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CONDUCTING FLAT DROPS IN A CONFINING POTENTIAL

CYRILL B. MURATOV, MATTEO NOVAGA, AND BERARDO RUFFINI

ABSTRACT. We study a geometric variational problem arising from modeling two-dimensional charged drops of a perfectly conducting liquid in the presence of an external potential. We characterize the semicontinuous envelope of the energy in terms of a parameter measuring the relative strength of the Coulomb interaction. As a consequence, when the potential is confining and the Coulomb repulsion strength is below a critical value, we show existence and partial regularity of volume-constrained minimizers. We also derive the Euler–Lagrange equation satisfied by regular critical points, expressing the first variation of the Coulombic energy in terms of the normal $\frac{1}{2}$ -derivative of the capacitary potential.

Keywords: geometric variational problems, Coulombic energy, relaxation, fractional PDEs
Mathematics Subject Classification (2010): Primary 49Q10; Secondary 49J45, 31A15

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1. INTRODUCTION

This paper is concerned with a geometric variational problem modeling charged liquid drops in two space dimensions, whose study was initiated in [28]. The problem in question arises in the studies of electrified liquids, and one of its main features is that the Coulombic repulsion of charges competes with the the cohesive action of surface tension and tends to destabilize the liquid drop [12, 31, 35], an effect that is used in many concrete applications (see, e.g., [3, 6, 17]). From a mathematical point of view, this problem is interesting due to the competition between short-range attractive and long-range repulsive forces that produces non-trivial energy minimizing configurations and even nonexistence of minimizers when the total charge is large enough (for an overview, see [7]). The original model in three dimensions was proposed by Lord Rayleigh [31] and later investigated by many authors (see, for example, [4, 5, 9, 14, 16, 19, 20, 27, 35]; this list is not meant to be exhaustive).

In mathematical terminology, we are interested in the properties of the energy

$$E_\lambda(\Omega) := \mathcal{H}^1(\partial\Omega) + \lambda \mathcal{I}_1(\Omega) + \int_\Omega g(x) dx, \quad (1.1)$$

where $\Omega \subset \mathbb{R}^2$ is a compact set with smooth boundary and prescribed area $|\Omega| = m$,

$$\mathcal{I}_1(\Omega) := \inf_{\mu \in \mathcal{P}(\Omega)} \int_\Omega \int_\Omega \frac{d\mu(x) d\mu(y)}{|x - y|}, \quad (1.2)$$

where $\mathcal{P}(\Omega)$ is the space of probability measures supported on Ω , and g is a continuous function. The function $\mathcal{I}_1(\Omega)$ is often referred to as the 1-Riesz capacitary energy of Ω , and the right-hand side of (1.2) admits a unique minimizer μ_Ω , which is called the *equilibrium measure* of Ω [22]. Physically, the terms in (1.1) are, in the order of appearance: the excess surface energy of a flat drop, the self-interaction Coulombic energy of a perfect conductor carrying a fixed charge, and the effect of an external potential. The first term in (1.1) acts as a cohesive term. In contrast, the second term is a capacitary term due to the presence of a charge and acts on the drop as a repulsive term. The parameter $\lambda > 0$ measures the relative strength of Coulombic repulsion. We refer to [28] for a more comprehensive derivation of the two-dimensional model, as well as for a deeper physical background.

A minimization problem for (1.1) must take into account the fine balance that exists between the surface and the capacitary term [28]. A rough prediction of the behavior of minimizers, when they exist, is that if λ is big enough, then the drop will tend to be unstable, possibly leading to absence of a minimizer at all, while if λ is small, the dominant term is the surface one, leading to existence and stability of energy minimizing drops in a suitable class of sets. One of the purposes of this paper is to make the above prediction precise.

We point out that the energy above is a particular case of the more general energy

$$E_{\lambda,\alpha,N}(\Omega) := \mathcal{H}^{N-1}(\partial\Omega) + \lambda \mathcal{I}_\alpha(\Omega) + \int_\Omega g(x) dx, \quad \mathcal{I}_\alpha(\Omega) = \inf_{\mu \in \mathcal{P}(\Omega)} \int_\Omega \int_\Omega \frac{d\mu(x) d\mu(y)}{|x - y|^\alpha}, \quad (1.3)$$

where $\Omega \subset \mathbb{R}^N$ is a compact set with smooth boundary and with prescribed Lebesgue measure $|\Omega| = m$, and $\alpha \in (0, N)$. For $g \equiv 0$, some mathematical analysis of the minimization problem associated with (1.3) has been carried out in [19, 20], where it was shown that the problem is ill-posed for $\alpha < N - 1$. Indeed, the nonlocal term $\mathcal{I}_\alpha(\Omega)$ is finite whenever the Hausdorff dimension of a compact set Ω is greater than $N - \alpha$. On the other hand, the Hausdorff measure \mathcal{H}^{N-1} is trivially null on sets whose Hausdorff dimension is less than $N - 1$. Thus, whenever a positive gap between $N - \alpha$ and $N - 1$ occurs, it is possible to construct sets with \mathcal{I}_α positive and finite, but zero \mathcal{H}^{N-1} -measure, ensuing non-existence of minimizers [19]. The existence of a minimizer for (1.3) in the case $g = 0$ and $\alpha \geq N - 1$ is still open, except in the borderline case $N = 2$ and $\alpha = 1$ (see [28]). In this latter case, we showed that there exists an explicit threshold $\lambda = \lambda_c(m)$, where

$$\lambda_c(m) := \frac{4m}{\pi}, \quad (1.4)$$

such that for $\lambda > \lambda_c(m)$ no minimizer exists, while for $\lambda \leq \lambda_c(m)$ the only minimizer is a ball of measure m .

In this paper we address the question of existence and qualitative properties of minimizers of (1.3) for $N = 2$ and $\alpha = 1$. To that aim, in Theorem 1 we characterize the lower semicontinuous envelope of the energy E_λ with respect to the L^1 topology. As a corollary, we show that the energy E_λ is lower semicontinuous as long as λ is below the precise threshold

$\lambda_c(m)$, which is the same as the one for the case $g \equiv 0$. Then in Theorem 3 we prove, under a suitable coercivity assumption on g , the existence of volume-constrained minimizers for E_λ , as long as $\lambda \leq \lambda_c(m)$. Furthermore, in Theorem 4 we obtain density estimates and finiteness of the number of connected components of minimizers. Building on these partial regularity results, in Theorem 6 we consider the asymptotic regime $\lambda, m \rightarrow 0$, with $\limsup(\lambda/\lambda_c(m)) < 1$. In this limit the potential term is of lower order, and we show that minimizers, suitably rescaled, tend to a ball, which is the unique minimizer when $g = 0$ [28]. Finally, in Theorem 7 we compute the first variation of \mathcal{I}_1 and, as a consequence, we derive the Euler–Lagrange equation of the functional E_λ , for sufficiently smooth sets.

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2. STATEMENT OF THE MAIN RESULTS

As was mentioned earlier, the main difficulty in showing existence of minimizers for the variational problems above is that adding a surface term to a nonlocal capacitary term typically leads to an ill-posed problem. The strategy adopted in [28] to study the minimizers of (1.1) with $g = 0$ was to show directly a lower bound on the energy, given by that of a single ball, using some concentration compactness tools and some fine properties of the theory of convex bodies in dimension two. The presence of the bulk energy in (1.1) precludes application of these techniques.

The strategy of this paper is different: We first characterize the lower semicontinuous envelope of the functional E_λ , in a class of sets which includes compact sets with smooth boundary. Its explicit expression allows us to state that for certain values of λ , the energy E_λ is lower semicontinuous with respect to the L^1 convergence. To state the main results of the paper, we introduce some notation. Given $m > 0$, we denote by \mathcal{A}_m the class of all measurable subsets of \mathbb{R}^2 of measure m :

$$\mathcal{A}_m := \{ \Omega \subset \mathbb{R}^2 : |\Omega| = m \}. \quad (2.1)$$

We then introduce the families of sets

$$\mathcal{S}_m := \{ \Omega \in \mathcal{A}_m : \Omega \text{ compact, } \partial\Omega \text{ smooth} \}, \quad (2.2)$$

$$\mathcal{K}_m := \{ \Omega \in \mathcal{A}_m : \Omega \text{ compact, } \mathcal{H}^1(\partial\Omega) < +\infty \}. \quad (2.3)$$

We can extend the functional E_λ defined in (1.1) over \mathcal{S}_m to the whole of \mathcal{K}_m by setting

$$E_\lambda(\Omega) := P(\Omega) + \lambda \mathcal{I}_1(\Omega) + \int_{\Omega} g(x) dx, \quad \Omega \in \mathcal{K}_m, \quad (2.4)$$

where $P(\Omega)$ denotes the De Giorgi perimeter of Ω , defined as

$$P(\Omega) := \sup \left\{ \int_{\Omega} \operatorname{div} \phi dx : \phi \in C_c^1(\mathbb{R}^2; \mathbb{R}^2), \|\phi\|_{L^\infty(\mathbb{R}^2)} \leq 1 \right\}, \quad (2.5)$$

which coincides with $\mathcal{H}^1(\partial\Omega)$ if $\Omega \in \mathcal{S}_m$. Given an open set $A \subset \mathbb{R}^2$, we also define the perimeter of Ω in A as

$$P(\Omega; A) := \sup \left\{ \int_{\Omega \cap A} \operatorname{div} \phi \, dx : \phi \in C_c^1(A; \mathbb{R}^2), \|\phi\|_{L^\infty(A)} \leq 1 \right\}, \quad (2.6)$$

so that, in particular, $P(\Omega) = P(\Omega; \mathbb{R}^2)$.

For $\Omega \in \mathcal{A}_m$ we introduce the L^1 -relaxed energy for E_λ restricted to \mathcal{S}_m :

$$\overline{E}_\lambda(\Omega) := \inf_{\Omega_n \in \mathcal{S}_m, |\Omega_n \Delta \Omega| \rightarrow 0} \liminf_{n \rightarrow \infty} E_\lambda(\Omega_n). \quad (2.7)$$

We observe that, as a consequence of Proposition 14 and Corollary 15 in the following section, we can equivalently define \overline{E}_λ starting from sets $\Omega_n \in \mathcal{K}_m$ in (2.7), that is, there holds

$$\overline{E}_\lambda(\Omega) = \inf_{\Omega_n \in \mathcal{K}_m, |\Omega_n \Delta \Omega| \rightarrow 0} \liminf_{n \rightarrow \infty} E_\lambda(\Omega_n). \quad (2.8)$$

Our first result below provides an explicit characterization of the relaxed energy for sets in \mathcal{K}_m .

Theorem 1. *Let g be a continuous function bounded from below and let $m > 0$. Then for any $\Omega \in \mathcal{K}_m$ we have $\overline{E}_\lambda(\Omega) = \mathcal{E}_\lambda(\Omega)$, where*

$$\mathcal{E}_\lambda(\Omega) := \begin{cases} E_\lambda(\Omega) & \text{if } \lambda \leq \lambda_\Omega, \\ E_{\lambda_\Omega}(\Omega) + 2\pi(\sqrt{\lambda} - \sqrt{\lambda_\Omega}) & \text{if } \lambda > \lambda_\Omega, \end{cases} \quad (2.9)$$

and

$$\lambda_\Omega := \left(\frac{\pi}{\mathcal{I}_1(\Omega)} \right)^2. \quad (2.10)$$

In particular, E_λ is lower semicontinuous on \mathcal{K}_m with respect to the L^1 -convergence if and only if $\lambda \leq \lambda_c(m)$.

We recall that the quantity $\lambda_c(m)$ is defined in (1.4).

Note that as can be easily seen from the definition of λ_Ω , we always have $E_\lambda(\Omega) \geq E_{\lambda_\Omega}(\Omega) + 2\pi(\sqrt{\lambda} - \sqrt{\lambda_\Omega})$ for all $\lambda > 0$. Therefore, the result of Theorem 1 may be interpreted as follows: either it is energetically convenient to distribute all the charges over the set Ω or it is favorable to send some excess charge off to infinity. More precisely, for a given set Ω such that $\lambda > \lambda_\Omega$ it is possible to find a sequence of sets converging to Ω in the L^1 sense that contain vanishing parts with positive capacitary energy. In particular, the vanishing parts contribute a finite amount of energy to the limit, which is a non-trivial property of the considered problem.

The above result implies existence of minimizers for \overline{E}_λ in \mathcal{A}_m , as long as we require the coercivity and the local Lipschitz continuity of the function g .

Definition 2. *We say that a function $g : \mathbb{R}^2 \rightarrow \mathbb{R}$ is coercive if*

$$\lim_{|x| \rightarrow +\infty} g(x) = +\infty, \quad (2.11)$$

Furthermore, we define the class of functions \mathcal{G} as follows:

$$\mathcal{G} := \{g : \mathbb{R}^2 \rightarrow [0, +\infty) : g \text{ is locally Lipschitz continuous and coercive}\}. \quad (2.12)$$

Note that the assumption of positivity of g in (2.12) is not essential and may be replaced by boundedness of g from below. For this class of functions, which represent the effect of confinement by an external potential g , we have the following existence result.

Theorem 3. *Let $m > 0$, let $\lambda < \lambda_c(m)$ and let $g \in \mathcal{G}$. Then there exists a minimizer Ω_λ for E_λ over all sets in \mathcal{K}_m .*

We stress that the existence result stated in Theorem 3 is not a direct consequence of Theorem 1, the reason being that the class \mathcal{K}_m is not closed under L^1 -convergence, and is in fact one of the main results of this paper.

Given $\Omega \in \mathcal{K}_m$, we let Ω^+ be defined as

$$\Omega^+ := \{x \in \Omega : |\Omega \cap B_r(x)| > 0 \text{ for all } r > 0\}. \quad (2.13)$$

Notice that Ω^+ is a closed set. Indeed, recalling that Ω is closed we have that $x \in (\Omega^+)^c$ if and only if there exists $r > 0$ such that $|\Omega \cap B_r(x)| = 0$. Then, for every $y \in B_r(x)$ there holds $|\Omega \cap B_{r-|y-x|}(y)| = 0$, hence $y \in (\Omega^+)^c$, that is, $(\Omega^+)^c$ is open and Ω^+ is closed. Furthermore, if $\Omega \in \mathcal{K}_m$, we have $\Omega^+ \subset \Omega$ and $\Omega \setminus \Omega^+ = \{x \in \Omega : |\Omega \cap B_r(x)| = 0 \text{ for some } r > 0\} \subset \partial\Omega$, so that

$$\mathcal{H}^1(\Omega \setminus \Omega^+) \leq \mathcal{H}^1(\partial\Omega) < +\infty. \quad (2.14)$$

As a consequence we get $|\Omega| = |\Omega^+|$, $P(\Omega) = P(\Omega^+)$. Moreover, since the Hausdorff dimension of $\Omega \setminus \Omega^+$ is at most 1, then $\mathcal{I}_1(\Omega) = \mathcal{I}_1(\Omega^+)$ (see Lemma 10 below). Therefore $E_\lambda(\Omega) = E_\lambda(\Omega^+)$, and Ω is a minimizer of E_λ if and only if Ω^+ is a minimizer. We observe that Ω^+ is a representative of Ω which is in general more regular, and for which we can show density estimates which do not necessarily hold for Ω itself.

We now state a partial regularity result for the minimizers given in Theorem 3.

Theorem 4. *Let $m > 0$, $\lambda < \lambda_c(m)$ and $g \in \mathcal{G}$. Let also Ω_λ be a minimizer of E_λ over \mathcal{K}_m . Then there exist $c > 0$ universal and $r_0 > 0$ depending only on m , λ and g such that for every $0 < r \leq r_0$ and every $x \in \partial\Omega_\lambda^+$ there holds*

$$|\Omega_\lambda \cap B_r(x)| \geq c \left(1 - \frac{\lambda}{\lambda_c(m)}\right)^2 r^2 \quad \text{and} \quad |\Omega_\lambda^c \cap B_r(x)| \geq c \left(1 - \frac{\lambda}{\lambda_c(m)}\right)^2 r^2. \quad (2.15)$$

Furthermore, both Ω_λ and Ω_λ^c have a finite number of indecomposable components in the sense of [1, Section 4].

Remark 5. From Theorem 4 and [25, Theorem II.5.14] it follows that

$$\mathcal{H}^1(\partial\Omega_\lambda^+) = P(\Omega_\lambda^+) = P(\Omega_\lambda). \quad (2.16)$$

Therefore, the set Ω_λ^+ also minimizes the energy E_λ as defined in (1.1), among all sets in \mathcal{K}_m .

The semicontinuity of E_λ allows us to get existence of minimizers for $\lambda < \lambda_c(m)$, but we cannot say much about their qualitative shape, besides the partial regularity result given in Theorem 4. On the other hand, for m sufficiently small and λ small relative to $\lambda_c(m)$ we can show that the minimizers become close to a single ball of mass m located at a minimum of g .

Theorem 6. *Let $g \in \mathcal{G}$ and let $m_k, \lambda_k > 0$, $k \in \mathbb{N}$, be two sequences such that*

$$\lim_{k \rightarrow +\infty} m_k = 0 \quad \text{and} \quad \limsup_{k \rightarrow +\infty} \frac{\lambda_k}{\lambda_c(m_k)} < 1. \quad (2.17)$$

Then the following assertions are true:

- (1) For every k large enough there exists a minimizer Ω_k of E_{λ_k} over \mathcal{K}_{m_k} .

- (2) As $k \rightarrow \infty$, there exists a bounded sequence $(x_k) \in \mathbb{R}^2$ such that the translated and rescaled minimizers $\left(\frac{\pi}{m_k}\right)^{\frac{1}{2}} (\Omega_k - x_k)$ converge to $B_1(0)$ in the Hausdorff distance.
- (3) If x_0 is a cluster point of (x_k) , then $x_0 \in \operatorname{argmin} g$.

We note that in the local setting, i.e., when $\lambda = 0$, the result in Theorem 6 was obtained by Figalli and Maggi in [13], who in fact also obtained strong quantitative estimates of the rate of convergence of these minimizers to balls in this perimeter-dominated regime. This is made possible in the context of local isoperimetric problems with confining potentials by an extensive use of the regularity theory available for such problems [25]. In contrast, minimizers of our problem fail to be quasi-minimizers of the perimeter and, therefore, their $C^{1,\alpha}$ -regularity is a difficult open question. The proof of Theorem 6, which extends some results of [13] to the nonlocal setting involving capacitary energies relies on the arguments used to obtain partial regularity of the minimizers in the subcritical regime in Theorem 4. These estimates are also the first step towards the full regularity theory of the minimizers of E_λ .

Finally, we derive the Euler–Lagrange equation for the energy E_λ under some smoothness assumptions on the shape of the minimizer. The main issue here is to compute the first variation of the functional $\mathcal{I}_1(\Omega)$ with respect to the deformations of the set Ω . To that end, given a compact set Ω with a sufficiently smooth boundary, we introduce the potential function

$$v_\Omega(x) := \int_\Omega \frac{d\mu_\Omega(y)}{|x-y|}, \quad (2.18)$$

where μ_Ω is the equilibrium measure of Ω minimizing \mathcal{I}_1 . The normal $\frac{1}{2}$ -derivative of the potential of v_Ω at the boundary of Ω is then defined as

$$\partial_\nu^{1/2} v_\Omega(x) := \lim_{s \rightarrow 0^+} \frac{v_\Omega(x + s\nu(x)) - v_\Omega(x)}{s^{1/2}}, \quad (2.19)$$

where $x \in \partial\Omega$ and $\nu(x)$ is the outward normal vector to $\partial\Omega$ at x .

Theorem 7. *Let Ω be a compact set with boundary of class C^2 , let $\zeta \in C^\infty(\mathbb{R}^2, \mathbb{R}^2)$, and let $(\Phi_t)_{t \in \mathbb{R}}$ be a smooth family of diffeomorphisms of the plane satisfying $\Phi_0 = \operatorname{Id}$ and $\frac{d}{dt} \Phi_t|_{t=0} = \zeta$. Then the normal $\frac{1}{2}$ -derivative $\partial_\nu^{1/2} v_\Omega$ of the potential v_Ω from (2.18) is well-defined and belongs to $C^\beta(\partial\Omega)$ for any $\beta \in (0, 1/2)$. Moreover, we have*

$$\left. \frac{d}{dt} \mathcal{I}_1(\Phi_t(\Omega)) \right|_{t=0} = -\frac{1}{8} \int_{\partial\Omega} (\partial_\nu^{1/2} v_\Omega(x))^2 \zeta(x) \cdot \nu(x) d\mathcal{H}^1(x). \quad (2.20)$$

As a consequence, the Euler–Lagrange equation for a critical point $\Omega \in \mathcal{A}_m$ of E_λ satisfying the above smoothness conditions is

$$\kappa - \frac{\lambda}{8} (\partial_\nu^{1/2} v_\Omega)^2 + g = p \quad \text{on } \partial\Omega, \quad (2.21)$$

where κ is the curvature of $\partial\Omega$ (positive if Ω is convex) and $p \in \mathbb{R}$ is a Lagrange multiplier due to the mass constraint.

We note that the result in Theorem 7 relies on recent regularity estimates for fractional elliptic PDEs obtained in [10, 32, 33]. It is also closely related to the result of Dalibard and Gérard-Varet [8] on the shape derivative of a fractional shape optimization problem.

3. PRELIMINARIES: CAPACITARY ESTIMATES, PERIMETERS AND CONNECTED COMPONENTS

In this section we give some preliminary definitions and results about the functionals \mathcal{I}_1 and P that define \mathcal{E}_λ . We begin with an important remark about the necessity of introducing the classes \mathcal{K}_m and \mathcal{S}_m .

Remark 8. As mentioned in the Introduction, we have to choose carefully the admissible class for the minimization of E_λ . A natural choice would be minimizing E_λ in the class of finite perimeter sets. However, in this class the functional E_λ is never lower semicontinuous. Indeed, given a set $\Omega \subset \mathbb{R}^2$ and $\varepsilon > 0$ it is possible to find another set Ω_ε , with $|\Omega \Delta \Omega_\varepsilon| = 0$ and $P(\Omega) = P(\Omega_\varepsilon)$, but with $\mathcal{I}_1(\Omega_\varepsilon) < \varepsilon$ (see the Introduction in [28]). Such a construction cannot be accomplished in \mathcal{K}_m . In this sense, \mathcal{K}_m is the largest class in which it is meaningful to consider the minimization of E_λ .

In [28, Theorems 1 and 2] uniform bounds on $E_\lambda(\Omega)$ were proved for $g = 0$, which are attained on balls. These estimates will play a crucial role in the proof of Theorem 1, and we recall them in the following lemma.

Lemma 9. *For any $\Omega \in \mathcal{K}_m$ there holds*

$$\mathcal{H}^1(\partial\Omega) + \lambda\mathcal{I}_1(\Omega) \geq 2\pi\sqrt{\lambda}. \quad (3.1)$$

Moreover, if $\lambda \leq \lambda_c(m)$ there also holds

$$\mathcal{H}^1(\partial\Omega) + \lambda\mathcal{I}_1(\Omega) \geq \mathcal{H}^1(\partial B_r(x_0)) + \lambda\mathcal{I}_1(B_r(x_0)), \quad (3.2)$$

where $r = \sqrt{m/\pi}$ and $x_0 \in \mathbb{R}^2$, i.e., $B_r(x_0)$ is a ball of measure m , and the equality holds if and only if $\Omega = B_r(x_0)$ for some $x_0 \in \mathbb{R}^2$.

We now recall some basic facts about the functional \mathcal{I}_1 .

Lemma 10. [28, Lemma 1] *Let $\Omega \subset \mathbb{R}^2$ be a compact set such that $|\Omega| > 0$ and $\mathcal{H}^1(\partial\Omega) < +\infty$. Then there exists a unique probability measure μ over \mathbb{R}^2 supported on Ω such that*

$$\mathcal{I}_1(\Omega) = \int_{\Omega} \int_{\Omega} \frac{d\mu(x)d\mu(y)}{|x-y|}. \quad (3.3)$$

Furthermore, $\mu(\partial\Omega) = 0$, and we have $d\mu(x) = \rho(x)dx$ for some $\rho \in L^1(\Omega)$ satisfying $0 < \rho(x) \leq C/\text{dist}(x, \partial\Omega)$ for some constant $C > 0$ and all $x \in \text{int}(\Omega)$.

Another useful estimate is the following:

Lemma 11. [28, Lemma 2] *Let $\Omega_1, \Omega_2 \subset \mathbb{R}^2$ be compact sets with positive measure such that $\mathcal{H}^1(\partial\Omega_i) < +\infty$ for $i \in \{1, 2\}$, and $|\Omega_1 \cap \Omega_2| = 0$. Then, for all $t \in [0, 1]$ there holds*

$$\mathcal{I}_1(\Omega_1 \cup \Omega_2) \leq t^2\mathcal{I}_1(\Omega_1) + (1-t)^2\mathcal{I}_1(\Omega_2) + \frac{2t(1-t)}{\text{dist}(\Omega_1, \Omega_2)}, \quad (3.4)$$

and there exists $\bar{t} \in (0, 1)$ such that

$$\mathcal{I}_1(\Omega_1 \cup \Omega_2) > \bar{t}^2\mathcal{I}_1(\Omega_1) + (1-\bar{t})^2\mathcal{I}_1(\Omega_2). \quad (3.5)$$

From [19, Section 2] (see also [22]) we have that

$$\mathcal{I}_1(\Omega) = \frac{2\pi}{\text{cap}_1(\Omega)}, \quad (3.6)$$

whenever Ω is a compact set, where $\text{cap}_1(\Omega)$ is the $\frac{1}{2}$ -capacity of Ω defined as

$$\text{cap}_1(\Omega) := \inf \left\{ \|u\|_{\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)}^2 : u \in C_c^1(\mathbb{R}^2), \quad u \geq \chi_\Omega \right\}, \quad (3.7)$$

and

$$\|u\|_{\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)}^2 := \frac{1}{4\pi} \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \frac{|u(x) - u(y)|^2}{|x - y|^3} dx dy \quad (3.8)$$

is the Gagliardo norm of the homogeneous fractional Sobolev space obtained via completion of $C_c^\infty(\mathbb{R}^2)$ with respect to that norm [11, 24]. For the sake of completeness, we provide a short justification of this fact: Let $v_\Omega := \mu_\Omega * |\cdot|^{-1}$ be the potential of Ω , where μ_Ω is the equilibrium measure for Ω . Then v_Ω satisfies (see, for instance, [19, Lemma 2.11])

$$\begin{cases} (-\Delta)^{\frac{1}{2}} v_\Omega = 0 & \text{on } \Omega^c \\ v_\Omega = \mathcal{I}_1(\Omega) & \text{a.e. on } \Omega \\ \lim_{|x| \rightarrow +\infty} v_\Omega(x) = 0. \end{cases} \quad (3.9)$$

Furthermore,

$$u_\Omega := \mathcal{I}_1^{-1}(\Omega) v_\Omega \quad (3.10)$$

is the $\frac{1}{2}$ -capacitary potential of Ω attaining the infimum in (3.7). In particular, by [11, Proposition 3.4] we have

$$\mathcal{I}_1(\Omega) = \int_{\mathbb{R}^2} v_\Omega d\mu_\Omega = \frac{1}{2\pi} \|v_\Omega\|_{\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)}^2, \quad (3.11)$$

so that

$$\text{cap}_1(\Omega) = \|u_\Omega\|_{\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)}^2 = \frac{\|v_\Omega\|_{\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)}^2}{\mathcal{I}_1(\Omega)^2} = \frac{2\pi}{\mathcal{I}_1(\Omega)}. \quad (3.12)$$

The link with the classical Newtonian capacity $\text{cap}(\Omega)$, defined for $\Omega \subset \mathbb{R}^3$ as

$$\text{cap}(\Omega) := \inf \left\{ \|\nabla u\|_{L^2(\mathbb{R}^3)}^2 : u \in C_c^1(\mathbb{R}^3), \quad u \geq \chi_\Omega \right\}, \quad (3.13)$$

is given by the equality

$$\text{cap}_1(\Omega) = 2 \text{cap}(\Omega \times \{0\}), \quad (3.14)$$

for any compact set $\Omega \subset \mathbb{R}^2$ [23, Theorem 11.16]. Finally, we recall that $\text{cap}_1(\Omega) = 0$ if $\mathcal{H}^1(\Omega) < \infty$ (see [22, Theorem 3.14]).

We note that a priori the functional \mathcal{I}_1 is not lower semicontinuous with respect to L^1 convergence. However, given a compact set Ω , \mathcal{I}_1 is semicontinuous along a specific family of sets, namely sets of the form

$$\Omega^\delta := \{x \in \mathbb{R}^2 : \text{dist}(x, \Omega) \leq \delta\}, \quad (3.15)$$

for $\delta \rightarrow 0$. This is formalized in the next lemma, and then exploited in Proposition 16.

Lemma 12. *Let Ω be a compact subset of \mathbb{R}^2 and let $(\delta_n)_{n \in \mathbb{N}} \subset [0, +\infty)$ and $\bar{\delta} \in [0, +\infty)$ be such that $\delta_n \rightarrow \bar{\delta}$ as $n \rightarrow \infty$. Then*

$$\mathcal{I}_1(\Omega^{\bar{\delta}}) \leq \liminf_{n \rightarrow +\infty} \mathcal{I}_1(\Omega^{\delta_n}). \quad (3.16)$$

Moreover, if $\delta_n \searrow \bar{\delta}$ there holds

$$\mathcal{I}_1(\Omega^{\bar{\delta}}) = \lim_{n \rightarrow +\infty} \mathcal{I}_1(\Omega^{\delta_n}). \quad (3.17)$$

Proof. We can suppose that $(\delta_n)_{n \in \mathbb{N}}$ is a monotone sequence. We have two cases: If $\delta_n \nearrow \bar{\delta}$, then $\delta_n \leq \bar{\delta}$ for any n and thus by the monotonicity of \mathcal{I}_1 with respect to set inclusions, we have that $\mathcal{I}_1(\Omega^{\delta_n}) \geq \mathcal{I}_1(\Omega^{\bar{\delta}})$ and the lower semicontinuity is proven.

We deal now with the case $\delta_n \searrow \bar{\delta}$. Let us fix $\varepsilon > 0$ and let $\varphi \in C_c^1(\mathbb{R}^2)$ be such that $\varphi > \chi_{\Omega^{\bar{\delta}}}$, and $\|\varphi\|_{\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)}^2 \leq \text{cap}_1(\Omega^{\bar{\delta}}) + \varepsilon$. Then, since $\{\varphi > 1\}$ is an open set which contains $\Omega^{\bar{\delta}}$, for n big enough (depending on ε) φ is also a test function for $\text{cap}_1(\Omega^{\delta_n})$, and we get

$$\text{cap}_1(\Omega^{\bar{\delta}}) \leq \text{cap}_1(\Omega^{\delta_n}) \leq \|\varphi\|_{\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)}^2 \leq \text{cap}_1(\Omega^{\bar{\delta}}) + \varepsilon. \quad (3.18)$$

Letting $\varepsilon \searrow 0$, we get the continuity of cap_1 and hence of \mathcal{I}_1 by (3.12). \square

We prove now a result which turns out to be very useful in the proof of the semicontinuity result in Theorem 1, as well as of the existence and regularity results in Theorems 3 and 4.

Lemma 13. *Let $\Omega = U \cup V$ with U and V compact sets of finite positive measure and such that $|U \cap V| = 0$. Then we have*

$$\mathcal{I}_1(\Omega) \geq \mathcal{I}_1(U) - \frac{\pi}{4|U|} P(V). \quad (3.19)$$

Proof. By Lemma 11 we have

$$\mathcal{I}_1(\Omega) \geq \min_{t \in [0,1]} \{t^2 \mathcal{I}_1(U) + (1-t)^2 \mathcal{I}_1(V)\}. \quad (3.20)$$

By computing the minimum on the right-hand side, we get

$$\mathcal{I}_1(\Omega) \geq \mathcal{I}_1(U) - \frac{\mathcal{I}_1^2(U)}{\mathcal{I}_1(U) + \mathcal{I}_1(V)} \geq \mathcal{I}_1(U) - \frac{\mathcal{I}_1^2(U)}{\mathcal{I}_1(V)}. \quad (3.21)$$

We recall that \mathcal{I}_1 is maximized by the ball among sets of fixed volume. Letting $B := B_{\sqrt{|U|/\pi}}(0)$, we then get that $|B| = |U|$ and [28, Lemma 3.3]

$$\mathcal{I}_1(U) \leq \mathcal{I}_1(B) = \frac{\pi^{\frac{3}{2}}}{2\sqrt{|U|}}. \quad (3.22)$$

Moreover, by [29, Corollary 3.2] the dilation invariant functional $\mathcal{F} := \mathcal{I}_1(\cdot)P(\cdot)$ is minimized by balls, and on a ball B_r it takes the value $\mathcal{I}_1(B_r)P(B_r) = \pi^2$, so that

$$\mathcal{I}_1(V) \geq \frac{\pi^2}{P(V)}. \quad (3.23)$$

We plug these two estimates into (3.21) to get

$$\mathcal{I}_1(\Omega) \geq \mathcal{I}_1(U) - \left(\frac{\pi^{\frac{3}{2}}}{2\sqrt{|U|}} \right)^2 \frac{P(V)}{\pi^2} = \mathcal{I}_1(U) - \frac{\pi}{4|U|} P(V), \quad (3.24)$$

which is the desired estimate. \square

In the proof of Theorem 3 we shall use some topological features of sets of finite perimeter in dimension two. Since these sets are defined in the L^1 -sense (as equivalence classes), it is not a priori immediate how to define what a connected component for a set of finite perimeter is. A suitable notion of connected components for sets of finite perimeter was introduced in [1]. Below we recall some of their main features that we shall use in the sequel.

Given $\Omega \in \mathcal{K}_m$, let $\mathring{\Omega}^M$ be its measure theoretic interior, namely:

$$\mathring{\Omega}^M := \left\{ x \in \mathbb{R}^2 : \lim_{r \rightarrow 0} \frac{|\Omega \cap B_r(x)|}{\pi r^2} = 1 \right\}. \quad (3.25)$$

Since $P(\mathring{\Omega}^M) = P(\Omega) = \mathcal{H}^1(\partial^M \Omega) \leq \mathcal{H}^1(\partial \Omega) < +\infty$, where $\partial^M \Omega$ is the essential boundary of Ω [25], the set $\mathring{\Omega}^M$ is a set of finite perimeter. Therefore, following [1], there exists an at most countable family of sets of finite perimeter Ω_i such that $\mathring{\Omega}^M = \left(\bigcup_i \mathring{\Omega}_i^M \right) \cup \Sigma$, with $\mathcal{H}^1(\Sigma) = 0$, where the sets $\mathring{\Omega}_i^M$ are the so-called *indecomposable components* of $\mathring{\Omega}^M$. In particular, the sets Ω_i admit unique representatives that are connected and satisfy the following properties:

- (i) $\mathcal{H}^1(\Omega_i \cap \Omega_j) = 0$ for $i \neq j$,
- (ii) $|\Omega| = \sum_i |\Omega_i|$,
- (iii) $P(\Omega) = \sum_i P(\Omega_i)$,
- (iv) $\Omega_i = \overline{\mathring{\Omega}_i^M}$.

Moreover, each set Ω_i is indecomposable in the sense that it cannot be further decomposed as above. We refer to these representatives of Ω_i as the *connected components* of Ω . We point out that this notion coincides with the standard notion of connected components in the following sense: if Ω has a regular boundary (Lipschitz continuous being enough) then the components Ω_i are the closures of the usual connected components of the interior of Ω .

Such a representation of Ω as a union of connected components allows us to convexify the components in order to decrease the energy. Indeed, for every $i \in \mathbb{N}$ there holds $\mathcal{I}_1(\Omega_i) \leq \mathcal{I}_1(\text{co}(\Omega_i))$ and $\mathcal{H}^1(\partial \text{co}(\Omega_i)) \leq \mathcal{H}^1(\partial \Omega_i)$, where $\text{co}(\Omega_i)$ denotes the convex envelope of the component Ω_i . This follows from the fact that $\Omega_i \subseteq \text{co}(\Omega_i)$, and that the outer boundary of a connected component can be parametrized by a Jordan curve of finite length (see [1, Section 8]). In addition, since $\partial \Omega$ is negligible with respect to the equilibrium measure for $\mathcal{I}_1(\Omega)$ by Lemma 10, we have $\mathcal{I}_1(\Omega) = \mathcal{I}_1(\mathring{\Omega}^M)$.

The next result shows that the relaxations of E_λ in \mathcal{S}_m and in \mathcal{K}_m coincide.

Proposition 14. *Given $\Omega \in \mathcal{K}_m$, there exists a sequence of sets $\Omega_n \in \mathcal{S}_m$ such that*

$$\lim_{n \rightarrow \infty} |\Omega_n \Delta \Omega| = 0 \quad \text{and} \quad \limsup_{n \rightarrow \infty} E_\lambda(\Omega_n) \leq E_\lambda(\Omega). \quad (3.26)$$

Proof. Assume first that $P(\Omega) = \mathcal{H}^1(\partial \Omega)$. Then by [34, Theorem 1.1] applied to $B_R(0) \setminus \Omega$, for $R > 0$ big enough there exists a sequence of compact sets $\tilde{\Omega}_n$ with smooth boundaries such that $\tilde{\Omega}_n \supset \Omega$, $|\tilde{\Omega}_n \Delta \Omega| \rightarrow 0$ and $P(\tilde{\Omega}_n) \rightarrow P(\Omega)$ as $n \rightarrow \infty$. Furthermore, by monotonicity of \mathcal{I}_1 with respect to set inclusions we have $\mathcal{I}_1(\tilde{\Omega}_n) \leq \mathcal{I}_1(\Omega)$. Now, we define $\Omega_n := (m/|\tilde{\Omega}_n|)^{1/2} \tilde{\Omega}_n \in \mathcal{S}_m$, and in view of the fact that $|\tilde{\Omega}_n| \rightarrow m$ as $n \rightarrow \infty$ we obtain the result.

Let us now consider the general case. By [1, Corollary 1], there exists a sequence of sets $\Omega_n \in \mathcal{K}_m$ such that $\partial \Omega_n$ is a finite union of Jordan curves, and as $n \rightarrow \infty$ we have

$$|\Omega_n \Delta \Omega| \rightarrow 0, \quad P(\Omega_n) \rightarrow P(\Omega), \quad P(\Omega \setminus \Omega_n) \rightarrow 0. \quad (3.27)$$

In particular, $P(\Omega_n) = \mathcal{H}^1(\partial\Omega_n)$ for every $n \in \mathbb{N}$. Then by Lemma 13 it follows that

$$\mathcal{I}_1(\Omega_n) \leq \mathcal{I}_1(\Omega_n \cap \Omega) \leq \mathcal{I}_1(\Omega) + \omega_n, \quad (3.28)$$

with

$$\omega_n := \frac{\pi}{4|\Omega_n \cap \Omega|} P(\Omega \setminus \Omega_n) \rightarrow 0 \quad \text{as } n \rightarrow \infty, \quad (3.29)$$

so that

$$\limsup_{n \rightarrow +\infty} E_\lambda(\Omega_n) \leq E_\lambda(\Omega). \quad (3.30)$$

Applying now the approximation with regular sets to each set Ω_n , we conclude by a diagonal argument. \square

Proposition 14 yields the following characterization of the relaxed energy \overline{E}_λ .

Corollary 15. *For every $\Omega \in \mathcal{A}_m$ there holds*

$$\overline{E}_\lambda(\Omega) = \inf_{\Omega_n \in \mathcal{K}_m, |\Omega_n \Delta \Omega| \rightarrow 0} \liminf_{n \rightarrow \infty} E_\lambda(\Omega_n). \quad (3.31)$$

4. THE RELAXED ENERGY: PROOF OF THEOREM 1

In this section we prove Theorem 1. We divide the proof into first characterizing the relaxation of E_λ in Proposition 16 and then showing the semicontinuity of E_λ for $\lambda \leq \lambda_c(m)$ in Proposition 17.

Proposition 16. *For any $\Omega \in \mathcal{K}_m$, there holds*

$$\overline{E}_\lambda(\Omega) = \begin{cases} E_\lambda(\Omega) & \text{if } \lambda \leq \lambda_\Omega, \\ E_{\lambda_\Omega}(\Omega) + 2\pi(\sqrt{\lambda} - \sqrt{\lambda_\Omega}) & \text{if } \lambda > \lambda_\Omega, \end{cases} \quad (4.1)$$

where λ_Ω is defined in (2.10).

Proof. Let Ω_n be a sequence of sets in \mathcal{S}_m such that $|\Omega_n \Delta \Omega| \rightarrow 0$ as $n \rightarrow \infty$. For any $\delta > 0$ we let Ω^δ as in (3.15). Notice that there exists $\delta_0 > 0$ such that $\Omega^\delta \in \mathcal{K}_{m+\omega(\delta)}$, for any $\delta \leq \delta_0$, where $\omega(\delta) \rightarrow 0$ as $\delta \rightarrow 0$ by the monotone convergence theorem.

For any $n \in \mathbb{N}$ we let $\Omega_n(\delta) := \Omega_n \cap \Omega^\delta$ and $\tilde{\Omega}_n(\delta) := \tilde{\Omega}_n \setminus \Omega^\delta$. By [25, Section II.7.1], we have

$$P(\Omega_n) \geq P(\Omega_n; \text{int}(\Omega^\delta)) + P(\Omega_n; \mathbb{R}^2 \setminus \Omega^\delta) = P(\Omega_n(\delta)) + P(\tilde{\Omega}_n(\delta)) - 2\mathcal{H}^1(\Omega_n \cap \partial\Omega^\delta). \quad (4.2)$$

Notice that for any fixed $\delta \in (0, \delta_0)$, by Coarea Formula [25, Theorem 18.1] we also have

$$\int_0^\delta \mathcal{H}^1(\Omega_n \cap \partial\Omega^t) dt = |\Omega_n \cap (\Omega^\delta \setminus \Omega)| \leq |\Omega_n \Delta \Omega|, \quad (4.3)$$

Therefore we can choose $\delta_n \in (\delta/2, \delta)$ such that

$$\mathcal{H}^1(\Omega_n \cap \partial\Omega^{\delta_n}) \leq \frac{2|\Omega_n \Delta \Omega|}{\delta}. \quad (4.4)$$

Recalling (4.2) this gives

$$P(\Omega_n) \geq P(\Omega_n(\delta_n)) + P(\tilde{\Omega}_n(\delta_n)) - \omega_n^\delta, \quad (4.5)$$

where $\omega_n^\delta \leq \frac{4}{\delta} |\Omega_n \Delta \Omega|$. Up to a subsequence, we can assume that $\delta_n \rightarrow \bar{\delta}$ as $n \rightarrow \infty$ for some $\bar{\delta} \in [\delta/2, \delta]$. Moreover, we can choose δ_n such that $P(\tilde{\Omega}_n(\delta_n)) = \mathcal{H}^1(\partial\tilde{\Omega}_n(\delta_n))$ (see [26, Equation (68)]).

We now estimate the nonlocal term. Since $\Omega_n \subset \Omega_n(\delta_n) \cup \tilde{\Omega}_n(\delta_n)$, we have

$$\begin{aligned} \mathcal{I}_1(\Omega_n) &\geq \mathcal{I}_1(\Omega_n(\delta_n) \cup \tilde{\Omega}_n(\delta_n)) \\ &\geq \min_{t \in [0,1]} \left(t^2 \mathcal{I}_1(\Omega_n(\delta_n)) + (1-t)^2 \mathcal{I}_1(\tilde{\Omega}_n(\delta_n)) \right) \\ &\geq \min_{t \in [0,1]} \left(t^2 \mathcal{I}_1(\Omega^{\delta_n}) + (1-t)^2 \mathcal{I}_1(\tilde{\Omega}_n(\delta_n)) \right), \end{aligned} \quad (4.6)$$

where the second inequality follows from Lemma 11, while the third is due to the fact that $\Omega_n(\delta_n)$ is contained in Ω^{δ_n} and that \mathcal{I}_1 is decreasing with respect to set inclusions.

By Lemma 9 we have that

$$\mathcal{H}^1(\partial \tilde{\Omega}_n(\delta_n)) + \lambda(1-t)^2 \mathcal{I}_1(\tilde{\Omega}_n(\delta_n)) \geq 2\pi(1-t)\sqrt{\lambda}. \quad (4.7)$$

Thus, by combining (4.6) with (4.5), recalling that $P(\tilde{\Omega}_n(\delta_n)) = \mathcal{H}^1(\partial \tilde{\Omega}_n(\delta_n))$, we obtain

$$\begin{aligned} E_\lambda(\Omega_n) &\geq P(\Omega_n(\delta_n)) + \int_{\Omega_n} g \, dx - \omega_n^\delta + \mathcal{H}^1(\partial \tilde{\Omega}_n(\delta_n)) \\ &\quad + \lambda \min_{t \in [0,1]} \left(t^2 \mathcal{I}_1(\Omega^{\delta_n}) + (1-t)^2 \mathcal{I}_1(\tilde{\Omega}_n(\delta_n)) \right) \\ &\geq P(\Omega_n(\delta_n)) + \int_{\Omega_n} g \, dx - \omega_n^\delta + \min_{t \in [0,1]} \left(\lambda t^2 \mathcal{I}_1(\Omega^{\delta_n}) + 2\pi(1-t)\sqrt{\lambda} \right) \\ &= P(\Omega_n(\delta_n)) + \int_{\Omega_n} g \, dx - \omega_n^\delta + \begin{cases} 2\pi\sqrt{\lambda} - \frac{\pi^2}{\mathcal{I}_1(\Omega^{\delta_n})} & \text{if } \mathcal{I}_1(\Omega^{\delta_n}) > \frac{\pi}{\sqrt{\lambda}} \\ \lambda \mathcal{I}_1(\Omega^{\delta_n}) & \text{if } \mathcal{I}_1(\Omega^{\delta_n}) \leq \frac{\pi}{\sqrt{\lambda}} \end{cases}. \end{aligned} \quad (4.8)$$

Therefore, thanks to the lower semicontinuity of the perimeter with respect to the L^1 convergence (notice that $|\Omega_n(\delta_n)\Delta\Omega^{\bar{\delta}}| \rightarrow 0$ as $n \rightarrow +\infty$) and thanks to the semicontinuity of \mathcal{I}_1 in Lemma 12, in the limit as $n \rightarrow \infty$ we obtain

$$\liminf_{n \rightarrow \infty} E_\lambda(\Omega_n) \geq P(\Omega^{\bar{\delta}}) + \int_{\Omega} g \, dx + \begin{cases} 2\pi\sqrt{\lambda} - \frac{\pi^2}{\mathcal{I}_1(\Omega^{\bar{\delta}})} & \text{if } \mathcal{I}_1(\Omega^{\bar{\delta}}) > \frac{\pi}{\sqrt{\lambda}} \\ \lambda \mathcal{I}_1(\Omega^{\bar{\delta}}) & \text{if } \mathcal{I}_1(\Omega^{\bar{\delta}}) \leq \frac{\pi}{\sqrt{\lambda}} \end{cases}, \quad (4.9)$$

Letting now $\delta \rightarrow 0$ in (4.9), and again using that $\mathcal{I}_1(\Omega^{\bar{\delta}}) \rightarrow \mathcal{I}_1(\Omega)$ by Lemma 12, we finally get

$$\begin{aligned} \liminf_{n \rightarrow \infty} E_\lambda(\Omega_n) &\geq P(\Omega) + \int_{\Omega} g \, dx + \begin{cases} 2\pi\sqrt{\lambda} - \frac{\pi^2}{\mathcal{I}_1(\Omega)} & \text{if } \lambda > \lambda_\Omega \\ \lambda \mathcal{I}_1(\Omega) & \text{if } \lambda \leq \lambda_\Omega \end{cases} \\ &= \mathcal{E}_\lambda(\Omega), \end{aligned} \quad (4.10)$$

where $\mathcal{E}_\lambda(\Omega)$ is defined in (2.9).

We now have to show that there exists a sequence Ω_n in \mathcal{S}_m such that $|\Omega_n \Delta \Omega| \rightarrow 0$ as $n \rightarrow +\infty$ and

$$\limsup_{n \rightarrow \infty} E_\lambda(\Omega_n) \leq \mathcal{E}_\lambda(\Omega). \quad (4.11)$$

Recalling Corollary 15, it is enough to find a sequence Ω_n in \mathcal{K}_m with the desired properties.

If $\lambda \leq \lambda_\Omega$ we can take $\Omega_n := \Omega$ and there is nothing to prove. If $\lambda > \lambda_\Omega$ we let $R > 0$ such that $\Omega \subset B_{R/2}(0)$. Notice that, for all n large enough (depending on R) there exist n

points x_1, \dots, x_n in $B_{2R}(0) \setminus B_R(0)$ such that $|x_i - x_j| \geq R/\sqrt{n}$ for all $i \neq j$. We then take $\Omega_n := \rho_n \Omega \cup (\cup_{i=1}^n B_{r/n}(x_i))$, where

$$r := \frac{\sqrt{\lambda} - \sqrt{\lambda\Omega}}{2} \quad \text{and} \quad \rho_n := \sqrt{1 - \frac{\pi r^2}{m n}}. \quad (4.12)$$

Notice that with these choices of r and ρ_n we have that the sets $\rho_n \Omega$ and $B_{r/n}(x_i)$ are disjoint, $|\Omega_n| = m$ and

$$\text{dist}(\rho_n \Omega, \cup_{i=1}^n B_{r/n}(x_i)) \geq \frac{R}{2} - \frac{r}{n} \geq \frac{R}{4} \quad (4.13)$$

for all n large enough. Letting $t = \sqrt{\lambda\Omega/\lambda}$, by Lemma 11 we estimate

$$\begin{aligned} E_\lambda(\Omega_n) &\leq E_{\lambda t^2}(\rho_n \Omega) + E_{\lambda(1-t)^2}(\cup_{i=1}^n B_{r/n}(x_i)) + \frac{2t(1-t)\lambda}{\text{dist}(\rho_n \Omega, \cup_{i=1}^n B_{r/n}(x_i))} \\ &\leq E_{\lambda t^2}(\rho_n \Omega) + E_{\lambda(1-t)^2}(\cup_{i=1}^n B_{r/n}(x_i)) + \frac{2\lambda}{R} \\ &= E_{\lambda\Omega}(\rho_n \Omega) + E_{(\sqrt{\lambda} - \sqrt{\lambda\Omega})^2}(\cup_{i=1}^n B_{r/n}(x_i)) + \frac{2\lambda}{R}. \end{aligned} \quad (4.14)$$

Let now μ_i be the equilibrium measure for $B_{r/n}(x_i)$. Then $\frac{1}{n} \sum_{i=1}^n \mu_i$ is an admissible measure in the definition of $\mathcal{I}_1(\cup_i B_{r/n}(x_i))$, so that

$$\begin{aligned} \mathcal{I}_1(\cup_{i=1}^n B_{r/n}(x_i)) &\leq n \cdot \frac{1}{n^2} \mathcal{I}_1(B_{r/n}(x_1)) + \frac{1}{n^2} \sum_{i \neq j} \int_{B_{r/n}(x_i)} \int_{B_{r/n}(x_j)} \frac{d\mu_i(x) d\mu_j(y)}{|x-y|} \\ &\leq \frac{1}{n} \mathcal{I}_1(B_{r/n}(x_1)) + \frac{1}{n^2} \sum_{i \neq j} \frac{1}{|x_i - x_j| - \frac{2r}{n}} \\ &\leq \frac{1}{n} \mathcal{I}_1(B_{r/n}(x_1)) + \frac{2}{n^2} \sum_{i \neq j} \frac{1}{|x_i - x_j|}, \end{aligned} \quad (4.15)$$

for n large enough. Since for any $i = 1, \dots, n$ we have

$$\int_{B_{r/n}(x_i)} g(y) dy \leq \frac{\pi r^2}{n^2} \|g\|_{L^\infty(B_{2R}(0))}, \quad (4.16)$$

from (4.14) we obtain

$$\begin{aligned}
E_\lambda(\Omega_n) &\leq E_{\lambda_\Omega}(\rho_n\Omega) + nP(B_{r/n}(x_1)) + \frac{(\sqrt{\lambda} - \sqrt{\lambda_\Omega})^2}{n} \mathcal{I}_1(B_{r/n}(x_1)) + \frac{\pi r^2}{n} \|g\|_{L^\infty(B_{2R}(0))} \\
&\quad + \frac{2(\sqrt{\lambda} - \sqrt{\lambda_\Omega})^2}{n^2} \sum_{i \neq j} \frac{1}{|x_i - x_j|} + \frac{2\lambda}{R} \\
&= E_{\lambda_\Omega}(\rho_n\Omega) + 2\pi r + \frac{\pi}{2r} (\sqrt{\lambda} - \sqrt{\lambda_\Omega})^2 + \frac{\pi r^2}{n} \|g\|_{L^\infty(B_{2R}(0))} \\
&\quad + \frac{2(\sqrt{\lambda} - \sqrt{\lambda_\Omega})^2}{n^2} \sum_{i \neq j} \frac{1}{|x_i - x_j|} + \frac{2\lambda}{R} \\
&= E_{\lambda_\Omega}(\rho_n\Omega) + 2\pi(\sqrt{\lambda} - \sqrt{\lambda_\Omega}) + \frac{\pi(\sqrt{\lambda} - \sqrt{\lambda_\Omega})^2}{4n} \|g\|_{L^\infty(B_{2R}(0))} \\
&\quad + \frac{2(\sqrt{\lambda} - \sqrt{\lambda_\Omega})^2}{n^2} \sum_{i \neq j} \frac{1}{|x_i - x_j|} + \frac{2\lambda}{R},
\end{aligned} \tag{4.17}$$

where we used (4.12) and the fact that $\mathcal{I}_1(B_r) = \frac{\pi}{2r}$ (see [28, Equation (2.5)]). Notice that, since $|x_i - x_j| \geq R/\sqrt{n}$, we have

$$\sum_{i \neq j} \frac{1}{|x_i - x_j|} \leq \frac{Cn^2}{R},$$

for some universal constant $C > 0$ and n large enough depending only on R . Notice also that $\rho_n \rightarrow 1$ as $n \rightarrow \infty$, so that

$$\lim_{n \rightarrow \infty} E_{\lambda_\Omega}(\rho_n\Omega) = \lim_{n \rightarrow \infty} \left(\rho_n P(\Omega) + \lambda_\Omega \rho_n^{-1} \mathcal{I}_1(\Omega) + \int_{\rho_n\Omega} g(x) dx \right) = E_{\lambda_\Omega}(\Omega), \tag{4.18}$$

where in the last term we passed to the limit using $g \in \mathcal{G}$ and the Dominated Convergence Theorem. Sending $n \rightarrow \infty$ in (4.17) we then get

$$\limsup_{n \rightarrow \infty} E_\lambda(\Omega_n) \leq E_{\lambda_\Omega}(\Omega) + 2\pi(\sqrt{\lambda} - \sqrt{\lambda_\Omega}) + \frac{2\lambda + C(\sqrt{\lambda} - \sqrt{\lambda_\Omega})^2}{R}.$$

Sending now $R \rightarrow +\infty$, we eventually obtain (4.11) and this concludes the proof. \square

From Proposition 16 we get the following result:

Proposition 17. *The functional E_λ is lower semicontinuous in \mathcal{K}_m if and only if $\lambda \leq \lambda_c(m)$.*

Proof. Since $\mathcal{I}_1(\Omega) \leq \mathcal{I}_1(B_m)$ for any $\Omega \in \mathcal{K}_m$ (see [30, VII.7.3, p.157]), where B_m is a ball of measure m , we have that $\lambda_\Omega \geq \lambda_{B_m} = 4m/\pi$, with equality if and only if $\Omega = B_m$. Thus, if $\lambda \leq 4m/\pi$, the energy E_λ coincides with its lower semicontinuous envelope \overline{E}_λ by Proposition

16. On the other hand, if $\lambda > \lambda_{B_m}$ then $\overline{E}_\lambda(B_m) < E_\lambda(B_m)$. Indeed, recalling (2.10) we have

$$\begin{aligned} \frac{E_\lambda(B_m) - \overline{E}_\lambda(B_m)}{\sqrt{\lambda} - \sqrt{\lambda_{B_m}}} &= \left(\sqrt{\lambda} + \sqrt{\lambda_{B_m}} \right) \mathcal{I}_1(B_m) - 2\pi \\ &= \left(\sqrt{\lambda} + \frac{\pi}{\mathcal{I}_1(B_m)} \right) \mathcal{I}_1(B_m) - 2\pi \\ &= \sqrt{\lambda} \mathcal{I}_1(B_m) - \pi = \left(\sqrt{\lambda} - \sqrt{\lambda_{B_m}} \right) \mathcal{I}_1(B_m) > 0. \end{aligned}$$

In particular, E_λ is not lower semicontinuous for $\lambda > \lambda_{B_m}$. \square

Lastly, Theorem 1 directly follows from Proposition 16 and Proposition 17.

5. EXISTENCE OF MINIMIZERS: PROOF OF THEOREM 3

In this section we show existence of minimizers of E_λ under suitable assumptions on λ and on the function g . We start with a simple existence result for minimizers of the relaxed energy \overline{E}_λ .

Proposition 18. *Let $g \in \mathcal{G}$. Then \overline{E}_λ admits a minimizer Ω_λ over \mathcal{A}_m for every $\lambda > 0$.*

Proof. Let Ω_k be a minimizing sequence for $\overline{E}_\lambda(\Omega)$. Notice that $P(\Omega_k) < c$ for some positive constant c independent of k . Letting $\Omega_k^R := \Omega_k \cap B_R(0)$, we have $P(\Omega_k^R) \leq P(\Omega_k) + P(B_R(0)) \leq c + 2\pi R$. Thus, by the compactness of the immersion of $BV(B_R(0))$ into $L^1(B_R(0))$, applied to the sequence $\chi_{\Omega_k^R}$, we get that there exists a set $\Omega^R \subset B_R(0)$ such that $\chi_{\Omega_k^R} \rightarrow \chi_{\Omega^R}$ in L^1 , up to a (not relabeled) subsequence, as $k \rightarrow +\infty$. Sending $R \rightarrow +\infty$, by a diagonal argument we get that there exists $\Omega_\lambda \subset \mathbb{R}^2$ such that, up to extracting a further subsequence, the functions χ_{Ω_k} converge to χ_{Ω_λ} in $L^1_{\text{loc}}(\mathbb{R}^2)$.

Now we observe that, since Ω_k is a minimizing sequence for \overline{E}_λ , there exists $C > 0$ such that, for all $R > 0$ large enough, we have

$$|\Omega_k \setminus B_R(0)| \inf_{x \in B_R^c(0)} g(x) \leq \int_{\Omega_k \setminus B_R(0)} g(x) dx \leq \int_{\Omega_k} g(x) dx \leq C, \quad (5.1)$$

so that

$$|\Omega_k \setminus B_R(0)| \leq \frac{C}{\inf_{x \in B_R^c(0)} g(x)}. \quad (5.2)$$

In particular, by (2.11) for any $\varepsilon > 0$ there exists $R_\varepsilon > 0$ such that $|\Omega_k \setminus B_{R_\varepsilon}(0)| \leq \varepsilon$ for all k . Thus, recalling the convergence of χ_{Ω_k} to χ_{Ω_λ} in $L^1_{\text{loc}}(\mathbb{R}^2)$ as $k \rightarrow \infty$, there also exists $k_\varepsilon \in \mathbb{N}$ such that

$$|\Omega_k \Delta \Omega_\lambda| = |(\Omega_k \Delta \Omega_\lambda) \cap B_{R_\varepsilon}(0)| + |(\Omega_k \Delta \Omega_\lambda) \setminus B_{R_\varepsilon}(0)| \leq 2\varepsilon, \quad (5.3)$$

for all $k \geq k_\varepsilon$, that is, the sequence χ_{Ω_k} converges to χ_{Ω_λ} in $L^1(\mathbb{R}^2)$ as $k \rightarrow \infty$.

Since, by definition, \overline{E}_λ is lower semicontinuous in $L^1(\mathbb{R}^2)$, we eventually get that Ω_λ is a minimizer of \overline{E}_λ . \square

The main difficulty in proving Theorem 3 is to show that the minimizer Ω_λ is indeed an element of \mathcal{K}_m , so that it is also a minimizer of E_λ by Proposition 16.

We first show that $\text{cap}_1(\Omega)$ depends continuously on smooth perturbations of Ω , where $\Omega \subset \mathbb{R}^2$ is a compact set with Lipschitz boundary.

Lemma 19. *Let $\Omega \subset \mathbb{R}^2$ be a compact set with positive measure and Lipschitz boundary. Let $\eta \in W^{1,\infty}(\mathbb{R}^2, \mathbb{R}^2)$, let $\Phi_t(x) := x + t\eta(x)$ be the corresponding family of (Lipschitz) diffeomorphisms, defined for $t \in (-t_0, t_0)$ and t_0 sufficiently small, and let $\Omega_t := \Phi_t(\Omega)$.*

Then, for $t \in (-t_0, t_0)$ there holds

$$\text{cap}_1(\Omega) \leq \text{cap}_1(\Omega_t)(1 + Ct), \quad (5.4)$$

where the constant $C > 0$ depends only on the $W^{1,\infty}$ -norm of η .

Proof. Let u_t be the $\frac{1}{2}$ -capacitary potential of Ω_t minimizing (3.7) with Ω replaced by Ω_t , and let $u := u_t \circ \Phi_t$. Notice that u is an admissible function for the minimum problem (3.7). In particular, we have

$$\text{cap}_1(\Omega) \leq \frac{1}{4\pi} \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \frac{|u(x) - u(y)|^2}{|x - y|^3} dx dy. \quad (5.5)$$

We now compute

$$\begin{aligned} \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \frac{|u(x) - u(y)|^2}{|x - y|^3} dx dy &= \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \frac{|u_t(\Phi_t(x)) - u_t(\Phi_t(y))|^2}{|x - y|^3} dx dy \\ &= \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \frac{|u_t(X) - u_t(Y)|^2}{|\Phi_t^{-1}(X) - \Phi_t^{-1}(Y)|^3} |\det \nabla \Phi_t^{-1}(X)| |\det \nabla \Phi_t^{-1}(Y)| dX dY, \end{aligned} \quad (5.6)$$

where we performed the change of variables $X = \Phi_t(x)$, $Y = \Phi_t(y)$. Observing that

$$|\det \nabla \Phi_t^{-1}(X) - 1| \leq Ct \quad \text{and} \quad |\Phi_t^{-1}(X) - \Phi_t^{-1}(Y)| \geq (1 - Ct)|X - Y|, \quad (5.7)$$

where $C > 0$ depends only on the $W^{1,\infty}$ -norm of η , from (5.5) and (5.6) we readily obtain (5.4). \square

From Lemma 19 and (3.6), we immediately get the following result:

Corollary 20. *Under the assumptions of Lemma 19, there holds*

$$\mathcal{I}_1(\Omega_t) \leq \mathcal{I}_1(\Omega)(1 + Ct), \quad (5.8)$$

where the constant $C > 0$ depends only on the $W^{1,\infty}$ -norm of η .

We now show that, if $\lambda < \lambda_c(m)$, we can decrease the energy of a set $\Omega \in \mathcal{K}_m$ by reducing the number of its connected components and holes.

Proposition 21. *Let $\lambda < \lambda_c(m)$ and $g \in \mathcal{G}$. Then, for any $\Omega \in \mathcal{K}_m$ we can find $\tilde{\Omega} \in \mathcal{K}_m$ such that $E_\lambda(\tilde{\Omega}) \leq E_\lambda(\Omega)$, $\tilde{\Omega} \subset B_R(0)$, and the numbers of connected components of both $\tilde{\Omega}$ and of $\tilde{\Omega}^c$ are bounded above by N , where the numbers R, N depend only on λ, m, g and $E_\lambda(\Omega)$.*

Proof. We divide the proof into two steps.

Step 1: Construction of a uniformly bounded set with a uniformly bounded number of connected components.

Let Ω_i be the connected components of Ω , and up to a relabeling we can suppose that if $m_i := |\Omega_i|$, then $m_i \geq m_{i+1}$. Let $\varepsilon \in (0, m/2)$. We claim that there exists $N_\varepsilon \in \mathbb{N}$ depending only on ε and m such that

$$\left| \Omega \setminus \bigcup_{i > N_\varepsilon} \Omega_i \right| \geq m - \frac{\varepsilon}{2} > \frac{3}{4}m. \quad (5.9)$$

Indeed, we have $\sum_{i=1}^{\infty} m_i = m$, and by the isoperimetric inequality we get

$$\sum_{i=1}^{\infty} \sqrt{4\pi m_i} \leq \sum_{i=1}^{\infty} P(\Omega_i) \leq E_{\lambda}(\Omega). \quad (5.10)$$

Recalling that the sequence $i \mapsto m_i$ is decreasing, it follows that

$$m_i \leq \frac{E_{\lambda}^2(\Omega)}{4\pi i^2}. \quad (5.11)$$

Hence there exists $C > 0$ depending only on m, g and $E_{\lambda}(\Omega)$ such that

$$\sum_{i \geq k} m_i \leq \frac{C}{k}, \quad (5.12)$$

so that (5.9) holds for $N_{\varepsilon} \geq 2C/\varepsilon$.

Let us set

$$U_{\varepsilon} := \bigcup_{i=1}^{N_{\varepsilon}} \Omega_i. \quad (5.13)$$

We claim that there exists $\bar{R} \geq 1$, depending only on m, g and $E_{\lambda}(\Omega)$ such that

$$|U_{\varepsilon} \cap B_{\bar{R}}(0)| \geq \frac{2}{3}m. \quad (5.14)$$

Notice that the previous equation implies in particular that

$$|U_{\varepsilon} \setminus B_{\bar{R}}(0)| \leq \frac{1}{3}m. \quad (5.15)$$

Indeed, reasoning as in the proof of Proposition 18, for any $R > 0$ we can write

$$E_{\lambda}(\Omega) \geq \int_{\Omega \setminus B_R(0)} g \, dx \geq |\Omega \setminus B_R(0)| \inf_{x \in B_R^c(0)} g(x), \quad (5.16)$$

so that

$$|\Omega \setminus B_R(0)| \leq \frac{E_{\lambda}(\Omega)}{\inf_{x \in B_R^c(0)} g(x)}. \quad (5.17)$$

Take now $\bar{R} \geq 1$ such that $\frac{E_{\lambda}(\Omega)}{\inf_{x \in B_{\bar{R}}^c(0)} g(x)} \leq \frac{m}{12}$. Such a radius exists in view of the coercivity of g . Then we have

$$|U_{\varepsilon} \cap B_{\bar{R}}(0)| \geq |U_{\varepsilon}| - \frac{m}{12} > \frac{3}{4}m - \frac{m}{12} = \frac{2}{3}m, \quad (5.18)$$

which gives (5.14).

By the same argument, there exists $R_{\varepsilon} \geq 2\bar{R}$ such that $|U_{\varepsilon} \cap B_{R_{\varepsilon}}(0)| \geq m - \varepsilon$. Moreover, since $P(U_{\varepsilon}) \leq E_{\lambda}(\Omega)$, we can also find a radius $R_{\varepsilon}^n \in [R_{\varepsilon}, R_{\varepsilon}']$, with $R_{\varepsilon}' := R_{\varepsilon} + 2E_{\lambda}(\Omega)$, such that $\mathcal{H}^1(U_{\varepsilon} \cap \partial B_{R_{\varepsilon}^n}(0)) = 0$.

Let now $\varphi : \mathbb{R} \rightarrow \mathbb{R}$ be a cutoff function defined as

$$\varphi(s) := \begin{cases} 1 & \text{if } |s| \leq \bar{R} \\ 2 - \frac{|s|}{\bar{R}} & \text{if } \bar{R} < |s| \leq 2\bar{R} \\ 0 & \text{if } |s| \geq 2\bar{R}. \end{cases} \quad (5.19)$$

For $t \geq 0$, we let $\Phi_t(x) := (1 + t\varphi(|x|))x$ and we notice that

$$\det \nabla \Phi_t(x) = (1 + t\varphi(|x|))^2 + t|x|\varphi'(|x|) + t^2|x|\varphi(|x|)\varphi'(|x|). \quad (5.20)$$

In particular, the map $t \mapsto |\Phi_t(A)| = \int_A \det \nabla \Phi_t(x) dx$ is continuous for every set $A \subset \mathbb{R}^2$ of finite measure. Recalling (5.14), (5.15) and letting $\tilde{U}_\varepsilon := U_\varepsilon \cap B_{R_\varepsilon}(0)$, we have

$$\begin{aligned} |\Phi_t(\tilde{U}_\varepsilon)| &= \int_{\tilde{U}_\varepsilon} \det \nabla \Phi_t(x) dx = \int_{\tilde{U}_\varepsilon} [(1 + t\varphi(|x|))^2 + t|x|\varphi'(|x|) + t^2|x|\varphi(|x|)\varphi'(|x|)] dx \\ &\geq |\tilde{U}_\varepsilon| + (2t + t^2)|U_\varepsilon \cap B_{\bar{R}}(0)| - \frac{t + t^2}{\bar{R}} \int_{U_\varepsilon \cap B_{2\bar{R}}(0) \setminus B_{\bar{R}}(0)} |x| dx \\ &\geq |\tilde{U}_\varepsilon| + \frac{2}{3}m(2t + t^2) - \frac{2}{3}m(t + t^2) = |\tilde{U}_\varepsilon| + \frac{2}{3}mt, \end{aligned}$$

which implies that

$$\left| \Phi_{\frac{3(m - |\tilde{U}_\varepsilon|)}{2m}}(\tilde{U}_\varepsilon) \right| \geq m. \quad (5.21)$$

Noting that $|\Phi_0(\tilde{U}_\varepsilon)| = |\tilde{U}_\varepsilon| = |U_\varepsilon \cap B_{R_\varepsilon}(0)| \leq m$, we obtain that there exists $t_\varepsilon \geq 0$ such that $|\Phi_{t_\varepsilon}(\tilde{U}_\varepsilon)| = m$ and

$$t_\varepsilon \leq \frac{3(m - |\tilde{U}_\varepsilon|)}{2m} \leq \frac{3\varepsilon}{2m}. \quad (5.22)$$

Let now $W_\varepsilon := \Phi_{t_\varepsilon}(\tilde{U}_\varepsilon)$. Recalling Corollary 20 and [21, Proposition 3.1] (see also [25, Proposition 17.1]), the following properties hold:

- (i) $W_\varepsilon \subset B_{R'_\varepsilon}(0)$ and W_ε has at most N_ε connected components;
- (ii) $|W_\varepsilon| = m$;
- (iii) $P(W_\varepsilon) \leq \text{Lip}(\Phi_{t_\varepsilon})P(\tilde{U}_\varepsilon) \leq (1 + t_\varepsilon)P(\tilde{U}_\varepsilon) \leq P(\tilde{U}_\varepsilon) + Ct_\varepsilon$;
- (iv) $\mathcal{I}_1(W_\varepsilon) \leq \mathcal{I}_1(\tilde{U}_\varepsilon) + Ct_\varepsilon$;
- (v) $\int_{W_\varepsilon} g(x) \leq \int_{\tilde{U}_\varepsilon} g(x) dx + Ct_\varepsilon$;

where the constant $C > 0$ depends only on g , m and $E_\lambda(\Omega)$. Indeed, the first two assertions follow by construction. Assertion (iii) holds true since $\|\varphi\|_{L^\infty(\mathbb{R})} \leq 1$. Assertion (iv) follows by Corollary 20, while (v) holds true since

$$\begin{aligned} \int_{W_\varepsilon} g(x) dx &= \int_{\tilde{U}_\varepsilon} g(\Phi_{t_\varepsilon}(x)) \det \nabla \Phi_{t_\varepsilon}(x) dx \\ &\leq (1 + t_\varepsilon)^2 \left(\int_{\tilde{U}_\varepsilon} g(x) dx + C \|\nabla g\|_{L^\infty(B_{2\bar{R}}(0))} mt_\varepsilon \right) \\ &\leq \int_{\tilde{U}_\varepsilon} g(x) dx + C' t_\varepsilon, \end{aligned}$$

for some $C, C' > 0$ depending only on g , m and $E_\lambda(\Omega)$.

We claim that $E_\lambda(W_\varepsilon) \leq E_\lambda(\Omega)$ for ε small enough. Letting $V_\varepsilon := \Omega \setminus \tilde{U}_\varepsilon$, we compute

$$\begin{aligned} \delta_\varepsilon &:= E_\lambda(\Omega) - E_\lambda(W_\varepsilon) = P(\tilde{U}_\varepsilon) + P(V_\varepsilon) + \lambda \mathcal{I}_1(\tilde{U}_\varepsilon \cup V_\varepsilon) + \int_{\tilde{U}_\varepsilon} g dx + \int_{V_\varepsilon} g dx \\ &\quad - P(W_\varepsilon) - \lambda \mathcal{I}_1(W_\varepsilon) - \int_{W_\varepsilon} g dx \\ &\geq P(V_\varepsilon) + \lambda \mathcal{I}_1(\tilde{U}_\varepsilon \cup V_\varepsilon) - \lambda \mathcal{I}_1(\tilde{U}_\varepsilon) - Ct_\varepsilon, \end{aligned} \quad (5.23)$$

where the constant $C > 0$ depends only on g , m , and $E_\lambda(\Omega)$. We also have $|V_\varepsilon| < \varepsilon$ by construction. Using Lemma 13 with $U = \tilde{U}_\varepsilon$ and $V = V_\varepsilon$, we obtain

$$P(V_\varepsilon) + \lambda \mathcal{I}_1(\tilde{U}_\varepsilon \cup V_\varepsilon) - \lambda \mathcal{I}_1(\tilde{U}_\varepsilon) \geq P(V_\varepsilon) \left(1 - \frac{\lambda\pi}{4|\tilde{U}_\varepsilon|}\right) \geq P(V_\varepsilon) \left(1 - \frac{\lambda\pi}{4(m-\varepsilon)}\right). \quad (5.24)$$

Recalling that $\lambda < 4m/\pi$, we can choose ε small enough so that

$$\left(1 - \frac{\lambda\pi}{4(m-\varepsilon)}\right) \geq \frac{1}{2} \left(1 - \frac{\lambda\pi}{4m}\right). \quad (5.25)$$

Recalling also (5.22), with the help of the isoperimetric inequality we then get

$$\delta_\varepsilon \geq \frac{1}{2} \left(1 - \frac{\lambda\pi}{4m}\right) P(V_\varepsilon) - \frac{3C}{2m} |V_\varepsilon| \geq \sqrt{\pi} \left(1 - \frac{\lambda\pi}{4m}\right) |V_\varepsilon|^{\frac{1}{2}} - \frac{3C}{2m} |V_\varepsilon| \geq 0, \quad (5.26)$$

provided we choose ε small enough depending only on g , m and $E_\lambda(\Omega)$. We thus proved that $\delta_\varepsilon \geq 0$, that is, $E_\lambda(W_\varepsilon) \leq E_\lambda(\Omega)$.

Step 2: Construction of a set with a uniformly bounded number of holes.

In Step 1 we built a set $W \in \mathcal{K}_m$, with a uniformly bounded number of connected components and such that $E_\lambda(W) \leq E_\lambda(\Omega)$. In particular, there exists a uniform radius $R > 0$ such that $W \subset B_R(0)$. Starting from this, we construct another set with a uniformly bounded number of holes, where a hole is a bounded connected component of the complement set.

Let us denote by $\{H_i\}_{i \in \mathbb{N}}$ the connected components of W^c which are bounded. As in Step 1, for $\varepsilon \in (0, m/2)$ we can find N_ε such that $\sum_{i > N_\varepsilon} |H_i| \leq \varepsilon$. Let us set $H_\varepsilon := \bigcup_{i > N_\varepsilon} H_i$ and

$$\Omega_\varepsilon := \sqrt{\frac{m}{m + |H_\varepsilon|}} (W \cup H_\varepsilon) \in \mathcal{K}_m. \quad (5.27)$$

Notice that

$$P(\Omega_\varepsilon) \leq P(W \cup H_\varepsilon) = P(W) - P(H_\varepsilon), \quad (5.28)$$

$$\mathcal{I}_1(\Omega_\varepsilon) = \sqrt{\frac{m + |H_\varepsilon|}{m}} \mathcal{I}_1(W \cup H_\varepsilon) \leq \left(1 + \frac{|H_\varepsilon|}{2m}\right) \mathcal{I}_1(W), \quad (5.29)$$

$$\begin{aligned} \int_{\Omega_\varepsilon} g(x) dx &= \frac{m}{m + |H_\varepsilon|} \int_W g\left(\sqrt{\frac{m}{m + |H_\varepsilon|}} x\right) dx \\ &\leq \int_W g(x) dx + C|H_\varepsilon|, \end{aligned} \quad (5.30)$$

where the constant $C > 0$ depends on m , g and R , and in obtaining (5.29), we used concavity of the square root and monotonicity of the capacity term with respect to filling the holes. Putting together (5.28), (5.29) and (5.30), we then get

$$E_\lambda(\Omega_\varepsilon) \leq E_\lambda(W) - P(H_\varepsilon) + \left(\frac{E_\lambda(\Omega)}{2m} + C\right) |H_\varepsilon|, \quad (5.31)$$

which yields the claim for ε small enough by the isoperimetric inequality. \square

We now prove Theorem 3.

Proof of Theorem 3. Let $\Omega_n \in \mathcal{K}_m$ be a minimizing sequence for E_λ . In particular $E_\lambda(\Omega_n) \leq c$, for some $c = c(\lambda, g, m) > 0$ depending only on g and m .

Thanks to Proposition 21, we can assume that the sets Ω_n are uniformly bounded and the number of connected components both of Ω_n and of $(\Omega_n)^c$ is uniformly bounded. In particular, the number of connected components of $\partial\Omega_n$ is also uniformly bounded.

Since $\mathcal{H}^1(\partial\Omega_n) \leq c$, it follows by Blaschke Theorem (see [2, Theorem 4.4.15]) that $\partial\Omega_n \rightarrow \Gamma$ in the Hausdorff distance, as $n \rightarrow +\infty$ up to passing to a subsequence, for some compact set $\Gamma \subset \mathbb{R}^2$ with $\mathcal{H}^1(\Gamma) < +\infty$.

Up to passing to a further subsequence, we also have that the sets Ω_n converge to some compact set Ω , again in the Hausdorff distance. We notice that

$$\partial\Omega \subset \Gamma. \quad (5.32)$$

Indeed if $x \in \partial\Omega \setminus \Gamma$, then there exists $x_n \in \Omega_n$ such that $x_n \rightarrow x$. On the other hand, there exists $N \in \mathbb{N}$ and $\varepsilon_0 > 0$ such that $d_H(x_n, \partial\Omega_n) \geq \varepsilon_0$ for $n \geq N$. Otherwise there would exist $y_n \in \partial\Omega_n$ such that $|y_n - x_n| = d(x_n, \partial\Omega_n) \rightarrow 0$ and thus

$$|y_n - x| \leq |y_n - x_n| + |x_n - x| \rightarrow 0, \quad (5.33)$$

which is impossible, since $x \notin \Gamma$. But then the ball $B_{\varepsilon_0}(x_n)$ is contained, for $n \geq N$, in Ω_n and converges in Hausdorff distance to $B_{\varepsilon_0}(x) \subset \Omega$. In particular we get $x \notin \partial\Omega$, which gives a contradiction. Thanks to Golab Theorem [2, Theorem 4.4.17], we then obtain

$$\mathcal{H}^1(\partial\Omega) \leq \mathcal{H}^1(\Gamma) \leq \liminf_{n \rightarrow +\infty} \mathcal{H}^1(\partial\Omega_n) \leq c. \quad (5.34)$$

Let now $x \in \mathbb{R}^N \setminus \Gamma$. Then there exist $\varepsilon > 0$ and $N \in \mathbb{N}$ such that for $n \geq N$, we have that $B_\varepsilon(x) \subset \Omega_n$ or $B_\varepsilon(x) \subset (\mathbb{R}^N \setminus \Omega_n)$. Thus $\chi_{\Omega_n}(x) = 1$ or $\chi_{\Omega_n}(x) = 0$ for n large enough. In particular $\chi_{\Omega_n} \rightarrow \chi_\Omega$ almost everywhere and, by the Dominated Convergence Theorem, we obtain that $\chi_{\Omega_n} \rightarrow \chi_\Omega$ in $L^1(\mathbb{R}^2)$.

We can now conclude that Ω is a minimizer in \mathcal{K}_m . Indeed, the minimality is granted by the lower semicontinuity of E_λ w.r.t. the L^1 -convergence, since $\lambda < \lambda_c(m)$. Moreover, $\Omega \in \mathcal{K}_m$ since it is compact, it has measure m and $\mathcal{H}^1(\partial\Omega) < +\infty$ by (5.34). The proof is concluded. \square

6. PARTIAL REGULARITY OF MINIMIZERS: PROOF OF THEOREM 4

In this section we show that all minimizers of our problem are bounded, contain finitely many connected components and holes, and satisfy suitable density estimates. For the latter, the argument essentially follows the classical proof of the density estimates for quasi-minimizers of the perimeter (see [25]). Note, however, that the standard regularity theory of quasi-minimizers of the perimeter cannot be applied directly, as the nonlocal term \mathcal{I}_1 presents a critical perturbation to the perimeter. This additional complication may be overcome with the help of Lemma 13 for subcritical values of $\lambda < \lambda_c(m)$, yielding partial regularity of the minimizers.

Proof of Theorem 4. Throughout the proof, we identify the minimizer Ω_λ with its regular representative Ω_λ^+ , and drop the superscript “+” for ease of notation.

First of all, the assertion about the number of connected components of Ω_λ and Ω_λ^c follows from the argument in the proof of Proposition 21, observing that the inequality in that proposition becomes strict otherwise, contradicting the minimality of Ω_λ . Therefore, the rest of the proof focuses on the density estimates (2.15), whose proof uses the estimates similar to those in the proof of Proposition 21. It is enough to show the first assertion, since the second one can be proved analogously, taking into account that Ω_λ^+ is a closed set.

For $r \in (0, \sqrt{m/(2\pi)})$, so that $|\Omega_\lambda \setminus B_r(x)| \geq m/2$, we set

$$v(0) := 0, \quad v(r) := |\Omega_\lambda \cap B_r(x)|, \quad \Omega_{\lambda,r} := \sqrt{\frac{m}{m-v(r)}} (\Omega_\lambda \setminus B_r(x)) \in \mathcal{K}_m. \quad (6.1)$$

Since $x \in \partial\Omega_\lambda^+$, we have that $v(r) > 0$ for all $r > 0$. Moreover, since Ω_λ has finite perimeter, for almost every $r > 0$ there holds (see [25])

$$P(\Omega_\lambda) = P(\Omega_\lambda; B_r(x)) + P(\Omega_\lambda; B_r^c(x)) \quad \text{and} \quad \frac{dv}{dr}(r) = \mathcal{H}^1(\partial B_r(x) \cap \Omega_\lambda). \quad (6.2)$$

Recalling the Lipschitz continuity of g , for almost every $r \in (0, \sqrt{m/(2\pi)})$ we then get

$$\begin{aligned} & P(\Omega_\lambda; B_r(x)) + P(\Omega_\lambda; B_r^c(x)) + \lambda \mathcal{I}_1(\Omega_\lambda) + \int_{\Omega_\lambda} g(y) dy = E_\lambda(\Omega_\lambda) \\ & \leq E_\lambda(\Omega_{\lambda,r}) = \sqrt{\frac{m}{m-v(r)}} (P(\Omega_\lambda; B_r^c(x)) + \mathcal{H}^1(\partial B_r(x) \cap \Omega_\lambda)) \\ & + \lambda \sqrt{\frac{m-v(r)}{m}} \mathcal{I}_1(\Omega_\lambda \setminus B_r(x)) + \frac{m}{m-v(r)} \int_{\Omega_\lambda \setminus B_r(x)} g\left(\sqrt{\frac{m}{m-v(r)}} y\right) dy \\ & \leq P(\Omega_\lambda; B_r^c(x)) + \frac{dv}{dr}(r) + \lambda \mathcal{I}_1(\Omega_\lambda \setminus B_r(x)) + \int_{\Omega_\lambda} g(y) dy + Cv(r), \end{aligned} \quad (6.3)$$

where the constant $C > 0$ depends only on m , λ and g .

After some simplifications, (6.3) reads

$$P(\Omega_\lambda; B_r(x)) \leq \frac{dv}{dr}(r) + Cv(r) + \lambda \mathcal{I}_1(\Omega_\lambda \setminus B_r(x)) - \lambda \mathcal{I}_1(\Omega_\lambda). \quad (6.4)$$

Applying Lemma 13 with $U = \Omega_\lambda \setminus B_r(x)$ and $V = \Omega_\lambda \cap B_r(x)$, we then obtain

$$\begin{aligned} P(\Omega_\lambda; B_r(x)) & \leq \frac{dv}{dr}(r) + Cv(r) + \frac{\lambda\pi}{4|\Omega_\lambda \setminus B_r(x)|} P(\Omega_\lambda \cap B_r(x)) \\ & \leq \frac{dv}{dr}(r) + C'v(r) + \frac{\lambda\pi}{4m} P(\Omega_\lambda \cap B_r(x)), \end{aligned} \quad (6.5)$$

where $C' > 0$ depends only on m , λ and g .

Since for almost every $r > 0$ there holds

$$P(\Omega_\lambda; B_r(x)) + \frac{dv}{dr}(r) = P(\Omega_\lambda \cap B_r(x)), \quad (6.6)$$

by adding the quantity $\frac{dv}{dr}(r)$ to both sides of (6.5) we obtain

$$P(\Omega_\lambda \cap B_r(x)) \left(1 - \frac{\lambda\pi}{4m}\right) \leq 2 \frac{dv}{dr}(r) + C'v(r). \quad (6.7)$$

Thanks to the isoperimetric inequality, for almost every $r \in (0, \sqrt{m/(2\pi)})$ we then get

$$2\sqrt{\pi} \left(1 - \frac{\lambda\pi}{4m}\right) \sqrt{v(r)} \leq 2 \frac{dv}{dr}(r) + C'v(r). \quad (6.8)$$

Recalling that $\lambda < 4m/\pi$, there exists $r_0 \in (0, \sqrt{m/(2\pi)})$, depending only on m , λ and g , such that

$$2\sqrt{\pi} \left(1 - \frac{\lambda\pi}{4m}\right) \sqrt{v(r)} - C'v(r) \geq \sqrt{\pi} \left(1 - \frac{\lambda\pi}{4m}\right) \sqrt{v(r)} \quad \text{for all } 0 < r \leq r_0, \quad (6.9)$$

which gives

$$\frac{dv}{dr}(r) \geq \frac{\sqrt{\pi}}{2} \left(1 - \frac{\lambda\pi}{4m}\right) \sqrt{v(r)} \quad \text{for a.e. } 0 < r \leq r_0. \quad (6.10)$$

After a direct integration, this inequality implies that

$$v(r) \geq \frac{\pi}{16} \left(1 - \frac{\lambda\pi}{4m}\right)^2 r^2 \quad \text{for a.e. } 0 \leq r \leq r_0, \quad (6.11)$$

which gives the first inequality in (2.15). This concludes the proof. \square

7. ASYMPTOTIC SHAPE OF MINIMIZERS: PROOF OF THEOREM 6

Proof of Theorem 6. The first assertion is a direct consequence of Theorem 3, since $\lambda_k < \lambda_c(m_k)$ for k large enough.

We now prove the second assertion. Let Ω_k be a minimizer of E_{λ_k} over \mathcal{K}_{m_k} . Recalling Remark 5, without loss of generality we can assume that

$$P(\Omega_k) = \mathcal{H}^1(\partial\Omega_k). \quad (7.1)$$

By a change of variables $x = r_k \tilde{x}$, with $r_k := \sqrt{m_k/\pi}$ we obtain that

$$E_{\lambda_k}(\Omega_k) = r_k F_k(\tilde{\Omega}_k), \quad (7.2)$$

where $\tilde{\Omega}_k := r_k^{-1}\Omega_k$, so that in particular $|\tilde{\Omega}_k| = \pi$, and

$$F_k(\Omega) := P(\Omega) + \frac{\lambda_k\pi}{m_k} \mathcal{I}_1(\Omega) + r_k \int_{\Omega} g(r_k \tilde{x}) d\tilde{x}. \quad (7.3)$$

Observe that since $g \in \mathcal{G}$, there exists $x_0 \in \mathbb{R}^2$ such that $g(x_0) = \min g$, and without loss of generality we may assume that $x_0 = 0$. By the minimality of Ω_k we have that

$$P(\tilde{\Omega}_k) + \frac{\lambda_k\pi}{m_k} \mathcal{I}_1(\tilde{\Omega}_k) + r_k \int_{\tilde{\Omega}_k} g(r_k \tilde{x}) d\tilde{x} \leq P(B_1(0)) + \frac{\lambda_k\pi}{m_k} \mathcal{I}_1(B_1(0)) + r_k \int_{B_1(0)} g(r_k \tilde{x}) d\tilde{x} \quad (7.4)$$

Notice also that, since the gradient of g is locally bounded, we have

$$0 \leq \int_{B_1(0)} (g(r_k \tilde{x}) - g(0)) d\tilde{x} \leq Cr_k, \quad (7.5)$$

where $C > 0$ depends only on g , for all k large enough. From (7.4) and (7.5) we then get

$$P(\tilde{\Omega}_k) + \frac{\lambda_k\pi}{m_k} \mathcal{I}_1(\tilde{\Omega}_k) + r_k \int_{\tilde{\Omega}_k} (g(r_k \tilde{x}) - g(0)) d\tilde{x} \leq P(B_1(0)) + \frac{\lambda_k\pi}{m_k} \mathcal{I}_1(B_1(0)) + Cr_k^2, \quad (7.6)$$

and we note that the integral in the left-hand side is non-negative.

We recall from Lemma 9 the inequality

$$P(B_1(0)) + \lambda \mathcal{I}_1(B_1(0)) \leq \mathcal{H}^1(\tilde{\Omega}_k) + \lambda \mathcal{I}_1(\tilde{\Omega}_k) = P(\tilde{\Omega}_k) + \lambda \mathcal{I}_1(\tilde{\Omega}_k), \quad (7.7)$$

where the last equality follows from Remark 5, for all $\lambda \leq 4$. Hence we get

$$\mathcal{I}_1(B_1(0)) - \mathcal{I}_1(\tilde{\Omega}_k) \leq \frac{1}{\lambda} \left(P(\tilde{\Omega}_k) - P(B_1(0)) \right). \quad (7.8)$$

From (7.6) and (7.8) with $\lambda = 4$ we then obtain

$$\left(1 - \frac{\lambda_k\pi}{4m_k}\right) \left(P(\tilde{\Omega}_k) - P(B_1(0)) \right) + r_k \int_{\tilde{\Omega}_k} (g(r_k \tilde{x}) - g(0)) d\tilde{x} \leq Cr_k^2. \quad (7.9)$$

By the isoperimetric inequality in quantitative form [15], there exist $\tilde{x}_k \in \mathbb{R}^2$ such that

$$|\tilde{\Omega}_k \Delta B_1(\tilde{x}_k)|^2 \leq C m_k \left(1 - \frac{\lambda_k \pi}{4m_k}\right)^{-1}, \quad (7.10)$$

for all k small enough, for some constant $C > 0$ depending only on g . Hence, recalling the assumption on λ_k, m_k , we obtain

$$\lim_{k \rightarrow +\infty} |\tilde{\Omega}_k \Delta B_1(\tilde{x}_k)| = 0, \quad (7.11)$$

implying that $\tilde{\Omega}_k$ converge to $B_1(0)$ in the L^1 -sense. Hausdorff convergence then follows from the fact that the density estimates in Theorem 4 can be easily seen to hold for $\tilde{\Omega}_k$ uniformly in k .

Similarly, from (7.9) written in the original unscaled variables, and with the help of the isoperimetric inequality we infer that

$$\frac{1}{m_k} \int_{\mathbb{R}^2} \chi_{\Omega_k}(x) \bar{g}(x) dx - g(0) \leq C m_k^{1/2}, \quad (7.12)$$

where $\bar{g}(x) = \min\{g(x), g(0) + 1\}$ and χ_{Ω_k} are the characteristic functions of Ω_k . At the same time, defining $x_k := r_k \tilde{x}_k$ and using (7.10) we have

$$\left| \int_{\mathbb{R}^2} (\chi_{\Omega_k} - \chi_{B_{r_k}(x_k)}) \bar{g} dx \right| \leq (g(0) + 1) |\Omega_k \Delta B_{r_k}(x_k)| \leq C m_k^{3/2}, \quad (7.13)$$

for $C > 0$ depending only on g and all k large enough. Thus, we have that (7.12) also holds with χ_{Ω_k} replaced with $\chi_{B_{r_k}(x_k)}$, and by Lipschitz continuity of \bar{g} we obtain

$$\begin{aligned} \bar{g}(x_k) &= \frac{1}{m_k} \int_{\mathbb{R}^2} \chi_{B_{r_k}(x_k)}(x) \bar{g}(x_k) dx \leq \frac{1}{m_k} \int_{\mathbb{R}^2} \chi_{B_{r_k}(x_k)}(x) \bar{g}(x) dx + C m_k^{1/2} \\ &\leq \frac{1}{m_k} \int_{\mathbb{R}^2} \chi_{\Omega_k}(x) \bar{g}(x) dx + C' m_k^{1/2} \leq g(0) + C'' m_k^{1/2}, \end{aligned} \quad (7.14)$$

for some $C, C', C'' > 0$ depending only on g and all k large enough. In particular, $\bar{g}(x_k) = g(x_k)$ for all k sufficiently large, and by coercivity of g the sequence of x_k is bounded. Thus, it is the desired sequence.

Finally, to prove the third assertion of the theorem, we pass to the limit $k \rightarrow \infty$ in (7.14), after extracting a convergent subsequence, and use continuity of g . \square

8. THE EULER-LAGRANGE EQUATION: PROOF OF THEOREM 7

The aim of this section is to obtain the Euler-Lagrange equation satisfied by regular critical points of the functional E_λ . In order to do this, we first compute the first variation of an auxiliary functional which will be shown to be related to the capacitary energy.

Given an open set $\Omega \subset \mathbb{R}^2$, not necessarily bounded, and a function $f \in L^{\frac{4}{3}}(\mathbb{R}^2)$, we define

$$I_{\Omega, f}(v) := \begin{cases} \frac{1}{2} \|v\|_{\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)}^2 - \int_{\mathbb{R}^2} f v dx & \text{if } v \in \dot{H}^{\frac{1}{2}}(\mathbb{R}^2) \text{ and } v|_{\Omega^c} = 0, \\ +\infty & \text{otherwise.} \end{cases} \quad (8.1)$$

Notice that since the space $\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)$ continuously embeds into $L^4(\mathbb{R}^2)$, the functional $I_{\Omega,f}$ admits a unique minimizer $u_{\Omega,f} \in \dot{H}^{\frac{1}{2}}(\mathbb{R}^2)$, which satisfies

$$\begin{cases} (-\Delta)^{\frac{1}{2}} u_{\Omega,f} = f & \text{on } \Omega, \\ u_{\Omega,f} = 0 & \text{on } \Omega^c, \end{cases} \quad (8.2)$$

in the distributional sense, namely (see [24, Eq. (4.14)]):

$$\int_{\Omega} u_{\Omega,f} (-\Delta)^{\frac{1}{2}} \varphi \, dx = \int_{\Omega} f \varphi \, dx \quad \forall \varphi \in C_c^\infty(\Omega), \quad (8.3)$$

where

$$(-\Delta)^{\frac{1}{2}} \varphi(x) := \frac{1}{4\pi} \int_{\mathbb{R}^2} \frac{2\varphi(x) - \varphi(x-y) - \varphi(x+y)}{|y|^3} \, dy \quad x \in \mathbb{R}^2, \quad (8.4)$$

with the usual convention of extending φ by zero outside Ω . Furthermore, when $u_{\Omega,f}|_{\Omega} \in C_{\text{loc}}^{1,\alpha}(\Omega) \cap L^\infty(\Omega)$ for some $\alpha \in (0, 1)$, we also have that (8.2) holds pointwise in Ω , with the definition of $(-\Delta)^{\frac{1}{2}}$ in (8.4) extended to such functions [32, Section 3]. In addition, in this case we have

$$J_f(\Omega) := \min I_{\Omega,f} = -\frac{1}{2} \int_{\Omega} u_{\Omega,f} f \, dx = -\frac{1}{2} \int_{\Omega} u_{\Omega,f} (-\Delta)^{\frac{1}{2}} u_{\Omega,f} \, dx. \quad (8.5)$$

The following lemma gives a basic regularity result for the Dirichlet problem in (8.2).

Lemma 22. *Let $f \in L^\infty(\mathbb{R}^2) \cap L^{\frac{4}{3}}(\mathbb{R}^2)$, let $\Omega \subset \mathbb{R}^2$ be an open set and let $u_{\Omega,f}$ be the minimizer of $I_{\Omega,f}$. Then there exists a constant $C > 0$ depending only on f such that $\|u_{\Omega,f}\|_{L^\infty(\mathbb{R}^2)} \leq C$. If in addition $f|_{\Omega} \in C_{\text{loc}}^\alpha(\Omega)$ for some $\alpha \in (0, 1)$ then $u_{\Omega,f}|_{\Omega} \in C_{\text{loc}}^{1,\alpha}(\Omega)$.*

Proof. Let $\varphi \in \dot{H}^{\frac{1}{2}}(\mathbb{R}^2)$ be the unique solution to $(-\Delta)^{\frac{1}{2}} \varphi = -f$ in \mathbb{R}^2 (for a detailed discussion of the notion and the representations of the solution, see [24, Section 4]). In particular, since by assumption $f \in L^{\frac{4}{3}}(\mathbb{R}^2) \cap L^\infty(\mathbb{R}^2)$, from [24, Lemma 4.1] it follows that $\varphi \in L^\infty(\mathbb{R}^2)$. Furthermore, since we have

$$\frac{1}{2} \|v\|_{\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)}^2 - \int_{\mathbb{R}^2} v f \, dx = \frac{1}{2} \|v + \varphi\|_{\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)}^2 - \frac{1}{2} \|\varphi\|_{\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)}^2 \quad \text{for any } v \in \dot{H}^{\frac{1}{2}}(\mathbb{R}^2), \quad (8.6)$$

we get that the function $w_{\Omega,f} := u_{\Omega,f} + \varphi$ solves the minimum problem

$$w_{\Omega,f} = \operatorname{argmin} \left\{ \|w\|_{\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)}^2 : w \in \dot{H}^{\frac{1}{2}}(\mathbb{R}^2), w|_{\Omega^c} = \varphi \right\}. \quad (8.7)$$

By an explicit computation, for any $w \in \dot{H}^{\frac{1}{2}}(\mathbb{R}^2)$ we have $\|\bar{w}\|_{\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)} \leq \|w\|_{\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)}$, where

$$\bar{w} := \min(\max(w, -\|\varphi\|_{L^\infty(\mathbb{R}^2)}), \|\varphi\|_{L^\infty(\mathbb{R}^2)}). \quad (8.8)$$

It then follows that $\|w_{\Omega,f}\|_{L^\infty(\mathbb{R}^2)} \leq \|\varphi\|_{L^\infty(\mathbb{R}^2)}$, yielding

$$\|u_{\Omega,f}\|_{L^\infty(\mathbb{R}^2)} \leq \|w_{\Omega,f}\|_{L^\infty(\mathbb{R}^2)} + \|\varphi\|_{L^\infty(\mathbb{R}^2)} \leq 2 \|\varphi\|_{L^\infty(\mathbb{R}^2)}. \quad (8.9)$$

Finally, Hölder regularity of the derivative of u is an immediate consequence of [32, Eq. (6.2)] (see also the references therein). \square

We now recall the definition of the normal $\frac{1}{2}$ -derivative of the function $u_{\Omega,f}$ vanishing at points of $\partial\Omega$:

$$\partial_\nu^{1/2} u_{\Omega,f}(x) := \lim_{s \rightarrow 0^+} \frac{u_{\Omega,f}(x - s\nu(x))}{s^{1/2}} \quad x \in \partial\Omega, \quad (8.10)$$

where $\nu(x)$ is the outward unit normal vector. We have the following result that will be crucial for the computation of the shape derivative of $J_f(\Omega)$.

Lemma 23. *Let $\Omega_n, \Omega_\infty \subset \mathbb{R}^2$, $n \in \mathbb{N}$, be open sets whose boundaries are uniformly bounded and uniformly of class $C^{1,\alpha}$ for some $\alpha \in (0, 1/2)$. Let $f \in L^\infty(\mathbb{R}^2) \cap L^{\frac{4}{3}}(\mathbb{R}^2)$ and assume that $\Omega_n \rightarrow \Omega_\infty$, as $n \rightarrow \infty$, in the Hausdorff distance. Then, for all $n \in \mathbb{N} \cup \{\infty\}$ the function $\partial_\nu^{1/2} u_{\Omega_n,f}$ can be continuously extended to a function $\bar{D}_n \in C^\alpha(\mathbb{R}^2)$ such that $\bar{D}_n \rightarrow \bar{D}_\infty$ as $n \rightarrow \infty$, locally uniformly in \mathbb{R}^2 .*

Proof. Denote $u_n := u_{\Omega_n,f}$ for simplicity. Let $R_1 > 2R_0 > 0$ be such that $\partial\Omega_n \subset B_{R_0/2}(0)$ and $B_{R_0}(0) \subset B_{R_1/2}(x_0)$ for all $n \in \mathbb{N} \cup \{\infty\}$ and $x_0 \in \partial\Omega_n$. Let also $\tilde{\Omega}_n := \Omega_n \cap B_{R_0+R_1}(0)$.

Notice that from Lemma 22 it follows that $\|u_n\|_{L^\infty(\mathbb{R}^2)} \leq C$ for some constant $C > 0$ independent of n . Then by [33, Proposition 1.1], applied with Ω replaced by $\tilde{\Omega}_n$ and $B_1(0)$ replaced by $B_{R_1}(x_0)$ for some $x_0 \in \partial\Omega_n$, the sequence (u_n) is uniformly bounded in $C^{1/2}(B_{R_0}(0))$. We observe that the $C^{1/2}$ -estimate in [33] is uniform in n since the involved constants depend only on the $C^{1,\alpha}$ -norm of the boundary of $\partial\tilde{\Omega}_n$. As a consequence, by Arzelà-Ascoli Theorem, up to passing to a subsequence, the functions u_n converge as $n \rightarrow \infty$ to u^* uniformly in $\bar{B}_{R_0}(0)$.

To identify the limit function u^* , we establish the Γ -convergence of the functional $I_{\Omega_n,f}$ to $I_{\Omega_\infty,f}$ with respect to the weak convergence in $\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)$. The latter is the natural topology, since the minimizers of $I_{\Omega_n,f}$ are uniformly bounded in $\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)$ independently of n . Indeed, by Hölder inequality we have

$$0 = I_{\Omega_n,f}(0) \geq \frac{1}{2} \|u_n\|_{\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)}^2 - \|f\|_{L^{\frac{4}{3}}(\mathbb{R}^2)} \|u_n\|_{L^4(\mathbb{R}^2)}, \quad (8.11)$$

and the last term is dominated by the first term in the right-hand side by fractional Sobolev inequality [11, Theorem 6.5]. The Γ -lim inf follows from lower-semicontinuity of the $\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)$ -norm and the continuity of the linear term, together with the fact that the limit function vanishes a. e. in Ω_∞^c by compact embedding of $\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)$ into $L_{\text{loc}}^p(\mathbb{R}^2)$ for any $p < 4$ [11, Corollary 7.2]. Finally, the Γ -lim sup follows by approximating the limit function by a function from $C_c^\infty(\Omega_\infty)$, for which we have pointwise convergence of $I_{\Omega_n,f}$, and a diagonal argument. As a corollary to this result, we have that $u_n \rightharpoonup u_\infty$ in $\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)$ and, hence, by uniqueness of the minimizer of $I_{\Omega_\infty,f}$, we also have $u_n \rightarrow u_\infty$ a. e. in \mathbb{R}^2 . In particular, $u^* = u_\infty$ a. e. in $B_{R_0}(0)$.

We now consider the functions $D_n : \tilde{\Omega}_n \rightarrow \mathbb{R}$, $D_n(x) := u_n(x)/d_n^{1/2}(x)$, where $d_n(x) := \text{dist}(x, \tilde{\Omega}_n^c)$ and $n \in \mathbb{N} \cup \{\infty\}$. Then by [33, Theorem 1.2] (see also [10]), applied as before with Ω replaced by $\tilde{\Omega}_n$ and $B_1(0)$ replaced by $B_{R_1}(x_0)$ for some $x_0 \in \partial\Omega_n$, the sequence (D_n) is uniformly bounded in $C^\alpha(\bar{B}_{R_0}(0))$. By classical extension theorems (see for instance [18, Theorem 6.38]) for all $n \in \mathbb{N}$ we can extend D_n to a function $\bar{D}_n : \bar{B}_{R_0}(0) \rightarrow \mathbb{R}$ such that

$$\|\bar{D}_n\|_{C^\alpha(\bar{B}_{R_0}(0))} \leq C_0 \|D_n\|_{C^\alpha(\bar{B}_{R_0}(0))} \leq C, \quad (8.12)$$

where the constants C_0, C are independent of n . Again by Arzelà-Ascoli Theorem, up to passing to a subsequence, the functions \overline{D}_n converge as $n \rightarrow \infty$ to a function $\overline{D}^* \in C^\alpha(\overline{B}_{R_0}(0))$ uniformly. Moreover, from the convergence of u_n to u_∞ we get that $\overline{D}^*|_{\overline{\Omega}_\infty \cap \overline{B}_{R_0}(0)} = D_\infty$.

Finally, we observe that \overline{D}_n is a continuous extension of $\partial_\nu^{1/2} u_n$ for all $n \in \mathbb{N} \cup \{\infty\}$, since we have, for any $x \in \partial\Omega_n$,

$$\overline{D}_n(x) = \lim_{s \rightarrow 0^+} D_n(x - s\nu(x)) = \lim_{s \rightarrow 0^+} \frac{u_n(x - s\nu(x))}{d_n(x - s\nu(x))^{1/2}} = \partial_\nu^{1/2} u_n(x), \quad (8.13)$$

concluding the proof. \square

Corollary 24. *Under the assumptions of Lemma 23, let $x_n \in \partial\Omega_n$ and $x \in \partial\Omega_\infty$ be such that $x_n \rightarrow x \in \partial\Omega_\infty$. Then $\partial_\nu^{1/2} u_n(x_n) \rightarrow \partial_\nu^{1/2} u_\infty(x)$ as $n \rightarrow +\infty$.*

Proof. Consider the extensions \overline{D}_n , $n \in \mathbb{N} \cup \{\infty\}$, constructed in the proof of the previous lemma. Then we have

$$\begin{aligned} |\partial_\nu^{1/2} u_n(x_n) - \partial_\nu^{1/2} u_\infty(x)| &= |\overline{D}_n(x_n) - \overline{D}_\infty(x)| \\ &\leq |\overline{D}_n(x_n) - \overline{D}_n(x)| + |\overline{D}_n(x) - \overline{D}_\infty(x)| \end{aligned} \quad (8.14)$$

and the right-hand side of the latter inequality converges to 0 as $n \rightarrow +\infty$. \square

We now compute the first variation of the functional J_f . We note that for bounded domains and under stronger regularity assumptions such a computation was carried out in [8], with a relatively long and technical proof. Here we provide an alternative, shorter proof, that also covers the case of unbounded domains and weaker assumptions on the regularity of f and $\partial\Omega$.

Theorem 25. *Let $f \in L^\infty(\mathbb{R}^2) \cap L^{\frac{4}{3}}(\mathbb{R}^2)$ be such that $f|_\Omega \in C_{\text{loc}}^\alpha(\Omega)$ for some $\alpha \in (0, 1)$. Let Ω be an open set with compact boundary of class C^2 , and let $u_{\Omega, f}$ be the unique minimizer of $I_{\Omega, f}$. Let $\zeta \in C^\infty(\mathbb{R}^2, \mathbb{R}^2)$, and let $(\Phi_t)_{t \in \mathbb{R}}$ be a smooth family of diffeomorphisms of the plane satisfying $\Phi_0 = \text{Id}$ and $\frac{d}{dt} \Phi_t|_{t=0} = \zeta$. Then, if ν is the outward pointing normal vector to $\partial\Omega$, the normal $\frac{1}{2}$ -derivative $\partial_\nu^{1/2} u_{\Omega, f}$ is well-defined and belongs to $C^\beta(\partial\Omega)$ for any $\beta \in (0, 1/2)$. Moreover, we have*

$$\left. \frac{d}{dt} J_f(\Phi_t(\Omega)) \right|_{t=0} = -\frac{\pi}{8} \int_{\partial\Omega} (\partial_\nu^{1/2} u_{\Omega, f}(x))^2 \zeta(x) \cdot \nu(x) d\mathcal{H}^1(x). \quad (8.15)$$

Proof. Let $\Omega_t := \Phi_t(\Omega)$. Since $\partial\Omega$ is of class C^2 , for all $x \in \partial\Omega_t$ and $|t|$ small enough we can write

$$\Phi_t^{-1}(x) = x + t\rho_t(x)\nu_t(x), \quad (8.16)$$

where $\rho_t \in C^2(\partial\Omega_t)$ is a scalar function and ν_t is the unit outward normal to $\partial\Omega_t$. Furthermore, the right-hand side of (8.16) establishes a bijection between $\partial\Omega_t$ and $\partial\Omega$, and we have

$$\rho_0(x) := \lim_{t \rightarrow 0} \rho_t(x) = -\zeta(x) \cdot \nu(x) \quad \forall x \in \partial\Omega. \quad (8.17)$$

For $t > 0$ sufficiently small, let $\Omega_t \subset \Omega$ be a regular inward deformation of Ω , namely, Ω_t is such that (8.16) holds true with some $\rho_t \geq 0$. Note that it is enough to consider inward perturbations, since for outward perturbations one would simply interchange the roles of Ω_t and Ω in the argument below.

We denote $u := u_{\Omega, f}$ and $u_t := u_{\Omega_t, f}$ for simplicity. Recall that u and u_t solve pointwise

$$\begin{cases} (-\Delta)^{\frac{1}{2}} u = f & \text{in } \Omega, \\ u = 0 & \text{in } \Omega^c, \end{cases} \quad (8.18)$$

and

$$\begin{cases} (-\Delta)^{\frac{1}{2}} u_t = f & \text{in } \Omega_t, \\ u_t = 0 & \text{in } \Omega_t^c. \end{cases} \quad (8.19)$$

In particular, by [33, Theorem 1.2] we have $|u(x)| \leq C \sqrt{\text{dist}(x, \partial\Omega)}$ for some constant $C > 0$, which in turn implies that $|(-\Delta)^{\frac{1}{2}} u(x)| \leq C/\sqrt{\text{dist}(x, \partial\Omega)}$, and the same holds for the function u_t , with Ω replaced by Ω_t and the constant C independent of t for all small enough t . These estimates justify all the computations of integrals involving u and u_t below.

From (8.18), (8.19) and (8.5) we get

$$\begin{aligned} J_f(\Omega_t) - J_f(\Omega) &= \frac{1}{2} \int_{\mathbb{R}^2} u(-\Delta)^{\frac{1}{2}} u \, dx - \frac{1}{2} \int_{\mathbb{R}^2} u_t(-\Delta)^{\frac{1}{2}} u_t \, dx \\ &= -\frac{1}{2} \int_{\mathbb{R}^2} (u_t + u)(-\Delta)^{\frac{1}{2}} (u_t - u) \, dx \\ &= -\frac{1}{2} \int_{\Omega \setminus \Omega_t} u(-\Delta)^{\frac{1}{2}} u_t \, dx + \frac{1}{2} \int_{\Omega \setminus \Omega_t} u f \, dx. \end{aligned} \quad (8.20)$$

The last term in (8.20) satisfies

$$\left| \frac{1}{2} \int_{\Omega \setminus \Omega_t} u f \, dx \right| \leq C \|f\|_{L^\infty(\Omega \setminus \Omega_t)} \|\rho_t\|_{L^\infty(\partial\Omega)}^{\frac{1}{2}} t^{\frac{1}{2}} |\Omega \setminus \Omega_t| \leq C' t^{\frac{3}{2}} = o(t). \quad (8.21)$$

We thus focus on the first term of the right-hand side of (8.20). We have:

$$\begin{aligned} -\frac{1}{2} \int_{\Omega \setminus \Omega_t} u(-\Delta)^{\frac{1}{2}} u_t \, dx &= -\frac{1}{8\pi} \int_{\Omega \setminus \Omega_t} \int_{\mathbb{R}^2} u(x) \frac{2u_t(x) - u_t(x-y) - u_t(x+y)}{|y|^3} \, dy \, dx \\ &= \frac{1}{4\pi} \int_{\Omega \setminus \Omega_t} \int_{\Omega_t} \frac{u(x)u_t(y)}{|x-y|^3} \, dy \, dx. \end{aligned} \quad (8.22)$$

Next we split the integral over Ω_t in (8.22) into integrals over Ω^R and $\Omega_t \setminus \Omega^R$, where

$$\Omega^R := \{x \in \Omega : \text{dist}(x, \Omega^c) > R\} \quad (8.23)$$

and $R > 0$ is such that $\partial\Omega^R$ is of class C^2 and $\Omega_t \setminus \Omega^R$ consists of a union of disjoint strip-like domains. We have

$$\begin{aligned} &-\frac{1}{2} \int_{\Omega \setminus \Omega_t} u(-\Delta)^{\frac{1}{2}} u_t \, dx \\ &= \frac{1}{4\pi} \int_{\Omega \setminus \Omega_t} \int_{\Omega^R} \frac{u(x)u_t(y)}{|x-y|^3} \, dy \, dx + \frac{1}{4\pi} \int_{\Omega \setminus \Omega_t} \int_{\Omega_t \setminus \Omega^R} \frac{u(x)u_t(y)}{|x-y|^3} \, dy \, dx \\ &= \frac{1}{4\pi} \int_{\Omega \setminus \Omega_t} \int_{\Omega^R} \frac{u(x)u_t(y)}{|x-y|^3} \, dy \, dx + \frac{1}{4\pi} \\ &\quad \times \int_{\partial\Omega_t} \int_{\partial\Omega_t} \int_0^{t\rho_t(x)} \int_0^R \frac{u(x + s\nu_t(x))u_t(y - s'\nu_t(y))}{|x-y + s\nu_t(x) + s'\nu_t(y)|^3} \\ &\quad \times (1 + s\kappa(x))(1 - s'\kappa(y)) \, ds' \, ds \, d\mathcal{H}^1(y) \, d\mathcal{H}^1(x), \end{aligned} \quad (8.24)$$

where κ is the curvature of $\partial\Omega_t$, positive if Ω_t is convex. As above, one can check that the first term on the right-hand side of (8.24) is $O(t^{3/2}R^{-2})$ for all t small enough, hence we can focus again just on the second term.

To estimate the last integral in the right-hand side of (8.24), we first observe that the curvature contributions inside the brackets can be bounded by $O(R)$ and, therefore, a posteriori give rise to errors of order $O(Rt)$ for all t small enough, as the integral itself will be shown to be $O(t)$. Thus, we have

$$\begin{aligned} -\frac{1}{2} \int_{\Omega \setminus \Omega_t} u(-\Delta)^{\frac{1}{2}} u_t dx &= \frac{1}{4\pi} \\ &\times \int_{\partial\Omega_t} \int_{\partial\Omega_t} \int_0^{t\rho_t(x)} \int_0^R \frac{u(x + s\nu_t(x))u_t(y - s'\nu_t(y))}{|x - y + s\nu_t(x) + s'\nu_t(y)|^3} ds' ds d\mathcal{H}^1(y) d\mathcal{H}^1(x) \\ &+ O(t^{3/2}R^{-2}) + O(Rt). \end{aligned} \quad (8.25)$$

For $x \in \partial\Omega_t$, we let

$$F(x) := \int_{\partial\Omega_t} \int_0^{t\rho_t(x)} \int_0^R \frac{u(x + s\nu_t(x))u_t(y - s'\nu_t(y))}{|x - y + s\nu_t(x) + s'\nu_t(y)|^3} ds' ds d\mathcal{H}^1(y), \quad (8.26)$$

and split the integral over y into a near-field part

$$F_R(x) := \int_{\partial\Omega_t \cap B_R(x)} \int_0^{t\rho_t(x)} \int_0^R \frac{u(x + s\nu_t(x))u_t(y - s'\nu_t(y))}{|x - y + s\nu_t(x) + s'\nu_t(y)|^3} ds' ds d\mathcal{H}^1(y), \quad (8.27)$$

and the far field part $F(x) - F_R(x)$. As with (8.25), the latter may be estimated to be $O(t^{3/2}R^{-2})$, so we focus on the computation of $F_R(x)$. To that end, we let $y = y(\sigma)$ be the arc-length parametrization of $\partial\Omega_t \cap B_R(x)$ relative to x and observe that

- (i) $(y(\sigma) - x) \cdot \nu_t(x) = O(\sigma^2)$,
- (ii) $\nu_t(x) \cdot \nu_t(y(\sigma)) = 1 + O(\sigma^2)$,
- (iii) $|y(\sigma) - x| = \sigma + O(\sigma^3)$,

uniformly in x and t . Therefore,

$$\begin{aligned} |y(\sigma) - x - s\nu_t(x) - s'\nu_t(y(\sigma))|^2 &= |y(\sigma) - x - (s + s')\nu_t(x) - s'(\nu_t(y(\sigma)) - \nu_t(x))|^2 \\ &= |y(\sigma) - x|^2 + (s + s')^2 - 2(y(\sigma) - x) \cdot \nu_t(x)(s + s') + |s'|^2 |\nu_t(y(\sigma)) - \nu_t(x)|^2 \\ &\quad - 2s'(y(\sigma) - x) \cdot (\nu_t(y(\sigma)) - \nu_t(x)) + 2(s + s')s'\nu_t(x) \cdot (\nu_t(y(\sigma)) - \nu_t(x)) \\ &= \sigma^2 + (s + s')^2 + O(\sigma^4) + O(\sigma^2 R) + O(\sigma^2 R^2) \\ &= (\sigma^2 + (s + s')^2)(1 + O(R)), \end{aligned} \quad (8.28)$$

again, uniformly in x and t , for all R small enough. Thus we have

$$|y(\sigma) - x - s\nu_t(x) - s'\nu_t(y(\sigma))|^{-3} = (\sigma^2 + (s + s')^2)^{-\frac{3}{2}}(1 + O(R)). \quad (8.29)$$

By the uniform convergence of $\partial_\nu^{1/2} u_t$ to $\partial_\nu^{1/2} u$ as $t \rightarrow 0$, and the fact that $\partial_\nu^{1/2} u_t$ is of class $C^\beta(\partial\Omega_t)$ for all $\beta \in (0, 1/2)$ (by Lemma 23), we have that

$$\begin{aligned} u(x + s\nu_t(x)) &= (1 + o_t(1)) \partial_\nu^{1/2} u(x + t\rho_t(x)\nu_t(x)) \sqrt{t\rho_t(x) - s} \\ &= (1 + o_t(1)) \partial_\nu^{1/2} u_t(x) \sqrt{t\rho_t(x) - s} \end{aligned} \quad (8.30)$$

and

$$\begin{aligned} u_t(y(\sigma) - s'\nu_t(y(\sigma))) &= (1 + o_t(1)) \partial_\nu^{1/2} u_t(y(\sigma)) \sqrt{s'} \\ &= (1 + o_t(1) + o_R(1)) \partial_\nu^{1/2} u_t(x) \sqrt{s'}. \end{aligned} \quad (8.31)$$

Plugging (8.29), (8.30) and (8.31) into (8.26), we get

$$F_R(x) = (1 + o_t(1) + o_R(1)) \int_{\sigma_R^-(x)}^{\sigma_R^+(x)} \int_0^{t\rho_t(x)} \int_0^R \frac{|\partial_\nu^{1/2} u_t(x)|^2 \sqrt{(t\rho_t(x) - s)s'}}{(\sigma^2 + (s + s')^2)^{3/2}} ds' ds d\sigma, \quad (8.32)$$

where $\sigma_R^\pm(x) = \pm R + O(R^3)$.

Observe that $F_R(x) = 0$ if $\rho_t(x) = 0$. If $\rho_t(x) > 0$, we can perform the change of variables

$$z = \frac{s}{t\rho_t(x)}, \quad z' = \frac{s'}{t\rho_t(x)}, \quad \zeta = \frac{\sigma}{t\rho_t(x)}, \quad (8.33)$$

to obtain

$$\begin{aligned} F_R(x) &= (1 + o_t(1) + o_R(1)) t\rho_t(x) |\partial_\nu^{1/2} u_t(x)|^2 \\ &\quad \times \int_{\sigma_R^-(x)/(t\rho_t(x))}^{\sigma_R^+(x)/(t\rho_t(x))} \int_0^1 \int_0^{R/(t\rho_t(x))} \frac{\sqrt{(1-z)z'}}{(\zeta^2 + (z+z')^2)^{3/2}} dz' dz d\zeta, \end{aligned} \quad (8.34)$$

which is also valid if $\rho_t(x) = 0$. By Dominated Convergence Theorem, as $t \rightarrow 0$ the integral in the right-hand side converges to

$$\int_{-\infty}^{\infty} \int_0^1 \int_0^{\infty} \frac{\sqrt{(1-z)z'}}{(\zeta^2 + (z+z')^2)^{3/2}} dz' dz d\zeta = 2 \int_0^1 \int_0^{\infty} \frac{\sqrt{(1-z)z'}}{(z+z')^2} dz' dz = \frac{\pi^2}{2}. \quad (8.35)$$

We thus have

$$-\frac{1}{2} \int_{\Omega \setminus \Omega_t} u(-\Delta)^{\frac{1}{2}} u_t dx = (1 + o_t(1) + o_R(1)) \frac{\pi t}{8} \int_{\partial\Omega_t} |\partial_\nu u_t(x)|^2 \rho_t(x) d\mathcal{H}^1(x),$$

so that by the above estimates and the uniform continuity of ρ_t and $\partial_\nu^{1/2} u_t$ in t , we get

$$\lim_{t \rightarrow 0} \frac{J_f(\Omega_t) - J_f(\Omega)}{t} = (1 + o_R(1)) \frac{\pi}{8} \int_{\partial\Omega} |\partial_\nu u(x)|^2 \rho_0(x) d\mathcal{H}^1(x). \quad (8.36)$$

Finally, by (8.17) the thesis follows by sending $R \rightarrow 0$ in (8.36) and Lemma 23. \square

Remark 26. As was mentioned earlier, for bounded domains and under stronger regularity assumptions the result in Theorem 25 was obtained in [8] with a different proof. In [8, Theorem 1], the first variation is stated with a non-explicit constant, but an analysis of the proof shows that their constant agrees with ours, as it should. Our proof exploits the boundary regularity for non-local elliptic problems developed in [33] (see also the survey [32] and [10]), which simplifies the proof even for bounded domains.

We are now in a position to compute the first variation of the functional \mathcal{I}_1 on C^2 -regular bounded sets, and consequently the Euler–Lagrange equation for E_λ for such sets. Recalling (3.6), it is enough to compute the first variation of the $\frac{1}{2}$ -capacity $\text{cap}_1(\Omega)$, which follows directly from Theorem 25, as we show below.

Theorem 27. *Let Ω be a compact set with boundary of class C^2 , let ν be the outward pointing normal vector to $\partial\Omega$ and let u_Ω be the $\frac{1}{2}$ -capacity potential of Ω defined in (3.10). Then, the*

1/2-derivative $\partial_\nu^{1/2} u_\Omega$ is well-defined and belongs to $C^\beta(\partial\Omega)$ for any $\beta \in (0, 1/2)$. Moreover, letting ζ and Φ_t be as in Theorem 25, there holds

$$\left. \frac{d}{dt} \text{cap}_1(\Phi_t(\Omega)) \right|_{t=0} = \frac{\pi}{4} \int_{\partial\Omega} (\partial_\nu^{1/2} u_\Omega(x))^2 \zeta(x) \cdot \nu(x) d\mathcal{H}^1(x). \quad (8.37)$$

Proof. Let $\varphi \in C_c^\infty(\mathbb{R}^2)$ be such that $\varphi = 1$ in an open neighborhood of Ω . Observe that our choice of φ implies that, if

$$f(x) := -(-\Delta)^{\frac{1}{2}} \varphi(x) = -\frac{1}{4\pi} \int_{\mathbb{R}^2} \frac{2\varphi(x) - \varphi(x-y) - \varphi(x+y)}{|y|^3} dy, \quad (8.38)$$

then $\in L^\infty(\mathbb{R}^2) \cap L^{\frac{4}{3}}(\mathbb{R}^2) \cap C^{0,1}(\mathbb{R}^2)$. Notice also that any test function u in the definition of $\text{cap}_1(\Omega)$ such that $u = 1$ on Ω can be put in correspondence with a test function $v = u - \varphi$ in the definition of the auxiliary functional $I_{\Omega^c, f}$ in (8.1). Moreover, since

$$\frac{1}{2} \|u\|_{\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)}^2 = \frac{1}{2} \|v\|_{\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)}^2 + \frac{1}{2} \|\varphi\|_{\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)}^2 - \int_{\mathbb{R}^2} v f dx, \quad (8.39)$$

we get that

$$\frac{1}{2} \text{cap}_1(\Omega) = \frac{1}{2} \|\varphi\|_{\dot{H}^{\frac{1}{2}}(\mathbb{R}^2)}^2 + J_f(\Omega^c), \quad (8.40)$$

and the minimizer u_Ω satisfies $u_\Omega = v_{\Omega^c, f} + \varphi$, where $v_{\Omega^c, f}$ is the minimizer of $I_{\Omega^c, f}$. Observing also that $\partial_\nu^{1/2} u_\Omega = \partial_\nu^{1/2} v_{\Omega^c, f}$, the conclusion follows by Theorem 25. \square

Finally, Theorem 7 is a direct consequence of Theorem 27, together with (3.6) and (3.10).

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