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On The Parametrizations for the Dissipation Rate of the Turbulence Kinetic Energy in Stable Conditions

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Abstract

Observations acquired in the stable surface layer during two field experiments (The Mountain Terrain Atmospheric Modeling and Observations Program and the Climate Change Tower Integrated Project) are considered to test different parametrizations of the dissipation rate of turbulence kinetic energy (TKE). Particular attention is dedicated to the effect of the submeso motions on these parametrizations. The analysis shows that TKE-based formulations are particularly prone to the submeso effect, whilst better results are obtained if the vertical velocity variance is considered. In the latter case, stability must be taken into account explicitly in Mellor-Yamada type parametrizations but not in shear-based formulations.

Keywords Energy dissipation rate · Stable surface layer · Shear-based parametrizations · Submeso motions · Vertical velocity variance

1 Introduction

The viscous dissipation rate of turbulence kinetic energy (TKE), ϵ , is a key variable for turbulence models because it is a fundamental term in the TKE budget equation (Chamecki et al. 2018). Theoretically, this equation may be used to derive turbulence characteristics under simplifying assumptions, such

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26 as steadiness, horizontal homogeneity, and negligible third-order terms (Zil-
27 itinkevich et al. 2013). Practically, it is solved numerically in many weather,
28 climate, and oceanic models to predict the TKE which, in turn, is used in other
29 parametrizations of the model (e.g., to compute eddy viscosity and diffusivity).

30 Direct calculation of ϵ is rarely performed both in numerical and exper-
31 imental studies due to the small spatial and temporal scales characterizing tur-
32 bulence dissipation. This requires very high-frequency sample rates from the
33 experimental instrumentation or fine-grid direct numerical simulations (DNS)
34 solvers which are typically expensive and exceed the available computational
35 resources for many applications. More often, indirect estimations of ϵ are ob-
36 tained from velocity spectra and structure functions by using Kolmogorov’s
37 law (Kolmogorov 1941), but even these solutions may not be convenient for
38 practical applications. Thus, significant work has been made to parametrize ϵ
39 in terms of easily measurable characteristics of the flow, such as the TKE and
40 the vertical velocity variance. Among the first and most recognized, Mellor and
41 Yamada (1982) developed a TKE-based parametrization which is still used in
42 numerical models and subject of investigation for more precise quantification
43 of its parameters (see Sect. 2). On the other hand, Chen (1974) showed the
44 proportionality of ϵ with the cube power of the vertical velocity variance, while
45 Weinstock (1981) suggested the implication of buoyancy. Recently, Basu et al.
46 (2021) reviewed these parametrizations by using DNS data and proposed new
47 shear-based formulations which should portray quasi-universal scaling.

48 Whereas flow conditions and driving mechanisms may be controlled in
49 numerical simulations, the atmospheric flow is perturbed by a variety of phe-
50 nomena whose effect is not fully understood. Among these phenomena there
51 are submeso motions. This term is used mainly in relation to the stable bound-
52 ary layer (SBL) and refers to all motions with scale smaller than the meso- γ
53 scale (about 2 km in the atmosphere) and larger than the scale of the main
54 turbulent eddies (about $0.1z$, with z distance from the ground) (Mahrt 2014).
55 However, a clear spectral gap between submeso motions and turbulent eddies
56 often does not exist, making this separation somewhat arbitrary. In the time
57 domain, where most observational analyses are carried out, submeso motions
58 have scales shorter than ≈ 1 hr (Mortarini et al. 2013).

59 Submeso motions are ubiquitous in the atmosphere and associated with
60 various phenomena, such as gravity waves, inertial oscillations, and drainage
61 flows (Kang et al. 2014). Although these motions are always present, their ef-
62 fect is more evident in weak-wind conditions (Anfossi et al. 2005), which char-
63 acterize the SBL. Study the submeso effect is thus crucial to address the SBL
64 long standing questions concerning both theory and practical applications.
65 With respect to the latter, submeso motions are among those boundary-layer
66 processes that hinder contemporary numerical weather-prediction (NWP) mod-
67 els (Calaf et al. 2022).

68 Close to the ground, submeso motions appear as a low-frequency contribu-
69 tion to horizontal velocity fluctuations leading to strong turbulence anisotropy
70 (Mortarini et al. 2019) that alters the amount of energy and momentum at

71 the surface (Barbano et al. 2022). This contribution is not accounted for in
72 the most common formulations for ϵ .

73 This study faces the same question of Basu et al. (2021), i.e., the validation
74 of different parametrizations for ϵ , but using tower micrometeorological obser-
75 vations. These observations were acquired in the stable surface-layer during
76 two field experiments and are hence characterized by the presence of submeso
77 motions. The considered formulations are thus tested in the non-ideal condi-
78 tion of a perturbed flow. In particular, the study verifies whether

- 79 – without filtering the submeso contribution, formulations based on the ver-
80 tical velocity variance are more robust than TKE-based parametrizations;
- 81 – in the stable atmospheric surface layer, shear-based parametrizations (Basu
82 et al. 2021) performs differently from Mellor-Yamada formulations (Mellor
83 and Yamada 1982).

84 The organization of the paper is as follows. Section 2 discusses the link
85 between spectra and ϵ and reviews the formulations for ϵ considered in this
86 study. In Sect. 3, the two experiments and the corresponding datasets ana-
87 lyzed in this study are described, along with the method used to estimate ϵ
88 from the spectra. In Sect. 4, the observed characteristics of velocity spectra
89 are discussed in relation to the addressed problem. In Sect. 5, the considered
90 parametrizations for ϵ are tested by using observations from the two experi-
91 ments. Conclusions are drawn in Sect. 6.

92 2 Theoretical Framework

93 It is common in turbulence research to partition each variable into mean and
94 turbulent parts and consider a reference system with the x -axis aligned with
95 the mean flow (Stull 1988). The velocity vector is thus written as $(U+u', v', w')$,
96 where U is the mean flow velocity (modulus) and u' , v' , and w' are the stream-
97 wise, lateral, and vertical velocity fluctuations, respectively. By definition, $\overline{u'} =$
98 $\overline{v'} = \overline{w'} = 0$, where the overbar denotes Reynolds average. The variances of
99 the three velocity components are $\overline{u'^2} \equiv \sigma_u^2$, $\overline{v'^2} \equiv \sigma_v^2$, and $\overline{w'^2} \equiv \sigma_w^2$ and the
100 TKE is $E_K \equiv (\sigma_u^2 + \sigma_v^2 + \sigma_w^2)/2$.

101 In the atmospheric surface layer, the varying stability may be accounted for
102 by the Obukhov length, L (Tampieri 2017). In particular, $L \equiv -(\Theta/g)(u_*^3/\overline{w'\theta'})$,
103 where g is gravitational acceleration, $\overline{w'\theta'}$ is the kinematic vertical turbulent
104 heat flux (θ' is the turbulent temperature fluctuation), $u_* \equiv [\overline{u'w'^2} + \overline{v'w'^2}]^{1/4}$
105 is friction velocity, and Θ is mean temperature (the minus sign provides $L > 0$
106 in the SBL).

107 To model turbulence behaviour, an important role is played by the power
108 spectrum of the three velocity components, $E_\alpha(k)$, which gives the variance
109 associated to each wavenumber k . In particular (Tampieri 2017)

$$\int_0^\infty E_\alpha(k) dk = \sigma_\alpha^2 \quad (1)$$

110 where k is the wavenumber in the stream-wise direction ($k = 2\pi f/U$, with f
 111 frequency in Hz), $\alpha = u, v, w$ represents the stream-wise, lateral, and vertical
 112 velocity component, and σ_α^2 its variance.

113 An integral length scale, l_α , may be defined and related to the value of the
 114 spectrum for $k = 0$ (Tampieri 2017):

$$l_\alpha \equiv \frac{\pi}{2\sigma_\alpha^2} E_\alpha(0) \quad (2)$$

115 Furthermore, given an analytical expression for the power spectrum $E_\alpha(k)$,
 116 a relation among the variance, σ_α^2 , the TKE viscous dissipation rate, ϵ , and
 117 the integral length scale, l_α , may be obtained. For instance, by using (Olesen
 118 et al. 1984; Kaimal and Finnigan 1994)

$$E_\alpha(k) = \frac{C_\alpha \epsilon^{2/3}}{(b_\alpha^{-1} + k)^{5/3}} \quad (3)$$

119 where $C_u = 0.55$, $C_{v,w} = (4/3)C_u$, and $b_\alpha \equiv 3l_\alpha/\pi$, it results from Eq. (2)
 120 that

$$\epsilon = \left(\frac{2}{3C_\alpha}\right)^{3/2} \frac{\sigma_\alpha^3}{b_\alpha}. \quad (4)$$

121 For $k \gg b_\alpha^{-1}$, i.e., in the inertial subrange, Eq. (3) follows Kolmogorov's
 122 law (Kolmogorov 1941),

$$E_\alpha(k) = C_\alpha \epsilon^{2/3} k^{-5/3} \quad (5)$$

123 and $E_\alpha(k)$ becomes independent of the integral length scale l_α .

124 Often, spectra observed within the atmospheric boundary layer do not
 125 follow Eq. (3) or similar formulations, showing instead higher values in the low-
 126 k range (Andreas and Paulson 1979; Cava et al. 2001; Mortarini et al. 2016,
 127 e.g). This occurs when the flow is perturbed by submeso motions which, close
 128 to the surface, manifest as a low-wavenumber contribution to u and v spectra
 129 (Mortarini et al. 2013; Mahrt 2014), whilst the vertical velocity component is
 130 almost unaffected (Sect. 4). Alternative spectral models accounting for these
 131 small- k modes may be formulated. For instance, Mortarini and Anfossi (2015)
 132 proposed a spectral model that is suitable for low-wind/meandering conditions
 133 and other modifications may account for gravity waves.

134 By modifying the spectra, submeso motions affect the validity of Eqs. (3)
 135 and (4) and thus the possibility to find quasi-universal relationships between
 136 ϵ and the integral parameters (σ_α and l_α). Alternatively, in presence of low- k
 137 modes not related to ϵ , only the high- k part of the spectrum, Eq. (5), may
 138 be considered (Chen 1974). However, this requires the case-by-case determina-
 139 tion of the inertial subrange extension, which is possible but not always easy
 140 (Falocchi et al. 2019).

141 Because time records are considered in this study, time scales instead of
 142 length scales – and frequencies instead of wavenumbers – are used hereafter.
 143 From dimensional considerations, the viscous dissipation may be written as

$$\epsilon = \frac{v^2}{T} \quad (6)$$

144 where v is a velocity scale and T is the dissipation time scale (e.g., Zilitinkevich
 145 et al. 2013). Taking $T \sim l_\alpha/v$ and $v = \sigma_\alpha$, Eq. (6) reduces to Eq. (4). Different
 146 parametrizations are thus characterized by different velocity- and time-scales.
 147 If submeso motions are not relevant, the normalized spectrum depends only on
 148 stability (Kaimal et al. 1972) and the same occurs for length- or time-scales.
 149 However, if submeso motions are present the involved scales may depend on
 150 other parameters.

151 The widely used approach by Mellor and Yamada (1982) takes as velocity
 152 scale $v = q$, where $q^2 \equiv 2E_K$, and prescribes $T = Bl/q$, where l is a length
 153 scale related to the size of the main eddies and B is an empirical constant, with
 154 value **varying among authors** in the range $B \approx 12 - 24$ (Mellor and Yamada
 155 1982; Nakanishi 2001; Nakanishi and Niino 2009; Wilson and Venayagamoorthy
 156 2015; Basu et al. 2021). With this choice, Eq. (6) becomes

$$\epsilon = \frac{q^2}{Bl} \quad (7)$$

157 In the near-neutral surface layer, a common solution is $l = \kappa z$, being z the
 158 distance from the surface and $\kappa = 0.4$ the von Kármán constant. Furthermore,
 159 accounting for stability (Cheng et al. 2020):

$$l = \frac{\kappa z}{1 + \alpha_1 z/L}, \quad 0 < z/L < 1 \quad (8)$$

160 where L is the Obukhov length and $\alpha_1 = 2.7$. According to Nakanishi and
 161 Niino (2009), the length scale l may be limited to a stability-independent
 162 value for $z/L > 1$.

163 Basu et al. (2021) use both $E_K^{1/2}$ and σ_w as velocity scales, and the inverse
 164 of the mean velocity shear as time scale, i.e., $T \propto [dU/dz]^{-1}$ (by assuming **no**
 165 **directional shear** in the surface-layer), leading to the relationships

$$\epsilon = c_E E_K \frac{dU}{dz}, \quad \text{with } c_E = 0.23 \quad (9)$$

166 and

$$\epsilon = c_w \sigma_w^2 \frac{dU}{dz}, \quad \text{with } c_w = 0.63 \quad (10)$$

167 For a log-linear velocity profile, i.e., for $dU/dz = u_*(1 + \alpha_2 z/L)/(\kappa z)$, with
 168 u_* friction velocity and $\alpha_2 \approx 5$, (e.g., Högström 1996), Eqs. (9) and (10) may
 169 be rewritten similarly to Eq. (7), i.e., in terms of a length scale like that of
 170 Eq. (8) and the ratios E_K/u_*^2 or σ_w^2/u_*^2 . For instance, from (9) we obtain

$$\epsilon = \frac{q^3}{B'l} \quad (11)$$

171 where $l = (\kappa z)/(1 + \alpha_2 z/L)$, similar to Eq. (8), and $B' \equiv (2/c_E)(q/u_*) \approx 20$ in
 172 near-neutral conditions (by taking $q/u_* \approx 2$, see, e.g., Tampieri 2017), which
 173 compares with the values of B used in Eq. (7). Thus, if the velocity profile
 174 is log-linear, Eqs. (7), (9), and (10) are equivalent. However, whereas Mellor-
 175 Yamada formulation (Eq. 7) **requires** the specification of the length scale and
 176 its stability dependence, shear-based formulations (Eqs. 9 and 10) do not.

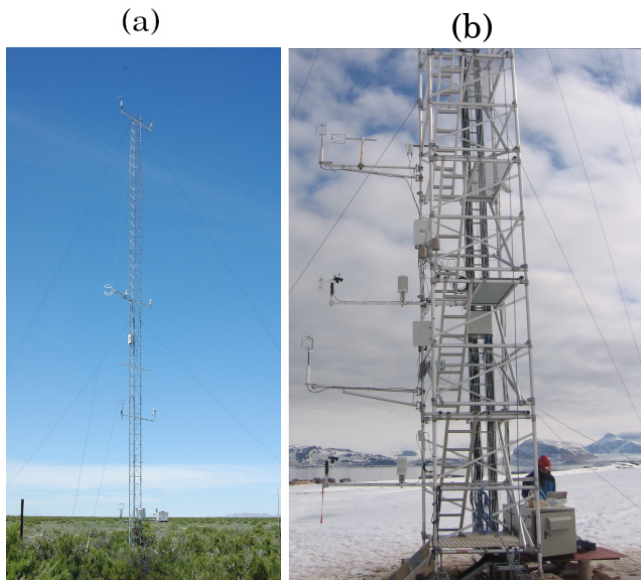


Fig. 1 Tower with instrumental setup for (a) MATERHORN and (b) CCT-IP.

177 3 Observations

178 Observations from two field experiments are considered in this study: the
 179 Mountain Terrain Atmospheric Modeling and Observations (MATERHORN)
 180 Program and the Climate Change Tower Integrated Project (CCT-IP). The
 181 two **datasets** refer to tower observations acquired in the stable surface-layer.
 182 Because of the site characteristics, submeso activity is common in both ex-
 183 periments and thus ϵ formulations may be tested in conditions perturbed by
 184 these motions.

185 3.1 The Mountain Terrain Atmospheric Modeling and Observations Program

186 The Mountain Terrain Atmospheric Modeling and Observations Program (MATER-
 187 HORN) dataset was assembled by using flux-tower measurement collected at
 188 the Dugway **Proving Ground** test-bed (Fernando et al. 2015). The gentle-
 189 sloping valley (**with an average angle of 0.06° along the valley axis**) is char-
 190 acterized by an arid soil heterogeneously covered by desert shrubs, located at
 191 1300 m above mean sea level in South Utah. The valley floor is 40×30 km wide,
 192 surrounded by an isolated mountain peak (840 m) to the west and a moun-
 193 tain chain (peaks below 800 m) to the south, separated by a 5-km gap. The flux
 194 tower (**Fig. 1a**) was located at the field site of Sagebrush ($40.121360^\circ\text{N}, 113.129070^\circ\text{W}$,
 195 altitude: 1316 m **ASL**) and equipped with 5 measurement levels (0.5 m, 2 m,
 196 5 m, 10 m and 20 m) of sonic anemometers (81000, Young Company, Traverse

City, U.S.) sampling at 20 Hz, and temperature and relative-humidity probes (HMP45C-L, Campbell Scientific, Logan, U.S.) sampling at 1 Hz.

The dataset used for this investigation consists in the nocturnal periods of a set of weak-synoptic days occurred during Intensive Operational Periods (IOPs), i.e., days with the 700-hPa wind speed $U \leq 5 \text{ ms}^{-1}$ (classified as quiescent IOPs, see Fernando et al. 2015) during fall 2012 and spring 2013. A total of 5 quiescent IOPs, namely IOP0, IOP1, IOP4, IOP7, and IOP8 (0,1, and 8, fall; 4 and 7, spring), compose the dataset (see Fernando et al. 2015 for a detailed description of them), characterized by a persistent low-level jet throughout the night and a continuous uptake of waves and intermittent turbulence arising close to the surface (Brognno et al. 2021).

To minimize unsteadiness, transitional periods across sunset and sunrise were removed. Therefore, the complex terrain heterogeneity and internal variability of the nocturnal boundary layer are expected to be the major source of perturbation for the boundary-layer flow. The collected data were preliminary processed to discard non-physical data. The sonic-anemometers measurements were further despiked using a data-removal procedure (Højstrup 1993) applied every 30-min data interval (Vickers and Mahrt 1997). The despiked wind components are then double-rotated to align the wind vector to the mean streamline direction (McMillen 1988). Second-order moments are then calculated as 30-min (co)variances.

3.2 Climate Change Tower Integrated Project

Two years (2012–2013) of observations from the Climate Change Tower Integrated Project (CCT-IP) are considered in this study (Mazzola et al. 2016). The Climate Change Tower (CCT) is 34 m high and equipped with fast- and slow-response instruments at several levels (Fig. 1b): mean velocity, temperature and humidity were measured with slow-response instruments at 2, 4.8, 10.3, and 33.4 m above the ground, whilst three sonic anemometers are placed at intermediate levels: 3.7, 7.5 (Gill R2 and R3, respectively, Lyvington, Hampshire, UK) and 20.5 m (CSAT3, Campbell Scientific, Logan, U.S.). This study focuses on turbulence observation at the 7.5 m level, because, for technical reasons, few data are available from the other two levels during the considered period.

The experimental site is located in Ny-Ålesund (78°55' N, 11°55' E), Svalbard, Norway, on the coast of Kongsfjorden, in an area with complex topography. The CCT is placed on a small relief (with height ≈ 50 m asl and horizontal scale ≈ 500 m), 2 km west to the Ny-Ålesund village and 1 km west to the Zeppelin mountain. Snow cover lasts from October to May whilst during the snow-free season, the ground is covered by stones and short grass, typical of arctic tundra. In this study, both snow-free and snow-covered conditions are considered without any distinction, because presented results do not differ for the two cases.

239 Raw data were divided into 30-min records. Sonic data, recorded at 20 Hz,
 240 were checked for spikes, plausibility limits and gaps. A double rotation was
 241 used to align the sonic reference system to the 30 min mean velocity. Second-
 242 order moments were calculated as 30-min (co)variances. To select stable con-
 243 ditions, only records with increasing temperature in the layer 2 – 10.3 m and
 244 negative vertical fluxes of heat ($\overline{w'\theta'} < 0$) at $z = 7.5$ m are considered. Nega-
 245 tive vertical fluxes of momentum ($\overline{u'w'} < 0$) at the same level and wind speed
 246 increasing in the same layer are also imposed, to guarantee shear production
 247 of TKE and obtain positive dissipations from Eqs. (9) and (10) which depend
 248 on the wind shear. Furthermore, wind directions in the range 150° – 270° are
 249 excluded from the analysis to avoid flow distortion by the tower structure.

250 3.3 Estimation of the Dissipation Rate

251 For both datasets, the dissipation rate is obtained from the inertial subrange
 252 of the velocity spectra, Eq. (5). Because observations are acquired in the time
 253 domain, $S_\alpha(f)$ instead of $E_\alpha(k)$ is considered as the power spectra of the
 254 velocity component α as a function of the frequency f (measured in Hz), such
 255 that $fS_\alpha(f) = kE_\alpha(k)$ with $k = 2\pi f/U$ (Kaimal and Finnigan 1994), by
 256 assuming Taylor’s hypothesis of frozen turbulence. This hypothesis may not
 257 hold under weak wind speed and significant submeso effect (Schiavon et al.
 258 2019), thus breaking the link between f and k . However, this has no significant
 259 implications on the estimation of the dissipation rate, because a clear inertial
 260 subrange is always present in observed spectra (Sect. 4).

261 In particular, the dissipation rate is obtained from the high-frequency part
 262 of the u spectrum, because, having the longest inertial subrange, it gives the
 263 most reliable estimate of ϵ (Yadav et al. 1996). Thus,

$$\epsilon = \frac{2\pi}{U} \left[\frac{S_u(f)f^{5/3}}{C_u} \right]^{3/2}. \quad (12)$$

264 Starting from Eq. (12), different techniques were used for the two datasets,
 265 because of the different characteristics of the two experiments. For CCT-IP,
 266 the term in square brackets was averaged over the interval $2U/z < f < 4$ Hz,
 267 where the lower boundary corresponds the low-frequency end of the inertial
 268 subrange (e.g. Kaimal and Finnigan 1994), while $f < 4$ Hz avoids aliasing
 269 effects. Inertial-subrange isotropy was verified by calculating ϵ also from the v
 270 and w spectra and obtaining differences $< 10\%$.

271 For MATERHORN, ϵ is calculated by a linear regression of Eq. (12) in a
 272 frequency range estimated from the mean nocturnal spectra (Barbano et al.
 273 2022): other techniques, including that used for CCT-IP, were tested for this
 274 dataset and gave similar results, thus indicating small sensitivity to the method.
 275 For both datasets, only records with at least four spectral points in the inertial
 276 subrange were retained.

4 Spectra

As discussed in Sect. 2, if an inertial subrange is present, the viscous dissipation rate, ϵ , is linked to the shape of the spectrum (Eq. 4). However, submeso motions modify the spectra in such a way that formulations like Eq. (3) are no longer valid. To account for these aspects, the spectra of the three velocity components for the considered datasets are analyzed in this section.

Figure 2 shows the observed spectra for the MATERHORN and CCT-IP experiments (the IOP1 from MATERHORN dataset is shown as an example due to the similar characteristics observed within the other IOPs). For CCT-IP, to isolate the submeso effect from the stability dependence, near-neutral conditions are selected, by imposing $0 < z/L < 0.05$ at $z = 7.5$ m (the level considered in this study). Furthermore, CCT-IP spectra are separated according to wind-speed, which is related to the relative strength of submeso motions (Schiavon et al. 2019). MATERHORN spectra, instead, are presented for the five tower levels. By increasing z or decreasing U , small-scale turbulence intensity decreases and the relative strength of submeso motion increases. All spectra are anchored in the inertial subrange by taking $fS_\alpha(f)/(\kappa z\epsilon)^{2/3}$, with $\alpha = u, v, w$.

For comparison, Fig. 2 also shows the model suitable for no submeso contribution and near-neutral conditions (Olesen et al. 1984):

$$\frac{fS_\alpha(f)}{(\kappa z\epsilon)^{2/3}} = \frac{A_\alpha n}{(1 + B_\alpha n)^{5/3}} \quad (13)$$

where $\alpha = u, v, w$, $n = fz/U$ is the non dimensional frequency,

$$A_u = B_u^{5/3} C_u (2\pi\kappa)^{-2/3} \quad \text{and} \quad A_{v,w} = \frac{4}{3} B_{v,w}^{5/3} C_u (2\pi\kappa)^{-2/3}. \quad (14)$$

In particular, $A_u = 102$, $A_v = 17$, $B_u = 33$, and $B_v = 9.5$ are taken from the Kansas spectra (Kaimal and Finnigan 1994). To fit better the observations, a model different from Eq. (13) was used for the w spectrum in the Kansas experiment. For sake of simplicity, and because in this case Eq. (13) agrees well with observations (Fig. 2f), in this study Eq. (13) was used also for the vertical velocity component, with $A_w = 4.3$ and $B_w = 4.2$ obtained from previous analysis (Schiavon et al. 2019). Equations (13) and (3) are similar and thus relations exist among the corresponding parameters, i.e., $B_\alpha = b_\alpha(2\pi/z) = 6l_\alpha/z$.

As expected, submeso motions lead to completely different behaviours of horizontal velocity components (Figs. 2a-d) vs the vertical one (Figs. 2e,f). Indeed, contrary to the latter (Figs. 2e-f), horizontal velocity components are significantly affected by submeso motions (Figs. 2a-d). In particular, two frequency ranges may be recognized. An high-frequency range, for $n \gtrsim 0.1$, where the observed spectra follow Eq. (13). A low frequency range, for $n \lesssim 0.1$, where the submeso contribution is dominant and spectral levels are higher than those predicted by Eq. (13). The high-frequency range is dominated by small-scale turbulence: for MATERHORN, the effect of increasing stability is visible

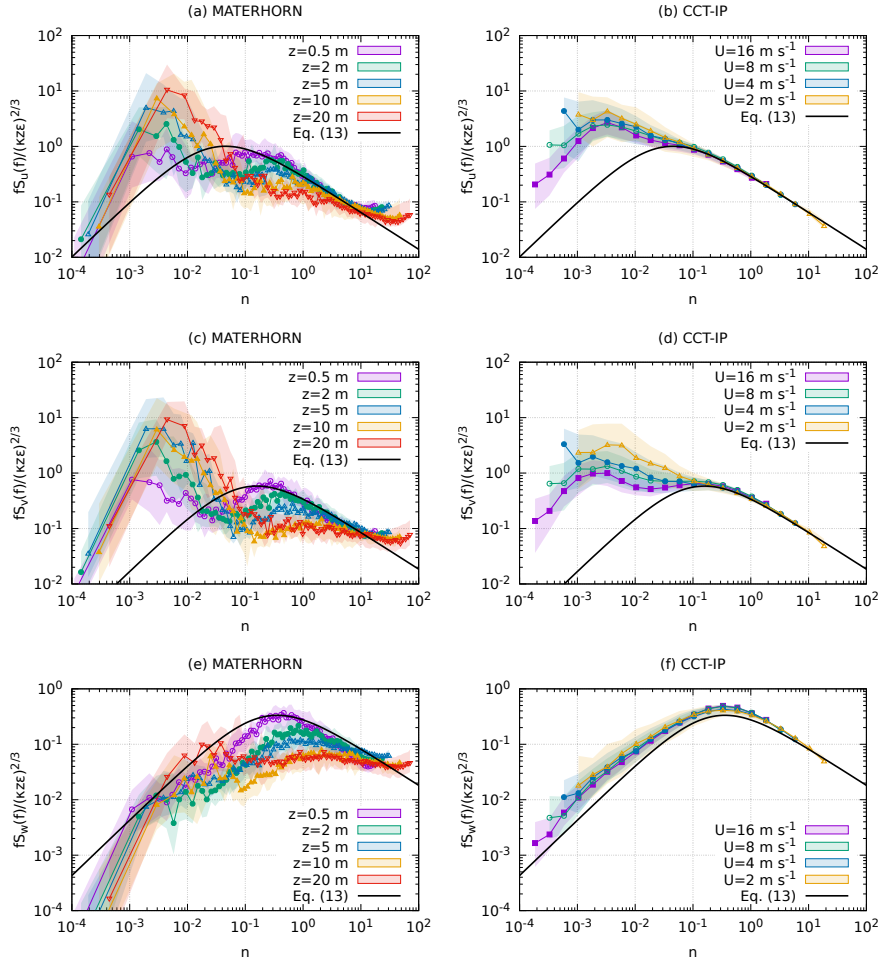


Fig. 2 Frequency weighted spectra, $fS_\alpha(f)$ (with $\alpha = u$, top; v , middle; and w , bottom), normalized by $(\kappa z \epsilon)^{2/3}$ vs the non-dimensional frequency $n = fz/U$ for the MATERHORN (left, IOP1) and CCT-IP dataset (right, $0 < z/L < 0.05$). MATERHORN spectra correspond to the height of the five tower levels, z . CCT-IP spectra correspond to $z = 7.5$ m and different wind-speed intervals, each 2 m s^{-1} wide and centered around the reported value (U is wind speed at 7.5 m). Median values (points) and variability (shaded area, corresponding to the interquartile range) are shown for each level or U class. Eq. (13) is also represented for comparison

316 in this range through the decrease in the spectral levels with increasing height
 317 (taking the IOP1 average, z/L increases from ≈ 2.5 to ≈ 7 from $z = 0.5$ m to
 318 $z = 20$ m). For CCT-IP, a clear inertial subrange is always observed, for $n \gtrsim 1$
 319 (Figs. 2b, d, and f). For MATERHORN, the extension of this range shortens
 320 as the height increases because of the increasing stability: for the case shown
 321 in Figs. 2a,c, and e, small-scale turbulence is weak at $z = 10$ m and 20 m.

322 The observed submeso contribution may have different origins. All the con-
 323 sidered IOPs of the MATERHORN dataset are characterized by wave activity.
 324 This is particularly evident by looking at the peak of the u and v spectra in
 325 the range $10^{-3} \lesssim n \lesssim 10^{-2}$ and at the spectral gap especially in the lowest
 326 levels (Figs. 2a,c): at $z = 0.5$ m (purple line) the gap is at $n \approx 0.1$ for the
 327 u component (Fig. 2a) and $n \approx 0.2$ for the v component (Figs. 2c). For the
 328 CCT-IP dataset, the nature of the submeso motions is less clear, with hor-
 329 izontal heterogeneity that is responsible of an intense and variable submeso
 330 activity. Within MATERHORN cases, some have been recognized as inertial-
 331 gravity waves induced by perturbations of the mean flow (Brognno et al. 2021;
 332 Barbano et al. 2022). In spite of these differences, the low-frequency peak for
 333 the CCT-IP spectra (Fig. 2b,d) is about at the same positions of the MATER-
 334 HORN dataset (Fig. 2a,c). Although this similarity is interesting, the position
 335 and the magnitude of this peak should be considered with caution, because
 336 Taylor’s hypothesis may be not fulfilled in weak wind conditions (Schiavon
 337 et al. 2019) and submeso scales may be poorly sampled, being close to the
 338 record length.

339 Whereas $(\kappa z \epsilon)^{2/3}$ is the adequate scale in the high-frequency range (with
 340 the exception of stability effects, all spectra collapse on the same curve for
 341 $n \gtrsim 0.1$), this is not the case for the submeso contribution ($n \lesssim 0.1$), whose
 342 relative magnitude **increases** with increasing height (Figs. 2a,c) or decreasing
 343 wind speed (Figs. 2b,d). This confirms the weak relation between the submeso
 344 contribution and viscous dissipation (**the former does not scale with the latter,**
 345 **contrary to small-scale turbulence**) and the **need** for other parameters **related**
 346 **to submeso motions** to describe the spectra in the low-frequency range. For
 347 **these reasons**, horizontal velocity variances, **which show the highest submeso**
 348 **contribution**, are expected to be **inappropriate** scales for ϵ .

349 Contrary to horizontal velocity components, vertical velocity spectra are
 350 almost unaffected by the submeso contribution, because large-scale vertical
 351 velocity fluctuations are damped close to the ground (Højstrup 1982). Thus
 352 the observed spectra closely follow Eq. (13). This is particularly evident for
 353 CCT-IP (Fig. 2f). The negligible submeso contribution to the w spectrum
 354 indicates that the vertical velocity variance is a suitable scale for ϵ , even in
 355 presence of submeso motions. Because these motions contribute to horizontal
 356 velocity components but not to the vertical one, larger anisotropy corresponds
 357 to stronger submeso effect (as discussed further in Sect. 5.1).

358 5 Results

359 The parametrizations discussed in Sect. 2 are tested with CCT-IP and MATER-
 360 HORN data by taking into account the submeso effect. For MATERHORN,
 361 data from different IOPs and levels are considered together, because a similar
 362 behaviour is observed.

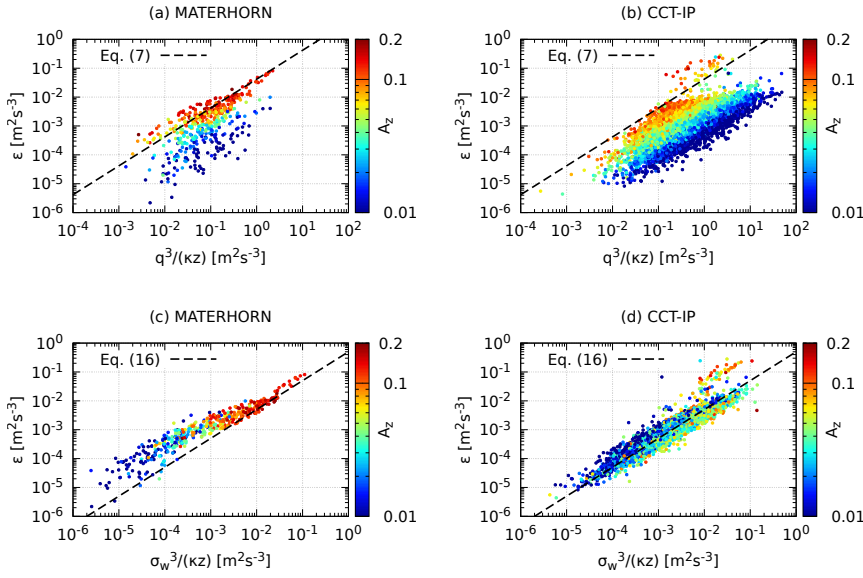


Fig. 3 Observed dissipation rate, ϵ , vs $q^3/(\kappa z)$ (top) and $\sigma_w^3/(\kappa z)$ (bottom) for MATERHORN (left) and CCT-IP (right). Each point corresponds to a 30-min record and is colored according to the anisotropy degree, A_z , Eq. (15). For comparison, Eqs. (7) and (16), with $l = \kappa z$, $B = 24$ and $B_w = 2$, respectively, are also represented.

363 5.1 Mellor-Yamada Type Parameterizations

364 **Figures 3a-b** show the observed dissipation rate, ϵ , vs $q^3/(\kappa z)$, which is the
 365 Mellor-Yamada-type parametrization, i.e., Eq. (7), without B and with $l = \kappa z$.
 366 To account for the **strength** of the submeso effect, data are stratified according
 367 to the anisotropy degree

$$A_z \equiv \frac{\sigma_w^2}{q^2} \quad (15)$$

368 which is the relative contribution to the TKE by the vertical velocity variance.
 369 **Besides** the fact that A_z has been used as a key parameter to model the
 370 turbulent flow (Zilitinkevich et al. 2013), its value is also related to the **strength**
 371 of the submeso effect (Mortarini et al. 2019; Schiavon et al. 2019, Sect. 4). In
 372 particular, A_z decreases (anisotropy increases) as the strength of submeso
 373 motions increases, because submeso motions are almost two-dimensional close
 374 to the ground.

375 **Figures 3a-b** show that observations dispose ordinately according to A_z ,
 376 with smaller A_z (stronger submeso effect) corresponding to larger **deviations**
 377 from Eq. (7). In particular, for MATERHORN (Fig. 3a), Eq. (7) (with $l = \kappa z$)
 378 is approximately valid when $A_z \gtrsim 0.1$, returning $B = 0.24$ as a best fit, in line
 379 with Nakanishi (2001). Conversely, **Eq. (7)** over-predicts the observed dissipa-
 380 tion for smaller A_z . The latter case always occurs for CCT-IP (Fig. 3b), for

381 which $A_z < 0.1$ is generally observed (Schiavon et al. 2019). The overestima-
 382 tion of ϵ by using Eq. (7) is due to the submeso contribution to the TKE but
 383 not to ϵ , consistently with the behaviour of the low-frequency part of u and v
 384 spectra discussed in Sect. 4.

385 As shown in Sect. 4, the submeso contribution to the vertical velocity vari-
 386 ance is negligible close to the ground. Thus, following Eq. (7), an alternative
 387 parametrization is considered by taking for the velocity scale σ_w :

$$\epsilon = \frac{\sigma_w^3}{B_w l}, \quad (16)$$

388 where, as in Eq. (7), B_w is an empirical constant and l is the length scale.
 389 This parametrization is tested in Figs. 3c-d by taking $l = \kappa z$ as in Figs. 3a-b.
 390 Contrary to Figs. 3a-b, data collapse on a single curve independently of A_z .
 391 This curve is close to Eq. (16) with $B_w = 2$, a value which corresponds to
 392 $B_w = BA_z^{3/2}$, by taking $B = 24$ and $A_z = 0.2$, consistently with the near-
 393 neutral reference value for A_z in absence of submeso contribution (Tampieri
 394 2017; Schiavon et al. 2019). Thus Eq. (16) is more robust than Eq. (7) against
 395 the submeso effect and explains most of the observed variability in ϵ .

396 The deviation from the linear behaviour observed for MATERHORN for
 397 low values of $\sigma_w^3/(\kappa z)$ (Fig. 3c) is due to the stability dependence, which
 398 instead is negligible for the CCT-IP dataset (Fig. 3d). As discussed in Sect. 2,
 399 this effect is accounted for by considering a stability dependence of the length
 400 scale l . According to Eqs. (7) and (16), this stability dependence may be
 401 studied by considering the ratio between $\kappa z \epsilon$ and q^3 or σ_w^3 . Following Eq. (8)
 402 and Nakanishi and Niino (2009), we expect that

$$\frac{\kappa z \epsilon}{q^3} = \begin{cases} (1 + \alpha_1 z/L)/B & \text{for } z/L \leq 1 \\ (1 + \alpha_1)/B & \text{for } z/L > 1 \end{cases} \quad (17)$$

403 where $\alpha_1 = 2.7$ and B_w substitutes B if σ_w instead of q is considered.

404 Figure 4 shows the stability dependence of $\kappa z \epsilon$ divided by q^3 and σ_w^3 . Equa-
 405 tion (17) is also reported, with $B = 24$ and $B_w = 2$. As expected, the stability
 406 dependence is more clear if σ_w instead of q is used as a velocity scale. This is
 407 true for both datasets but is more evident for MATERHORN (compare Fig. 4a
 408 and c): when q is considered, only data with large A_z follow Eq. (17) (Fig. 4a),
 409 whereas, by using σ_w all data collapse around the expected relationship. With
 410 respect to MATERHORN, more scatter and a negligible stability dependence
 411 are observed for the CCT-IP dataset, even if σ_w is considered (Fig. 4c). Fig-
 412 ures 4c-d also show that, on average, A_z decreases with increasing stability,
 413 consistently with other experiments (Zilitinkevich et al. 2013; Tampieri 2017).
 414 As observed in Fig. 3d, the stability dependence for CCT-IP is weak (Fig. 4d).

415 5.2 Shear-Based Parametrizations

416 Figure 5 shows shear-based parametrizations, both in terms of the TKE and
 417 the vertical velocity variance. Since the estimation of vertical gradients may

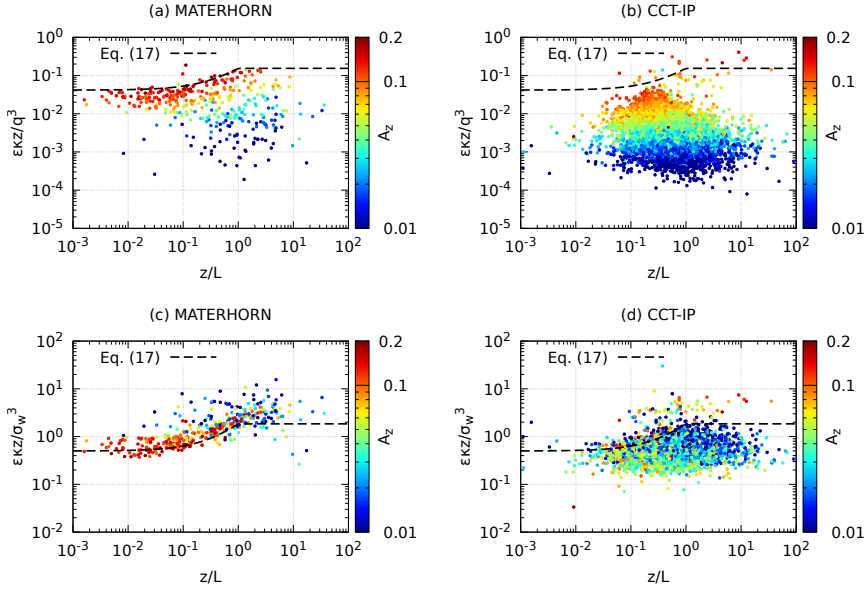


Fig. 4 Dependence on z/L of $\kappa z \epsilon$ divided by q^3 (top) and σ_w^3 (bottom) for MATERHORN (left) and CCT-IP (right). As in previous figures, data are colored according to A_z . Eq. (17), with $B = 24$ (top) and $B_w = 0.2$ (bottom) is also represented

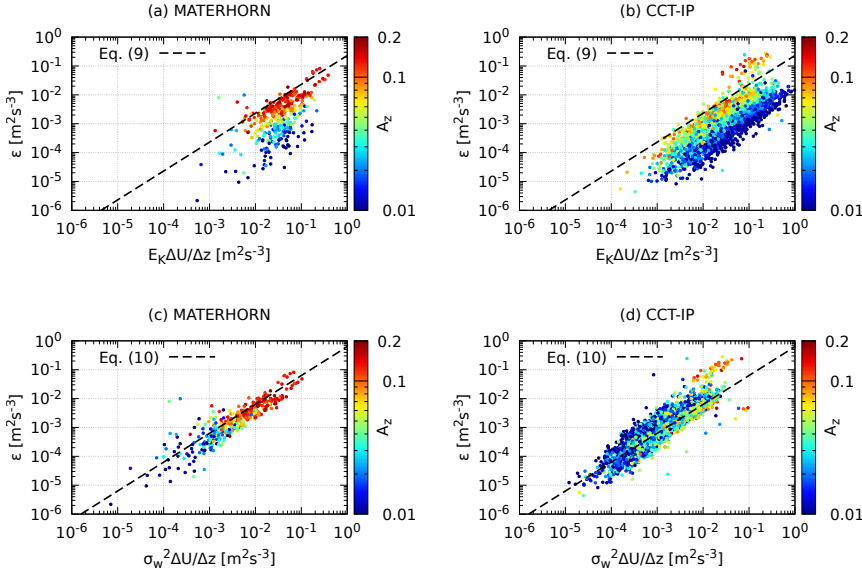


Fig. 5 Observed dissipation rate, ϵ , vs shear-based parametrizations: $E_K \Delta U / \Delta z$ (top) and $\sigma_w^2 \Delta U / \Delta z$ (bottom), for MATERHORN (left) and CCT-IP (right). As in previous figures data are colored according to A_z . Eqs. (9) and (10) are also represented

418 be sensitive to the method and may introduce further errors, their bulk formu-
 419 lation is considered, by taking the bulk wind shear $\Delta U/\Delta z$, instead of dU/dz :
 420 the two formulations are equivalent if ϵ and E_K or σ_w^2 are constant in the
 421 considered layer, which is a reasonable approximation close to the surface.
 422 Eqs. 9 and 10 are also plotted in Fig. 5 for reference. $\Delta U/\Delta z$ is calculated
 423 between 4.8 and 10.3 m for CCT-IP (i.e., the two levels that contain the sonic
 424 at $z = 7.5$ m), whilst the given sonic level and the sonic level above are used
 425 for MATERHORN (with the exception of the highest level, for which the level
 426 below is considered). These differences between datasets are due to different
 427 experimental setups and data availability (Sect. 3) and have a minor impact
 428 on the presented results.

429 For the considered datasets, concerning their robustness against the sub-
 430 meso effect, similar considerations apply for shear-based and Mellor-Yamada
 431 formulations (Sect. 5.1), confirming that the key factor is the choice of the
 432 velocity scale. Indeed, also shear-based parametrizations are unaffected by
 433 submeso motions if the vertical velocity variance, instead of the TKE, is used
 434 to define the velocity scale (compare Figs. 5a,b with Figs. 5c,d). However, the
 435 advantage of shear-based formulations is that no stability correction is neces-
 436 sary, because stability is embedded in the wind shear (compare Fig. 5c and
 437 Fig. 3c). The drawback is that, when the stability effect is negligible, as for
 438 CCT-IP, the calculation of the wind shear may introduce more scatter in the
 439 data (compare Fig. 3d and Fig. 5d).

440 6 Conclusions

441 Different parametrizations of the dissipation rate of turbulence kinetic en-
 442 ergy (TKE) were validated with turbulence observations acquired in the at-
 443 mospheric stable surface-layer during two field experiments. In particular,
 444 Mellor-Yamada type formulations (Mellor and Yamada 1982) and shear-based
 445 parametrizations (Basu et al. 2021) were considered, with velocity scale based
 446 on the unfiltered TKE and vertical velocity variance, σ_w^2 . The flow was char-
 447 acterized by the presence of submeso motions. Particular attention was paid
 448 to the effect of these motions on the considered formulations.

449 Among all factors, the choice of the velocity scale was determinant for the
 450 robustness of the parametrization against the submeso effect. In particular,
 451 as expected, formulations based on σ_w were more robust than TKE-based
 452 parametrizations, because of the submeso contribution to horizontal velocity
 453 variances which is uncorrelated with dissipation. Hence, the dissipation rate is
 454 overestimated if TKE-based parametrizations are used in presence of submeso
 455 motions as often occurs in the atmosphere. Furthermore, TKE-based formu-
 456 lations cannot be universal, because of the high variability of the submeso
 457 contribution at the same place and among different places. Hence, close to the
 458 ground, the vertical velocity variance should be preferred on the TKE for the
 459 velocity scale of the dissipation rate.

460 This result is not in contrast with the good performance of TKE-based
461 parametrizations observed in direct numerical simulations (Basu et al. 2021),
462 because, in this case, only small-scale turbulence contributes to the TKE. This
463 may suggest that a “filtered” TKE could be used also for the atmosphere. **How-**
464 **ever, filtering out the submeso contribution from horizontal velocity variances**
465 **is not always possible, because a clear spectral gap often does not exist. An**
466 **alternative approach is to retain only inertial-subrange scales (Falocchi et al.**
467 **2019). Clearly, this would give the “right” TKE for the dissipation rate, but**
468 **at the cost of a more difficult implementation, especially for practical appli-**
469 **cations. For this reason, in the surface layer, the use of the unfiltered σ_w**
470 **may be more convenient. If the TKE is considered, different scales should be**
471 **used for different applications: the small-scale TKE may be used in numeri-**
472 **cal weather prediction (NWP) models, whereas the submeso contribution is**
473 **critical in dispersion models, to estimate the probability distribution function**
474 **of the three velocity components. To compare results obtained in this study**
475 **with large-eddy simulations (LES), the total TKE, i.e., that from resolved and**
476 **unresolved scales, should be considered.**

477 If σ_w is used for the velocity scale, Mellor-Yamada and shear-based parametriza-
478 tions are equally good if a stability correction is applied to the former. The
479 equivalence of these formulations is related to the link between the dissipation
480 length scale and the wind shear given by the log-linear velocity profile.

481 In agreement with other studies (Mortarini et al. 2019; Schiavon et al.
482 2019), turbulence anisotropy degree was a useful parameter to identify the
483 presence of submeso motions close to the ground.

484 Future research may focus on the link between these results and deeper
485 aspects of the turbulent flow, that may be investigated by using spectral mod-
486 els accounting for the submeso contribution and by considering the effect of
487 this contribution on the TKE budget. Because the dissipation rate is a key
488 element of the TKE budget (Chamecki et al. 2018), the discussion about its
489 parameterization is tied with understanding and interpreting the budget in
490 actual, usually non-ideal, conditions.

491 7 Data Availability

492 Concerning the CCT-IP dataset, data generated and analysed in this study
493 are available from M.S. with permission of the National Research Council,
494 Institute of Polar Sciences (CNR-ISP).

495 Concerning MATERHORN dataset, data analyzed during the current study
496 are available in the EOL data archive (<https://data.eol.ucar.edu>). This
497 dataset was derived from the following public domain resource: MATERHORN
498 data, https://data.eol.ucar.edu/master_lists/generated/materhorn-x.

499 8 Competing Interests

500 The authors have no competing interests to declare that are relevant to the
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