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ON THE EXTENSION PROBLEM FOR SEMICONCAVE FUNCTIONS WITH FRACTIONAL MODULUS

PAOLO ALBANO, VINCENZO BASCO, AND PIERMARCO CANNARSA

ABSTRACT. Consider a locally Lipschitz function u on the closure of a possibly unbounded open subset Ω of \mathbb{R}^n with nonempty boundary. Suppose u is (locally) semiconcave on $\overline{\Omega}$ with a fractional semiconcavity modulus. Is it possible to extend u in a neighborhood of any boundary point retaining the same semiconcavity modulus? We show that this is indeed the case and we give two applications of this extension property. First, we derive an approximation result for semiconcave functions on closed domains. Then, we use the above extension property to study the propagation of singularities of semiconcave functions at boundary points.

1. Introduction and statement of the results

Semiconcave functions are an important class of nonsmooth functions that relaxes the classical notion of concavity allowing for localization, but preserves the main properties of concave functions. Such a class has many applications in analysis and geometry, see [6] and [9].

When semiconcave functions are assumed to have linear modulus, their structure is particularly appealing as they can be locally represented as the sum of a concave function plus a smooth remainder. However, such a representation fails if the modulus is fractional, even though many other properties remain true. On the other hand, fractionally semiconcave functions are interesting in their own right. For instance, value functions of constrained variational problems have been proved to be semiconcave with fractional modulus (see [5]), while linear semiconcavity cannot be expected (see [7]).

This paper is concerned with the classical extension problem, that we set and solve in the class of fractionally semiconcave functions.

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We observe that, in the case of a semiconcave functions with linear modulus, a local extension property, near a boundary point of a convex set, was established in [2, Proposition 3.1].

We give two extension results: a local one, showing that in this case the set of reachable gradients is preserved, and a global one. Then, we deduce an approximation theorem for a semiconcave function on a closed domain and we study the propagation of singularities from a boundary point.

We now proceed to describe the problem in detail and outline our main results.

1.1. Semiconcave functions with fractional modulus. Let $A \subset \mathbb{R}^n$ $(n \geq 1)$, a function $u: A \longrightarrow \mathbb{R}$ is semiconcave with a fractional modulus of semiconcavity if it is locally Lipschitz continuous¹ and there exist $\alpha \in]0,1]$ and $C=C_A \in \mathbb{R}$ such that

$$(1.1) \ \lambda u(x) + (1 - \lambda)u(y) - u(\lambda x + (1 - \lambda)y) \le C\lambda(1 - \lambda)|x - y|^{1 + \alpha},$$

for any $x, y \in A$ such that the line segment [x, y] is contained in A and for every $\lambda \in [0, 1]$. Furthemore, we call any constant $C \in \mathbb{R}$, for which (1.1) holds true, a semiconcavity constant for u in A. Finally, we define

$$SC^{\alpha}_{loc}(A)=\{u:A\longrightarrow \mathbb{R}:u \text{ is locally Lipschitz on }A \text{ and }u \text{ satisfies (1.1) on every compact subset of }A\}$$

(in the above definition the constant C may depend on the compact set under exam).

1.2. The extension problem. For $x_0 \in \mathbb{R}^n$ and $\delta > 0$, we denote by $B_{\delta}(x_0)$ the open ball with center at x_0 and radius δ . Let $\Omega \subset \mathbb{R}^n$ be an open set with nonempty boundary.

We study the following problem: given $u \in SC_{loc}^{\alpha}(\overline{\Omega})$ and a boundary point $x_0 \in \partial\Omega$, is there a function E(u) defined on $B_{\delta}(x_0)$ (for a suitable $\delta > 0$), such that

$$E(u) \in SC^{\alpha}(B_{\delta}(x_0))$$
 and $E(u)(x) = u(x)$, for every $x \in B_{\delta}(x_0) \cap \overline{\Omega}$?

For some of the applications we have in mind we will need E(u) to satisfy the additional condition we are going to describe. For $x \in \overline{\Omega}$,

¹We observe that if A is an open set, then u is locally Lipschitz continuous on A (see e.g. [6]). We are requiring the local Lipschitz regularity of u since we are not assuming that A be an open set.

we define the set of reachable (or, achievable) gradients of u at x by

(1.2)
$$D^*u(x) = \{ p \in \mathbb{R}^n : p = \lim_{h \to \infty} Du(x_h), \Omega \ni x_h \to x,$$

 $u \text{ differentiable at } x_h \}.$

Notice that $D^*u(x) \neq \emptyset$ for all $x \in \overline{\Omega}$ owing to Rademacher's Theorem. Furthermore, for every $x \in \overline{\Omega}$ and for every $p \in D^*u(x)$,

(1.3)
$$u(y) \le u(x) + \langle p, y - x \rangle + C|y - x|^{1+\alpha},$$

for every $y \in \overline{\Omega}$ such that $[x, y] \subset \overline{\Omega}$. Then, we would like to find a local extension of u with the additional property

$$(1.4) D^*E(u)(x) = D^*u(x), \quad \forall x \in B_{\delta}(x_0) \cap \partial\Omega.$$

Remark 1.1. We point out that property (1.4) is useful in the analysis of the singularities (i.e. the points of nondifferentiability) of u.

Let us state our local extension result:

Theorem 1.1. Let $\Omega \subset \mathbb{R}^n$ be an open set with nonempty boundary, and let $u \in SC^{\alpha}_{loc}(\overline{\Omega})$. Then, for every $x \in \partial \Omega$ and for every $\delta > 0$ there exist a function $E(u) \in SC^{\alpha}(B_{\delta}(x))$ such that

- (1) E(u)(y) = u(y) for every $y \in B_{\delta}(x) \cap \overline{\Omega}$;
- (2) $D^*E(u)(y) = D^*u(y)$ for every $y \in B_{\delta}(x) \cap \partial\Omega$.

Furthermore, denoting by C a semiconcavity constant for u in $B_{\delta}(x) \cap \overline{\Omega}$, we have that there is C_E , a semiconcavity constant for E(u) in $B_{\delta}(x)$, with

(1.5)
$$C_E \le (C+1)(1+\alpha)(1+2^{2-\alpha}).$$

Remark 1.2.

- (i) A first version of this extension result was established in [2] in the special case of $\alpha = 1$ with Ω convex. While the result in [2] was motivated by the study of the boundary behavior of the singularities of solutions to first order Hamilton-Jacobi equations with Dirichlet boundary conditions, Theorem 1.1 is intended for different boundary data such as those which fit optimal control problems with state constraints.
- (ii) The extension E(u) given in the proof of Theorem 1.1 is not unique (see Remark 2.5 below).

Given a set A we denote by co A the convex hull of A. A global version of Theorem 1.1 is obtained as follows:

Theorem 1.2. Let $\Omega \subset \mathbb{R}^n$ be an open set with nonempty boundary, and let $u \in SC^{\alpha}_{loc}(\overline{\Omega})$. Then, there exist an open subset $\Omega' \supset \Omega$ and a function $E(u) \in SC^{\alpha}_{loc}(\Omega')$ such that

- (1) E(u)(x) = u(x) for every $x \in \overline{\Omega}$;
- (2) co $D^*E(u)(x) = \operatorname{co} D^*u(x)$ for every $x \in \partial \Omega$.

Remark 1.3. We observe that, in Theorem 1.2, Ω may be unbounded. If we assume that Ω is a bounded set then one can obtain some stronger results:

(i) taking $x_0 \in \partial \Omega$ and $\delta > 0$ so that $\overline{\Omega} \subset B_{\delta}(x_0)$, and using Theorem 1.1 we find an extension of u, E(u), such that

$$D^*E(u)(x) = D^*u(x), \quad \forall x \in \partial\Omega,$$

instead of the weaker conclusion (2) in Theorem 1.2.

- (ii) u can be extended as a semiconcave function on the whole space. (This property can be justified by a cut-off argument.)
- 1.3. **Approximation.** A first application of Extension Theorem 1.1 is the following local approximation result

Theorem 1.3. Let $u \in SC^{\alpha}_{loc}(\overline{\Omega})$ and let $x_0 \in \partial\Omega$. Then there exist $\delta > 0$ and a sequence of functions $u_h \in C^{\infty}_0(B_{\delta}(x_0))$, $h \in \mathbb{N}$, such that

- (1) u_h uniformly converges to u on $B_{\delta/2}(x_0) \cap \bar{\Omega}$ as $h \to \infty$;
- (2) denoting by C a semiconcavity constant for an extension of u on $B_{\delta}(x_0)$, we have that

$$\lambda u_h(x_1) + (1 - \lambda)u_h(x_2) - u_h(\lambda x_1 + (1 - \lambda)x_2)$$

$$\leq C\lambda(1 - \lambda)|x_1 - x_2|^{1+\alpha},$$

for every $\lambda \in [0,1]$ and $x_1, x_2 \in B_{\delta/2}(x_0)$.

We observe that a global version of the above result can be given as follows.

Theorem 1.4. Let $u \in SC_{loc}^{\alpha}(\overline{\Omega})$. Then there exist an open set $\Omega' \supset \overline{\Omega}$ and a sequence of functions $u_h \in C^{\infty}(\Omega')$, $h \in \mathbb{N}$, such that

- (1) u_h uniformly converges to u locally uniformly on $\overline{\Omega}$, as $h \to \infty$;
- (2) for every compact set $K \subset \Omega'$ denoting by C a semiconcavity constant, on K, for the extension of u given by Theorem 1.2, we have that

$$\lambda u_h(x_1) + (1 - \lambda)u_h(x_2) - u_h(\lambda x_1 + (1 - \lambda)x_2)$$

$$\leq C\lambda(1 - \lambda)|x_1 - x_2|^{1+\alpha},$$

for every $\lambda \in [0,1]$ and $x_1, x_2 \in K$ such that $[x_1, x_2] \subset K$.

Remark 1.4. It is worth noting that, in the case of $\alpha = 1$, Theorem 1.4 ensures the existence of an approximating sequence satisfying, on every compact set $K \subset \Omega'$,

$$D^2 u_h < C \cdot I \qquad \forall h \in \mathbb{N}.$$

where C is a semiconcavity constant for E(u) on K.

1.4. Singularities. Let us introduce the singular set of u:

$$\Sigma(u) = \{x \in \overline{\Omega} : D^*u(x) \text{ has at least two elements} \}.$$

We observe that, for $x \in \Omega$, $x \in \Sigma(u)$ if and only if u is not differentiable at x. Given a set A the symbol ∂A stands for the topological boundary of A.

We have the following

Theorem 1.5. Let Ω be an open set with nonempty boundary, let $u \in SC^{\alpha}_{loc}(\overline{\Omega})$ and let $x_0 \in \partial \Omega$ such that

$$(1.6) \partial \operatorname{co} D^* u(x_0) \setminus D^* u(x_0) \neq \emptyset.$$

Let $p_0 \in \operatorname{co} D^*u(x_0) \setminus D^*u(x_0)$ and let $-\theta$ be a vector in the normal cone to $\operatorname{co} D^*u(x_0)$ at p_0 . Let $E(u) \in SC^{\alpha}(B_{\delta}(x_0))$ be an extension of u satisfying property (2) of Theorem 1.1. Then, there is a map

$$[0,\sigma] \ni s \mapsto x(s) \in B_{\delta}(x_0)$$

(depending on E(u)) such that

- (1) $x(0) = x_0$ and $\lim_{s\to 0^+} x(s) = x_0$;
- (2) $x(s) \neq x_0$, for every $s \in [0, \sigma]$;
- (3) $x(s) \in \Sigma(E(u))$, for every $s \in [0, \sigma]$;
- (4) $x(s) = x_0 + s\theta + o(s)$ with $o(s)/s \to 0$ as $s \to 0^+$,

for a suitable $\sigma > 0$ depending on the "initial" point x_0 .

Since u is semiconcave, the set co $D^*u(x)$ above coincides with the superdifferential of u at x, $D^+u(x)$, for all $x \in \Omega$. See [6] for more details.

2. Proof of Theorems 1.1 and 1.2

2.1. Proof of Theorem 1.1. Let $x_0 \in \partial \Omega$, $\delta > 0$, and set

$$A := \Omega \cap B_{\delta}(x_0).$$

Let C > 0 be a semiconcavity constant for u in \bar{A} and define

(2.1)
$$E(u)(x) = \inf_{y \in \bar{A}, p \in D^*u(y)} \left[u(y) + \langle p, x - y \rangle + (C+1)|x - y|^{1+\alpha} \right],$$

for $x \in B_{\delta}(x_0)$. We claim that E(u) satisfies all the properties stated in Theorem 1.1.

- (I) E(u) IS A SEMICONCAVE FUNCTION IN $SC^{\alpha}(B_{\delta}(x_0))$. Indeed, by the definition, we have that
 - (1) $C^{1,\alpha} \subset SC^{\alpha}$ (this is a direct consequence of the Taylor formula, the semiconcavity constant C can be taken greater of equal to the Hölder seminorm of the gradient);
 - (2) if I is a set of indices and $\{f_i\}_{i\in I}$ is a family of semiconcave functions satisfying (1.1) with the same C, then $\inf_{i\in I} f_i$ is a semiconcave function with the same constant C (this follows by (1.1) and the definition of infimum);
 - (3) the sum of semiconcave functions is a semiconcave function (also this fact is a direct consequence of the definition (1.1)).

Now, let us define

$$K = \{(y, p) : y \in \bar{A} \text{ and } p \in D^*u(y)\}.$$

We observe that K is a compact nonempty set. Indeed K is a bounded set (D^*u) is bounded, by the local Lipschitz continuity of u) and it is a closed set (if $(y_h, p_h) \in K$ converges to (y, p) then $y \in \bar{A}$ and, by a diagonal argument based on the Rademacher Theorem, we deduce that there exists a sequence $y_j \in \bar{A} \setminus \Sigma(u)$, such that $(y_j, Du(y_j)) \to (y, p)$, i.e. $(y, p) \in K$).

Then, for every $(y, p) \in K$ the function $B_{\delta}(x_0) \ni x \mapsto u(y) + \langle p, x - y \rangle$ is concave while, for every $y \in \bar{A}$, the function $B_{\delta}(x_0) \ni x \mapsto C|x - y|^{1+\alpha}$ is of class $C^{1,\alpha}$. Let us estimate the Hölder seminorm of the derivative of the last function. For every $y \in \bar{A}$, set

$$v_y(x) = C|x - y|^{1+\alpha} \quad (x \in B_{\delta}(x_0)).$$

Then,

$$Dv_y(x) = \begin{cases} C(1+\alpha)|x-y|^{\alpha-1}(x-y), & \text{if } x \in B_\delta(x_0) \setminus \{y\}, \\ 0, & \text{if } x = y, \end{cases}$$

and, for every $x, z \in B_{\delta}(x_0)$, we have that

(2.2)
$$Dv_y(x) - Dv_y(z)$$

= $C(1+\alpha) (|x-y|^{\alpha-1}(x-y) - |z-y|^{\alpha-1}(z-y)).$

We may assume that

$$(2.3) |x-y| \le |z-y|.$$

If x = y, by (2.2), we deduce that

$$(2.4) |Dv_{y}(x) - Dv_{y}(z)| \le C(1+\alpha)|x-z|^{\alpha}.$$

Furthermore, for any $x \neq y$, we have

$$|Dv_{u}(x) - Dv_{u}(z)|$$

$$= C(1+\alpha) \left| (|x-y|^{\alpha} - |z-y|^{\alpha}) \frac{x-y}{|x-y|} + |z-y|^{\alpha} \left(\frac{x-y}{|x-y|} - \frac{z-y}{|z-y|} \right) \right|$$

$$\leq C(1+\alpha) \left(|x-z|^{\alpha} + \frac{|z-y|^{\alpha}}{|x-y|} [|z-y|(x-y) - |x-y|(z-y)] \right).$$

Now, using the elementary inequality

$$||z - y|(x - y) - |x - y|(z - y)|$$

$$= |(|z - y| - |x - y|)(x - y) + |x - y|(x - z)|$$

$$\leq 2|x - y| |x - z|,$$

we find that

$$|Dv_y(x) - Dv_y(z)| \le C(1+\alpha)|x-z|^{\alpha} \left\{ 1 + 2\left(\frac{|x-z|}{|z-y|}\right)^{1-\alpha} \right\}.$$

By (2.3), we have that

$$\frac{|x-z|}{|z-y|} \le \frac{|x-y| + |y-z|}{|z-y|} \le 2$$

and, recalling (2.4), we conclude that

$$|Dv_y(x) - Dv_y(z)| \le C(1+\alpha)(1+2^{2-\alpha})|x-z|^{\alpha}, \quad \forall x, z \in B_{\delta}(x_0).$$

Hence, by (1), (3) and (2) above, we deduce that $E(u) \in SC^{\alpha}(B_{\delta}(x_0))$ and that $(C+1)(1+\alpha)(1+2^{2-\alpha})$ is a semiconcavity constant for E(u) on $B_{\delta}(x_0)$.

(II)
$$E(u)(x) = u(x)$$
, for every $x \in \bar{A}$.

Indeed, let $x \in \bar{A}$. Then, by taking y = x in the definition of E(u), we find that $E(u)(x) \le u(x)$. On the other hand, by (1.3),

$$u(x) \le u(y) + \langle p, x - y \rangle + (C+1)|x - y|^{1+\alpha},$$

for every $y \in \bar{A}$, i.e. $u(x) \leq E(u)(x)$ and the conclusion follows.

(III)
$$D^*E(u)(x) = D^*u(x)$$
, for every $x \in B_{\delta}(x_0) \cap \partial\Omega$.

It suffices to show that $D^*E(u)(x) \subseteq D^*u(x)$ for every $x \in B_{\delta}(x_0) \cap \partial \Omega$. For this purpose, fix $x \in B_{\delta}(x_0) \cap \partial \Omega$ and let $p \in D^*E(u)(x)$. Without loss of generality, we suppose there is a sequence $x_h \in B_{\delta}(x_0) \setminus \overline{\Omega}$, $h \in \mathbb{N}$, such that $x_h \to x$, E(u) is differentiable at x_h , and $DE(u)(x_h) \to 0$

8

p (indeed, for otherwise the conclusion would be trivial). We have to show that $p \in D^*u(x)$.

Since K is a compact set, there exists $(y_h, p_h) \in K$ such that

- (1) $(y_h, p_h) \to (y_0, p_0) \in K$, for a suitable (y_0, p_0) ;
- (2) $E(u)(x_h) = u(y_h) + \langle p_h, x_h y_h \rangle + (C+1)|x_h y_h|^{1+\alpha};$
- (3) $DE(u)(x_h) = p_h + (C+1)(1+\alpha)|x_h y_h|^{\alpha-1}(x_h y_h).$

Then, by (1) and (3) above, we find that

(2.5)
$$p = p_0 + (C+1)(1+\alpha)|x-y_0|^{\alpha-1}(x-y_0)$$

and, by (2),

$$(2.6) u(x) = E(u)(x) = u(y_0) + \langle p_0, x - y_0 \rangle + (C+1)|x - y_0|^{1+\alpha}.$$

Then, by (2.6) and (1.3), we deduce that

$$u(x) \ge u(x) + |x - y_0|^{1+\alpha} \implies x = y_0.$$

Hence, by (2.5), we find that $p = p_0 \in D^*u(x)$. This completes our proof.

- **Remark 2.5.** We observe that the extension, E(u), given by Formula (2.1), is not unique. Indeed, the coefficient C + 1 in the definition of E(u) is not uniquely determined (C + 1) can be replaced by any number greater than a given semiconcavity constant for u).
- 2.2. **Proof of Theorem 1.2.** Not surprisingly, the idea of the proof consists of using a partition of unity in order to glue together the local extensions given by Theorem 1.1. However, this procedure provides just a global semiconcave extension of u, but yields no information on $D^*E(u)$ at boundary points. For this purpose, we need an extra argument which represents the main point of the proof.

We observe that, by Theorem 1.1, for every $x \in \partial \Omega$ there exist $B_{\delta_x}(x)$ and an extension $E_x(u)$ on $B_{\delta_x}(x)$ such that $D^*u(y) = D^*E_x(u)(y)$, for every $y \in \partial \Omega \cap B_{\delta_x}(x)$. Define

$$\Omega' := \cup_{x \in \partial \Omega} B_{\delta_x}(x) \cup \Omega.$$

Then $\{B_{\delta_x}(x)\}_{x\in\partial\Omega}\cup\{\Omega\}$ is a covering of Ω' . Let $\{\chi_j\}_{j\in\mathbb{N}}$ be a partition of unity subordinate to such a covering, that is, a countable family of smooth functions satisfying the following:

- (A) $0 \le \chi_j \le 1$ for all j and all $y \in \Omega'$;
- (B) every $y \in \Omega'$ has a neighborhood on which all but finitely many functions χ_j are identically zero;
- (C) each function χ_j is identically zero except on some closed set contained in one of the open sets of the cover;
- (D) $\sum_{j} \chi_{j}(y) = 1$ for every $y \in \Omega'$.

(The existence of $\{\chi_j\}_{j\in\mathbb{N}}$ is well-known, see, e.g., page 52 of [8].) Let

$$J = \{ j \in \mathbb{N} \mid \exists x \in \partial \Omega : \operatorname{supp} \chi_j \subset B_{\delta_x}(x) \}.$$

For every $j \in J$, we define $E_j(u) \in SC^{\alpha}(B_{\delta_x}(x))$ to be the extension of u to the ball $B_{\delta_x}(x)$, containing supp χ_j , which is given by Theorem 1.1, for $j \in J$. Set

(2.7)
$$E(u)(y) := \sum_{j \in J} \chi_j(y) E_j(u)(y) + \sum_{j \in \mathbb{N} \setminus J} \chi_j(y) u(y), \quad y \in \mathbb{R}^n.$$

We observe that, by Condition (D) above, we deduce

$$E(u)(y) = \sum_{j \in \mathbb{N}} \chi_j(y) u(y) = u(y), \quad \forall y \in \overline{\Omega}.$$

Furthermore, we have that $E(u) \in SC^{\alpha}_{loc}(\Omega')$. Indeed, let $K \subset \Omega'$ be a compact set. Then, by Condition (B) above, only for finitely many j supp $\chi_j \cap K \neq \emptyset$ (i.e. the sum in (2.7) is finite). Then, recalling that the product of a smooth nonnegative function with a semiconcave one is semiconcave and that the sum of finitely many semiconcave functions is a semiconcave function, we deduce that $E(u) \in SC^{\alpha}(K)$.

In order to complete our proof, it remains to show that, for every $x \in \partial\Omega$, co $D^*E(u)(x) = \operatorname{co} D^*u(x)$. We observe that, by construction, $D^*E(u)(x) \supset D^*u(x)$. Then, our proof reduces to show that

(2.8)
$$D^*E(u)(x) \subset \operatorname{co} D^*u(x), \quad \forall x \in \partial \Omega.$$

Then, let $x \in \partial\Omega$ and let $x_h \in \Omega' \setminus \overline{\Omega}$, $h \in \mathbb{N}$, be a sequence of points of differentiability for E(u) such that x_h converges to x and $DE(u)(x_h)$ converges to a suitable vector p. Hence, the proof reduces to show that $p \in \operatorname{co} D^*u(x)$. We observe that the sum, in the definition of E(u), is a finite sum (on a compact set only finitely many j are involved, say j_1, \ldots, j_s).

Let us suppose that

(2.9) each
$$E_{j_k}(u)$$
 is differentiable at x_h , for every h and

$$k = 1, ..., s$$
.

Then, we find that

(2.10)
$$D(\chi_{j_k} E_{j_k}(u))(x_h)$$

= $D\chi_{j_k}(x_h) E_{j_k}(u)(x_h) + \chi_{j_k}(x_h) DE_{j_k}(u)(x_h).$

Hence, taking the sum w.r.t. k in both the sides of the identity (2.10), and recalling Condition (D) above, we deduce that

$$DE(u)(x_h) = \sum_{k=1}^{s} \chi_{j_k}(x_h) DE_{j_k}(u)(x_h).$$

Then, possibly taking a subsequence of x_h , we may assume that, as $h \to \infty$, $DE_{j_k}(u)(x_h)$ converges to a suitable p_k , with $p_k \in D^*u(x)$ (by Theorem 1.1), i.e. we conclude that

$$p = \sum_{k=1}^{s} \chi_{j_k}(x) p_k \in \text{co } D^*u(x).$$

It remains to discuss Assumption (2.9) which, as shown in the next result, is automatically satisfied.

Lemma 2.1. Let $v_1, \ldots, v_\ell \in SC^{\alpha}(B)$, for suitable $\ell \in \mathbb{N}$, $\alpha \in]0,1]$ and $B \subset \mathbb{R}^n$. Then, if $\sum_{j=1}^{\ell} v_j$ is differentiable at x_0 , then each v_j is differentiable at x_0 .

Proof. It suffices to verify the statement in the case of $\ell=2$ (being the general case a direct consequence of an elementary argument by induction). We have that

$$v_1(x) = (v_1(x) + v_2(x)) + (-v_2(x))$$

and we observe that $-v_2$ is a semiconvex function. Then, we find that

$$D^+v_1(x_0) = D(v_1 + v_2)(x_0) + D^+(-v_2)(x_0).$$

(Here, we are using a calculus rule for the superdifferential which applies because of we are assuming that $v_1 + v_2$ is differentiable at x_0 .) Hence, we deduce that $D^+(-v_2)(x_0)$ is nonempty if and only if $-v_2$ is differentiable at x_0 (see e.g. [6]). Then, we deduce that v_1 and v_2 are differentiable at x_0 .

This completes our proof.

3. Examples

In order to clarify that the key information provided by Theorem 1.5 is a direction of "propagation" θ , let us give some examples. We begin by showing that, under Condition (1.6), a singularity may propagate in the exterior of the set Ω .

Example 1. Let $\Omega \subset \{(x_1, x_2) \in \mathbb{R}^2 \mid x_1 > 0\}$ be an open set, with nonemtpy boundary, such that

$$\Omega \supset \{(x_1, x_2) \in \mathbb{R}^2 \mid x_1 > 0 \text{ and } x_1^2 + x_2^2 < 1\},$$

and let

$$u(x) = -|x|, \quad \forall x \in \bar{\Omega}.$$

Let us compute $D^*u(0)$. For $x \in \Omega$, we have

$$Du(x) = -\frac{x}{|x|}.$$

For every unit vector $v = (v_1, v_2)$, with $v_1 > 0$, let $x_h \in \Omega$ be such that

$$x_h \to 0$$
 and $\frac{x_h}{|x_h|} \to v$, as $h \to \infty$.

Then, we find that $Du(x_h) = -x_h/|x_h| \to -v$, as $h \to \infty$, i.e.

$$D^*u(0) = \{ p \in \mathbb{R}^2 \mid |p| = 1 \text{ and } p_1 \le 0 \}.$$

(In the last identity we used the fact that D^*u is a closed set.) Furthermore, we have that

$$co D^*u(0) \setminus D^*u(0) = \{ p \in \mathbb{R}^2 \mid |p| < 1 \text{ and } p_1 \le 0 \} \ne \emptyset$$

and that, by Theorem 1.5 with $p_0 = 0$ and $\theta = (-1, 0)$, we deduce that the singularity at 0 propagates along the negative x_1 axis. Let us verify the propagation result by a direct computation of the extension E(u). We point out that, since u is a concave function, we can take C = 0 in the definition of E(u) (2.1). We have that

$$= \inf \left(\{ \langle \eta, x \rangle + |x|^2 \mid \text{ for } |\eta| = 1, \, \eta_1 \le 0 \} \right.$$
$$\left. \cup \{ -|y| - \frac{1}{|y|} \langle y, x - y \rangle + |x - y|^2 \mid \text{ for } 0 < |y| \le 1, \, y_1 \ge 0 \} \right).$$

In order to evaluate the infimum above, we observe that

$$(3.11) -|y| - \frac{1}{|y|} \langle y, x - y \rangle + |x - y|^2 = -\frac{1}{|y|} \langle y, x \rangle + |x - y|^2$$

and that, since $x_1 < 0$ and $y_1 \ge 0$,

$$-\frac{1}{|y|}\langle y, x \rangle \ge -|x_2|.$$

(Analogously we have that $\langle \eta, x \rangle \geq -|x_2|$.) Then, we find that

(3.12)
$$E(u)(x) \ge -|x_2| + x_1^2$$
 for $x \in B_1(0)$ with $x_1 < 0$

Hence, by (3.12) and (3.11) with $y = (0, x_2)$, we conclude that

$$E(u)(x) = \begin{cases} -|x|, & \text{for } x \in B_1(0) \text{ with } x_1 \ge 0, \\ -|x_2| + x_1^2 & \text{for } x \in B_1(0) \text{ with } x_1 < 0. \end{cases}$$

Let us remark that, even if u is a concave function in Ω , we have that $E(u) \in SC^1(B_1(0))$ is not concave (in particular $u(x) \neq -|x|$, for $x \in B_1(0)$ with $x_1 < 0$).

In the second example we show that Condition (1.6) can be satisfied and a singularity may propagate in the interior of the set Ω .

Example 2. Let $\Omega \subset \{(x_1, x_2) \in \mathbb{R}^2 \mid x_1 > 0\}$ be an open set, with nonempty boundary, such that

$$\Omega \supset \{(x_1, x_2) \in \mathbb{R}^2 \mid x_1 > 0 \text{ and } x_1^2 + x_2^2 < 1\},$$

and let

$$u(x) = -|x_2|, \quad \forall x \in \bar{\Omega}.$$

Then, we find that

$$D^*u(0) = \{(0, p_2) \in \mathbb{R}^2 \mid p_2 = \pm 1\}$$

and

$$co D^*u(0) \setminus D^*u(0) = \{0\} \times [-1, 1] \setminus \{(0, \pm 1)\} = \{0\} \times [-1, 1] \neq \emptyset.$$

Even if in this example it is clear that and that all the points of the form $(x_1, 0)$ are points of nondifferentiability for u, we observe that one may apply Theorem 1.5 with $p_0 = 0$ and $\theta = (1, 0)$ to deduce that the singularity at 0 propagates in the interior of the set Ω .

Let us also observe that

$$E(u)(x) = \begin{cases} -|x_2|, & \text{for } x \in B_1(0) \text{ with } x_1 \ge 0, \\ -|x_2| + x_1^2, & \text{for } x \in B_1(0) \text{ with } x_1 < 0. \end{cases}$$

In the next example we show that Assumption (1.6) is only a sufficient condition for the propagation of singularities.

Example 3. Let $\Omega \subset \{(x_1, x_2) \in \mathbb{R}^2 \mid x_1 > 0\}$ be an open set, with nonempty boundary, such that

$$\Omega \supset \{(x_1, x_2) \in \mathbb{R}^2 \mid x_1 > 0 \text{ and } x_1^2 + x_2^2 < 1\},$$

and let

$$u(x) = -\sqrt{x_1^4 + x_2^2}, \qquad \forall x \in \bar{\Omega}.$$

Then, we find that

$$D^*u(0) = \{0\} \times [-1,1]$$

and

$$\operatorname{co} D^*u(0) \setminus D^*u(0) = \emptyset.$$

Let $x \in B_1(0)$ with $x_1 < 0$, we have

$$E(u)(x) = \inf_{y \in B_1(0), y_1 \ge 0, p \in D^*u(y)} \left[-\sqrt{y_1^4 + y_2^2} + \langle p, x - y \rangle + |x - y|^2 \right]$$

$$\leq \inf_{p_2, y_2 \in [-1, 1]} \left[-|y_2| + p_2(x_2 - y_2) + x_1^2 + (x_2 - y_2)^2 \right] \le -|x_2| + x_1^2.$$

Furthermore, if either $y_1 > 0$ (i.e. $x_1y_1 < 0$) or $y_1 = 0$ and $y_2 \neq 0$, we have

$$-\sqrt{y_1^4 + y_2^2} - \frac{1}{\sqrt{y_1^4 + y_2^2}} \langle (2y_1^3, y_2), x - y \rangle + |x - y|^2$$

$$= \frac{y_1^4 - x_2 y_2 - 2x_1 y_1^3}{\sqrt{y_1^4 + y_2^2}} + |x - y|^2$$

$$\geq \frac{-x_2 y_2}{\sqrt{y_1^4 + y_2^2}} + |x - y|^2$$

$$\geq -|x_2| + |x - y|^2 \geq -|x_2| + x_1^2.$$

Finally, if y = 0 and $p \in D^*u(0)$, we find

$$-\sqrt{y_1^4 + y_2^2} + \langle p, x - y \rangle + |x - y|^2 \ge -|x_2| + |x|^2.$$

Then, we conclude that, for $x \in B_1(0)$,

$$E(u)(x) = \begin{cases} -\sqrt{x_1^4 + x_2^2}, & \text{if } x_1 \ge 0\\ -|x_2| + x_1^2, & \text{if } x_1 < 0. \end{cases}$$

In other words, condition (1.6) is not satisfied but the singularity of u at the origin propagates along the negative x_1 axis.

4. Proof of Theorems 1.3, 1.4 and 1.5.

4.1. **Proof of Theorems 1.3 and 1.4.** We provide the proof only of the local approximation result Theorem 1.3. We point out that the proof of Theorem 1.4 follows exactly the same lines using Theorem 1.2 instead of the local extension result.

Fix $x_0 \in \partial\Omega$. Let $\delta > 0$ and E(u) the number and the extension given by Theorem 1.1 respectively. Let $\chi \in C_0^{\infty}(B_1(0))$ be a nonnegative function such that $\int \chi dx = 1$ and define

(4.13)
$$u_h(x) = \int E(u)(x + y/h)\chi(y) \, dy,$$

where $h > \frac{2}{\delta}$ is a positive integer. We observe that

$$|x + y/h - x_0| \le \delta$$

for every $x \in B_{\delta/2}(x_0)$ and $y \in B_1(0)$. Then u_h is well-defined for $x \in B_{\delta/2}(x_0)$ and $u_h \to u$ uniformly on $\bar{B}_{\delta/2}(x_0) \cap \bar{\Omega}$. In order to complete our proof it remains to show that u_h satisfies a uniform semiconcavity estimate. Let $\lambda \in [0,1]$ and $x_1, x_2 \in B_{\delta/2}(x_0)$, then we have

$$\lambda u_h(x_1) + (1 - \lambda)u_h(x_2) - u_h(\lambda x_1 + (1 - \lambda)x_2)$$

$$= \int [\lambda E(u)(x_1 + y/h) + (1 - \lambda)E(u)(x_2 + y/h)$$

$$- E(u)(\lambda x_1 + (1 - \lambda)x_2 + y/h)] \chi(y) dy \le C\lambda(1 - \lambda)|x_1 - x_2|^{1+\alpha}.$$

This completes our proof.

4.2. **Proof of Theorem 1.5.** The proof is based on an abstract propagation result given in [1] (see also [3] for an earlier form of the result).

Let $x_0 \in \partial\Omega \cap \Sigma(u)$, in particular the set $D^*u(x_0)$ has at least two elements. Let us consider the extension given by Theorem 1.1. We have that

$$(4.14) D^{+}E(u)(x_{0}) = \operatorname{co} D^{*}E(u)(x_{0}) (= \operatorname{co} D^{*}u(x_{0})).$$

By Assumption (1.6), there exist $p_0 \in \partial D^+ E(u)(x_0) \setminus D^* E(u)(x_0)$ and a vector $-\theta$ in the normal cone to $D^+ E(u)(x_0)$ at p_0 .

Then, by Theorem 4.2. of [1], we deduce that there exist a positive number σ and a map $[0, \sigma] \ni s \to x(s)$ such that

- (1) $x(0) = x_0$ and $\lim_{s\to 0} x(s) = x_0$;
- (2) $x(s) \neq x_0$, for every $s \in [0, \sigma]$;
- (3) $x(s) \in \Sigma(E(u))$, for every $s \in [0, \sigma]$;
- (4) $x(s) = x_0 + s\theta + o(s)$ with $o(s)/s \to 0$ as $s \to 0^+$.

This completes our proof.

5. Declarations

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Dipartimento di Matematica, Università di Bologna, Piazza di Porta San Donato 5, 40127 Bologna, Italy

Email address: paolo.albano@unibo.it

Thales Alenia Space, via Saccomuro 24, Roma, Italy.

Email address: vincenzo.basco@thalesaleniaspace.com

Email address: vincenzobasco@gmail.com

DIPARTIMENTO DI MATEMATICA, UNIVERSITÀ DI ROMA "TOR VERGATA", ROMA, ITALY

Email address: cannarsa@mat.uniroma2.it