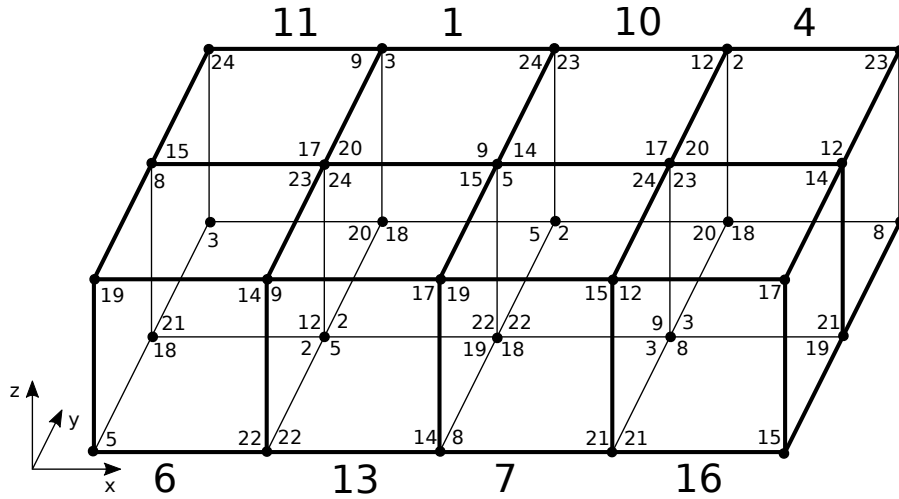
FIGURE 1. A fundamental domain for a horosection of one of the two 3–torus cusps of M in its universal cover, tessellated by 8 unit cubes. A cube with label i corresponds to the vertex v_i of the 24–cell. A vertex of cube i has label j if the corresponding edge of the 24–cell joins v_i and v_j. The resulting Euclidean lattice is generated by translations along the vectors $(4, 0, 0)$, $(0, 2, 0)$ and $(0, 0, 1)$.

FIGURE 2. A fundamental domain for a horosection of the other 3–torus cusp of M in its universal cover. The resulting Euclidean lattice is generated by translations along the vectors $(4, 0, 0)$, $(2, 2, 0)$ and $(0, 0, 1)$.

can be simplified considerably: we provide a more computationally suitable one below. The 8 cubes glue together in a pattern corresponding to a square 2–torus tiled by 8 squares with sides at $\frac{\pi}{4}$ angle to the axes of the torus as in Figure 4, multiplied by an interval in order to produce 8 cubes. The top and bottom tori are identified with a $\frac{\pi}{2}$ twist of the square torus, which is exactly the gluing pattern for the F_4 manifold.
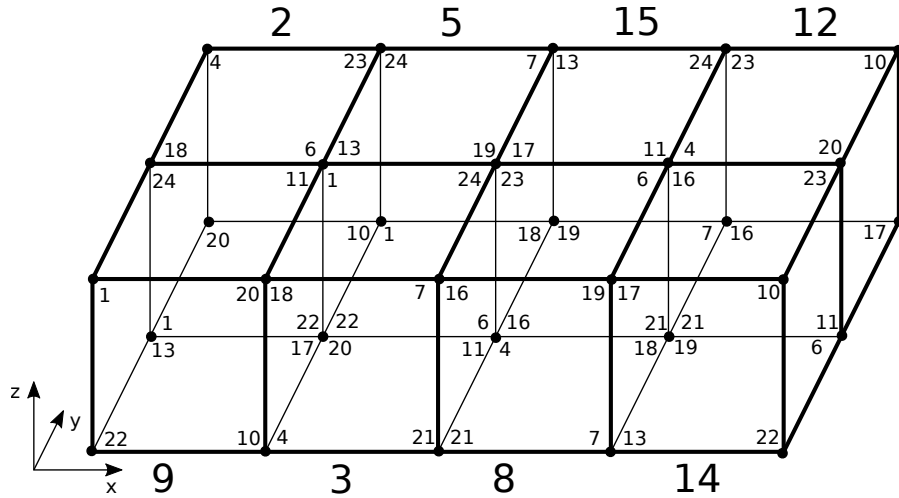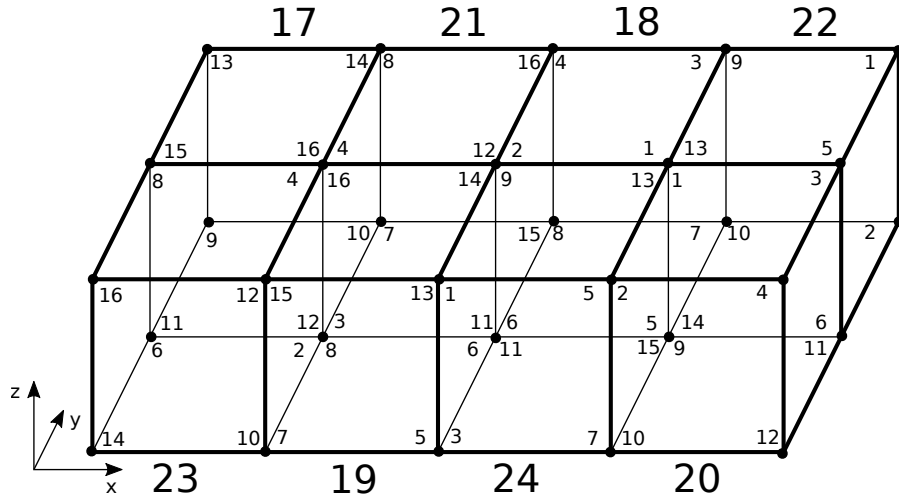
FIGURE 3. A fundamental domain for a horosection of the F_4–cusp C of M in its universal cover. The resulting Euclidean lattice is generated by translations along the vectors $(2, 2, 0)$ and $(-2, 2, 0)$, and the rototranslation along $(0, 0, 1)$ whose rotational part has vertical axis through the centre of cube 21 (see also Figure 4).
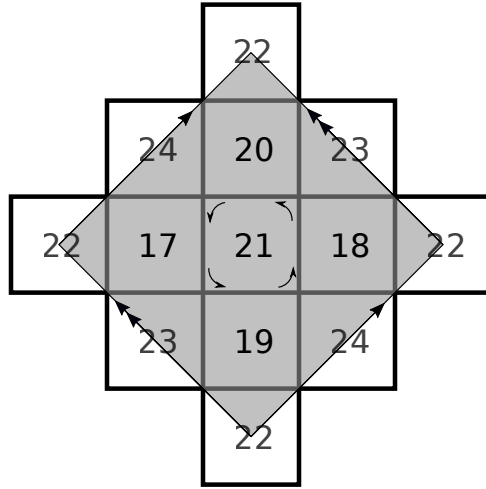
FIGURE 4. A portion of a horizontal slice of the universal cover of a horosection of the F_4–cusp C of M. The labels agree with the vertex indices of the 24–cell. The shaded square is a fundamental domain for the action of the group generated by translations along the vectors $(2, 2, 0)$ and $(-2, 2, 0)$ (see Figure 3). The "quarter-turn" action of the rototranslation in the direction orthogonal to the slice is shown by arrows in the centre.

Extracting the words in the generators of $\pi_1(M)$ giving parabolic elements stabilising vertex v_{21} produces the generators for $\pi_1(C)$, see the accompanying Tables 5 and 6. The two homomorphisms h and v are defined in Table 7.

The proof of Theorem 3.1 is now complete.

$$v_1 = \left(-\tfrac{1}{2}, -\tfrac{1}{2}, -\tfrac{1}{2}, -\tfrac{1}{2}, 1\right) \quad v_2 = \left(-\tfrac{1}{2}, -\tfrac{1}{2}, -\tfrac{1}{2}, \tfrac{1}{2}, 1\right)$$

$$v_3 = \left(-\tfrac{1}{2}, -\tfrac{1}{2}, \tfrac{1}{2}, -\tfrac{1}{2}, 1\right) \quad v_4 = \left(-\tfrac{1}{2}, -\tfrac{1}{2}, \tfrac{1}{2}, \tfrac{1}{2}, 1\right)$$

$$v_5 = \left(-\tfrac{1}{2}, \tfrac{1}{2}, -\tfrac{1}{2}, -\tfrac{1}{2}, 1\right) \quad v_6 = \left(-\tfrac{1}{2}, \tfrac{1}{2}, -\tfrac{1}{2}, \tfrac{1}{2}, 1\right)$$

$$v_7 = \left(-\tfrac{1}{2}, \tfrac{1}{2}, \tfrac{1}{2}, -\tfrac{1}{2}, 1\right) \quad v_8 = \left(-\tfrac{1}{2}, \tfrac{1}{2}, \tfrac{1}{2}, \tfrac{1}{2}, 1\right)$$

$$v_9 = \left(\tfrac{1}{2}, -\tfrac{1}{2}, -\tfrac{1}{2}, -\tfrac{1}{2}, 1\right) \quad v_{10} = \left(\tfrac{1}{2}, -\tfrac{1}{2}, -\tfrac{1}{2}, \tfrac{1}{2}, 1\right)$$

$$v_{11} = \left(\tfrac{1}{2}, -\tfrac{1}{2}, \tfrac{1}{2}, -\tfrac{1}{2}, 1\right) \quad v_{12} = \left(\tfrac{1}{2}, -\tfrac{1}{2}, \tfrac{1}{2}, \tfrac{1}{2}, 1\right)$$

$$v_{13} = \left(\tfrac{1}{2}, \tfrac{1}{2}, -\tfrac{1}{2}, -\tfrac{1}{2}, 1\right) \quad v_{14} = \left(\tfrac{1}{2}, \tfrac{1}{2}, -\tfrac{1}{2}, \tfrac{1}{2}, 1\right)$$

$$v_{15} = \left(\tfrac{1}{2}, \tfrac{1}{2}, \tfrac{1}{2}, -\tfrac{1}{2}, 1\right) \quad v_{16} = \left(\tfrac{1}{2}, \tfrac{1}{2}, \tfrac{1}{2}, \tfrac{1}{2}, 1\right)$$

$$v_{17} = (1, 0, 0, 0, 1) \quad v_{18} = (-1, 0, 0, 0, 1)$$

$$v_{19} = (0, 1, 0, 0, 1) \quad v_{20} = (0, -1, 0, 0, 1)$$

$$v_{21} = (0, 0, 1, 0, 1) \quad v_{22} = (0, 0, -1, 0, 1)$$

$$v_{23} = (0, 0, 0, 1, 1) \quad v_{24} = (0, 0, 0, -1, 1)$$

TABLE 1. The vertices of an ideal regular 24–cell in the hyperboloid model of hyperbolic 4–space.

From side	To side	Vertex map		
1	2	$(13, 14, 15, 16, 17, 19)$	$\mapsto$	$(7, 8, 5, 6, 19, 18)$
2	1	$(5, 6, 7, 8, 18, 19)$	$\mapsto$	$(15, 16, 13, 14, 19, 17)$
3	4	$(9, 10, 11, 12, 17, 20)$	$\mapsto$	$(3, 4, 1, 2, 20, 18)$
4	3	$(1, 2, 3, 4, 18, 20)$	$\mapsto$	$(11, 12, 9, 10, 20, 17)$
5	14	$(11, 12, 15, 16, 17, 21)$	$\mapsto$	$(6, 2, 8, 4, 23, 18)$
6	13	$(3, 4, 7, 8, 18, 21)$	$\mapsto$	$(12, 16, 10, 14, 23, 17)$
7	16	$(9, 10, 13, 14, 17, 22)$	$\mapsto$	$(3, 7, 1, 5, 24, 18)$
8	15	$(1, 2, 5, 6, 18, 22)$	$\mapsto$	$(13, 9, 15, 11, 24, 17)$
9	18	$(7, 8, 15, 16, 19, 21)$	$\mapsto$	$(10, 2, 12, 4, 23, 20)$
10	17	$(3, 4, 11, 12, 20, 21)$	$\mapsto$	$(8, 16, 6, 14, 23, 19)$
11	20	$(5, 6, 13, 14, 19, 22)$	$\mapsto$	$(3, 11, 1, 9, 24, 20)$
12	19	$(1, 2, 9, 10, 20, 22)$	$\mapsto$	$(13, 5, 15, 7, 24, 19)$
13	6	$(10, 12, 14, 16, 17, 23)$	$\mapsto$	$(7, 3, 8, 4, 21, 18)$
14	5	$(2, 4, 6, 8, 18, 23)$	$\mapsto$	$(12, 16, 11, 15, 21, 17)$
15	8	$(9, 11, 13, 15, 17, 24)$	$\mapsto$	$(2, 6, 1, 5, 22, 18)$
16	7	$(1, 3, 5, 7, 18, 24)$	$\mapsto$	$(13, 9, 14, 10, 22, 17)$
17	10	$(6, 8, 14, 16, 19, 23)$	$\mapsto$	$(11, 3, 12, 4, 21, 20)$
18	9	$(2, 4, 10, 12, 20, 23)$	$\mapsto$	$(8, 16, 7, 15, 21, 19)$
19	12	$(5, 7, 13, 15, 19, 24)$	$\mapsto$	$(2, 10, 1, 9, 22, 20)$
20	11	$(1, 3, 9, 11, 20, 24)$	$\mapsto$	$(13, 5, 14, 6, 22, 19)$
21	23	$(4, 8, 12, 16, 21, 23)$	$\mapsto$	$(11, 3, 15, 7, 21, 24)$
22	24	$(2, 6, 10, 14, 22, 23)$	$\mapsto$	$(5, 13, 1, 9, 22, 24)$
23	21	$(3, 7, 11, 15, 21, 24)$	$\mapsto$	$(8, 16, 4, 12, 21, 23)$
24	22	$(1, 5, 9, 13, 22, 24)$	$\mapsto$	$(10, 2, 14, 6, 22, 23)$

TABLE 2. Side pairings defining M.

$$g_1 = \begin{pmatrix} 2 & 1 & 0 & 0 & -2 \\ -1 & -2 & 0 & 0 & 2 \\ 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ -2 & -2 & 0 & 0 & 3 \end{pmatrix} \qquad g_3 = \begin{pmatrix} 2 & -1 & 0 & 0 & -2 \\ 1 & -2 & 0 & 0 & -2 \\ 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ -2 & 2 & 0 & 0 & 3 \end{pmatrix}$$

$$g_5 = \begin{pmatrix} 2 & 0 & 1 & 0 & -2 \\ 0 & 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ -1 & 0 & -2 & 0 & 2 \\ -2 & 0 & -2 & 0 & 3 \end{pmatrix} \qquad g_6 = \begin{pmatrix} 2 & 0 & -1 & 0 & 2 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & -1 & 0 & 0 & 0 \\ 1 & 0 & -2 & 0 & 2 \\ 2 & 0 & -2 & 0 & 3 \end{pmatrix}$$

$$g_7 = \begin{pmatrix} 2 & 0 & -1 & 0 & -2 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & -1 & 0 & 0 & 0 \\ 1 & 0 & -2 & 0 & -2 \\ -2 & 0 & 2 & 0 & 3 \end{pmatrix} \qquad g_8 = \begin{pmatrix} 2 & 0 & 1 & 0 & 2 \\ 0 & 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ -1 & 0 & -2 & 0 & -2 \\ 2 & 0 & 2 & 0 & 3 \end{pmatrix}$$

$$g_9 = \begin{pmatrix} 0 & 0 & 0 & -1 & 0 \\ 0 & 2 & 1 & 0 & -2 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & -1 & -2 & 0 & 2 \\ 0 & -2 & -2 & 0 & 3 \end{pmatrix} \qquad g_{10} = \begin{pmatrix} 0 & 0 & 0 & 1 & 0 \\ 0 & 2 & -1 & 0 & 2 \\ -1 & 0 & 0 & 0 & 0 \\ 0 & 1 & -2 & 0 & 2 \\ 0 & 2 & -2 & 0 & 3 \end{pmatrix}$$

$$g_{11} = \begin{pmatrix} 0 & 0 & 0 & 1 & 0 \\ 0 & 2 & -1 & 0 & -2 \\ -1 & 0 & 0 & 0 & 0 \\ 0 & 1 & -2 & 0 & -2 \\ 0 & -2 & 2 & 0 & 3 \end{pmatrix} \qquad g_{12} = \begin{pmatrix} 0 & 0 & 0 & -1 & 0 \\ 0 & 2 & 1 & 0 & 2 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & -1 & -2 & 0 & -2 \\ 0 & 2 & 2 & 0 & 3 \end{pmatrix}$$

$$g_{21} = \begin{pmatrix} 0 & -1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & -2 & 2 \\ 0 & 0 & 2 & 1 & -2 \\ 0 & 0 & -2 & -2 & 3 \end{pmatrix} \qquad g_{22} = \begin{pmatrix} 0 & 1 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & 2 & -2 \\ 0 & 0 & -2 & 1 & -2 \\ 0 & 0 & 2 & -2 & 3 \end{pmatrix}$$

TABLE 3. Generators of $\pi_1(M)$ in $SO(4,1)$.

$g_3 g_{10}^{-1} g_{22}^{-1} g_8$	$g_3 g_5^{-1} g_{22}^{-1} g_{12}$	$g_7 g_8 g_{12}^{-1} g_{11}^{-1}$	$g_3 g_{11} g_{22}^{-1} g_7^{-1}$
$g_3 g_8 g_{22}^{-1} g_{11}^{-1}$	$g_7 g_{11}^{-1} g_{12}^{-1} g_8$	$g_1 g_8 g_{22} g_{12}^{-1}$	$g_1 g_7^{-1} g_{22} g_9$
$g_1 g_{12} g_{22} g_7^{-1}$	$g_1 g_{11}^{-1} g_{22} g_6$	$g_3 g_9 g_{21} g_5^{-1}$	$g_3 g_6 g_{21} g_9^{-1}$
$g_5 g_6 g_{10}^{-1} g_9^{-1}$	$g_5 g_{10}^{-1} g_{11}^{-1} g_8$	$g_6 g_9^{-1} g_{12}^{-1} g_7$	$g_3 g_{12}^{-1} g_{21} g_6$
$g_3 g_7^{-1} g_{21} g_{10}$	$g_6 g_7 g_{12}^{-1} g_9^{-1}$	$g_5 g_8 g_{11}^{-1} g_{10}^{-1}$	$g_1 g_6 g_{21}^{-1} g_{10}^{-1}$
$g_1 g_5^{-1} g_{21}^{-1} g_{11}$	$g_5 g_9^{-1} g_{10}^{-1} g_6$	$g_1 g_{10} g_{21}^{-1} g_5^{-1}$	$g_1 g_9^{-1} g_{21}^{-1} g_8$

TABLE 4. Defining relations for $\pi_1(M)$.

$$t_1 = g_5^{-1} g_8^{-1} g_{12} g_9 = \begin{pmatrix} 1 & 0 & -4 & 0 & 4 \\ 0 & 1 & 4 & 0 & -4 \\ 4 & -4 & -15 & 0 & 16 \\ 0 & 0 & 0 & 1 & 0 \\ 4 & -4 & -16 & 0 & 17 \end{pmatrix}$$

$$t_2 = g_9^{-1} g_{10}^{-1} g_5 g_6 = \begin{pmatrix} 1 & 0 & -4 & 0 & 4 \\ 0 & 1 & -4 & 0 & 4 \\ 4 & 4 & -15 & 0 & 16 \\ 0 & 0 & 0 & 1 & 0 \\ 4 & 4 & -16 & 0 & 17 \end{pmatrix}$$

$$t_3 = g_{21}^4 = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & -31 & -8 & 32 \\ 0 & 0 & 8 & 1 & -8 \\ 0 & 0 & -32 & -8 & 33 \end{pmatrix}$$

$$a = g_{21} = \begin{pmatrix} 0 & -1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & -2 & 2 \\ 0 & 0 & 2 & 1 & -2 \\ 0 & 0 & -2 & -2 & 3 \end{pmatrix}$$

TABLE 5. Generators of $\pi_1(C)$ in $SO(4,1)$.

$$a^4 t_3^{-1} \qquad a t_1 a^{-1} t_2^{-1} \quad a t_2 a^{-1} t_1 \quad a t_3 a^{-1} t_3^{-1}$$
$$t_1 t_2 t_1^{-1} t_2^{-1} \quad t_1 t_3 t_1^{-1} t_3^{-1} \quad t_2 t_3 t_2^{-1} t_3^{-1}$$

TABLE 6. Defining relations for $\pi_1(C)$.

$$
\begin{array}{llll}
h(g_1) = 1 & h(g_3) = 1 & h(g_5) = 2 & h(g_6) = 0 \\
h(g_7) = 2 & h(g_8) = 0 & h(g_9) = 1 & h(g_{10}) = 1 \\
h(g_{11}) = 1 & h(g_{12}) = 1 & h(g_{21}) = 0 & h(g_{22}) = 0 \\
\\
v(g_1) = 2 & v(g_3) = 0 & v(g_5) = 2 & v(g_6) = 0 \\
v(g_7) = 2 & v(g_8) = 0 & v(g_9) = 1 & v(g_{10}) = 1 \\
v(g_{11}) = 1 & v(g_{12}) = 1 & v(g_{21}) = 1 & v(g_{22}) = -1
\end{array}
$$

TABLE 7. The two homomorphisms $h, v \colon \pi_1(M) \to \mathbb{Z}$.

References

[1] M. F. Atiyah, V. K. Patodi, I. M. Singer, *Spectral asymmetry and Riemannian geometry, I*, Math. Proc. Camb. Phil. Soc. **77** (1975), 43–69.

[2] M. Burger, T. Gelander, A. Lubotzky, S. Mozes, *Counting hyperbolic manifolds*, Geom. Funct. Anal. **12 (6)** (2002), 1161–1173.

[3] T. Gelander, A. Levit, *Counting commensurabilty classes of hyperbolic manifolds*, Geom. Funct. Anal. **24 (5)** (2014), 1431–1447.

[4] M. Gromov, *Asymptotic invariants of infinite groups*, in: Geometric group theory, Vol. 2 (A. Niblo, M. A. Roller eds.), London Math. Soc. Lecture Note Ser. **182**, Cambridge Univ. Press, Cambridge, 1993, vii + 295 pp.

[5] W. Hantzsche, H. Wendt, *Dreidimensionale euklidische Raumformen*, Math. Ann. **110** (1935), 593–611.

[6] A. Hatcher, *Hyperbolic structures of arithmetic type on some link complements*, J. London Math. Soc. **27** (1983), 345–355.

[7] F. E. A. Johnson, D. Kotschick, *On the signature and Euler characteristic of certain four-manifolds*, Math. Proc. Cambridge Phil. Soc. **114** (1993), 431–437.

[8] R. Kellerhals, *Volumes of cusped hyperbolic manifolds*, Topology **37** (1998), 719–734.

[9] A. Kolpakov, A. W. Reid, L. Slavich, *Embedding arithmetic hyperbolic manifolds*, Math. Res. Lett. **25** (2018), 1305–1328.

[10] A. Kolpakov, S. Riolo, L. Slavich, *Embedding non-arithmetic hyperbolic manifolds*, to appear in Math. Res. Lett., `arXiv:2003.01707`.

[11] A. Kolpakov, S. Riolo, S. T. Tschantz, *Counting cusped hyperbolic 4–manifolds with given signature*, in progress.

[12] D. D. Long, A. W. Reid, *On the geometric boundaries of hyperbolic 4–manifolds*, Geom. Topol. **4** (2000), 171–178.

[13] B. Martelli, *Hyperbolic four-manifolds*, in "Handbook of group actions Vol. III", Adv. Lect. Math. **40** (2018), 37–58.

[14] B. Martelli, *Hyperbolic three-manifolds that embed geodesically*, `arXiv:1510.06325`.

[15] D. B. McReynolds, A. W. Reid, M. Stover, *Collisions at infinity in hyperbolic manifolds*, Math. Proc. Cambridge Phil. Soc. **155** (2013), 459–463.

[16] M. Q. Ouyang, *Geometric invariants for Seifert fibred 3–manifolds*, Trans. Amer. Math. Soc. **346** (1994), 641–659.

[17] J. G. Ratcliffe, "Foundations of Hyperbolic Manifolds", Graduate Texts in Mathematics **149**, Springer (1994).

[18] J. G. Ratcliffe, S. T. Tschantz, *The volume spectrum of hyperbolic 4–manifolds*, Experiment. Math **9** (2000), 101–125.

[19] J. G. Ratcliffe, S. T. Tschantz, *Hyperbolic 24–cell 4–manifolds with one cusp*, Experiment. Math (2021), online first; `arXiv:2004.07284`.

[20] A. I. Stipsicz, The geography problem of 4–manifolds with various structures. Acta Math. Hungarica **87** (2000), 267–278.

Institut de Mathématiques, Université de Neuchâtel, Rue Emile-Argand 11, 2000 Neuchâtel, Suisse / Switzerland

Email address: `kolpakov dot alexander at gmail dot com`

Section de Mathématiques, Université de Genève, Rue du Conseil-Général 7-9, 1205 Genève, Suisse / Switzerland

Email address: `stefano dot riolo at unige dot ch`

Department of Mathematics, Vanderbilt University, 1326 Stevenson Center Ln, Nashville, TN 37212, U.S.A.

Email address: `steven dot tschantz at vanderbilt dot edu`